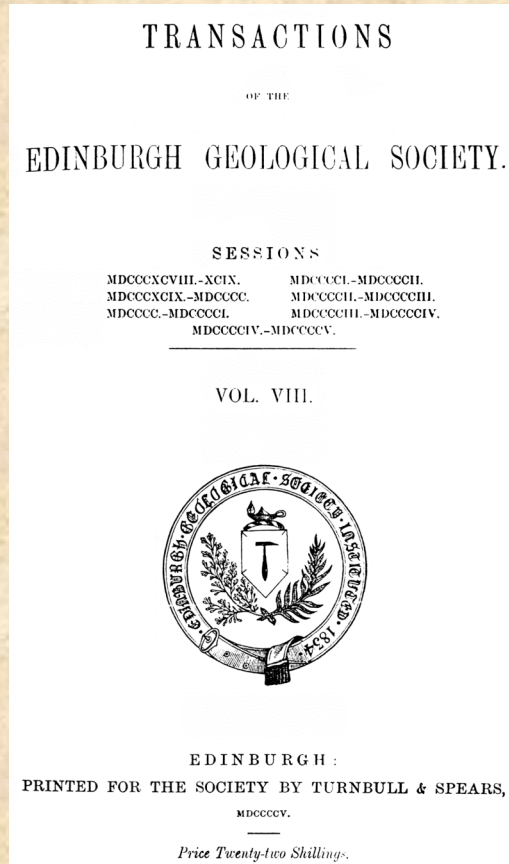


QUE NOUS DISENT LES MÉCANISMES AU FOYER SUR L'ÉTAT DE CONTRAINTE DANS LA CROÛTE ET SUR LA THÉORIE D'ANDERSON ?

- **ANDERSON'S FAULTING**
 - CONJUGATE PLANES
 - OPTIMAL STRESS ORIENTATION
- **FRICTIONAL REACTIVATION:**
 - MAKES IT IRRELEVANT OR NOT ?
- **FOCAL MECHANISMS**
 - P, B, T
 - FROHLICH'S TRIANGULAR DIAGRAMS
 - GLOBAL CMT
 - QUALITY
- **GCMT ANALYSIS**
 - BY DEPTH
 - BY RAKE (FAULT TYPE)
 - INTERPRETATION
- **CONCLUSIONS**

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GÉOSCIENCES MONTPELLIER
UNIVERSITÉ DE MONTPELLIER II - CNRS

Anderson's faulting



THE DYNAMICS OF FAULTING. 387

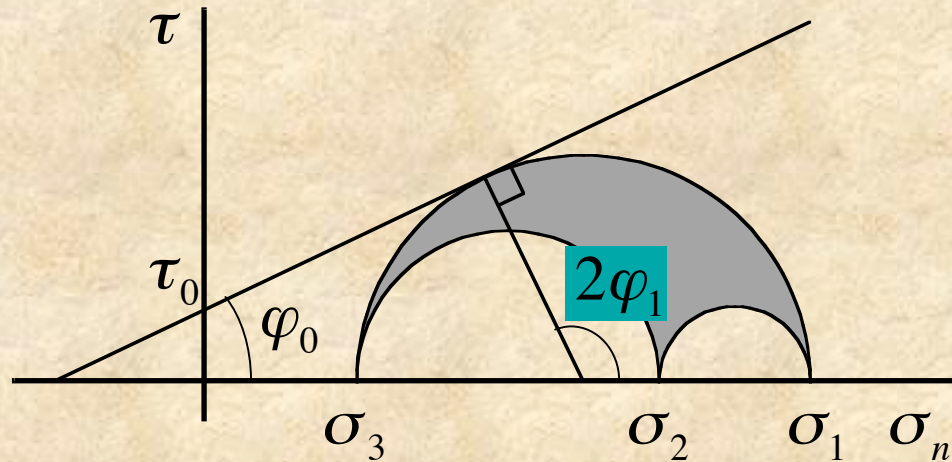
XIII. *The Dynamics of Faulting.* By ERNEST M. ANDERSON,
M.A., B.Sc., H.M. Geological Survey.

(Read 15th March 1905.)

It has been known for long that faults arrange themselves naturally into different classes, which have originated under different conditions of pressure in the rock mass. The object of the present paper is to show a little more clearly the connection between any system of faults and the system of forces which gave rise to it.

- Coulomb criterion for rupture
- Rupture occurs on optimal planes
- A principal stress direction is vertical

Stress orientation -> optimal conjugate faults



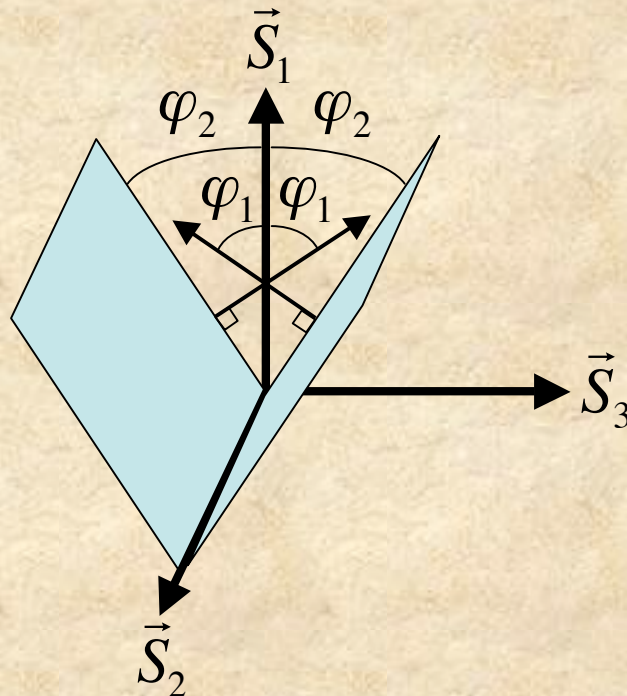
- Coulomb criterion for rupture
- Rupture occurs on optimal planes

$$\mu = \tan(\varphi_0) \approx 0.6$$

$$\varphi_0 \approx 30^\circ$$

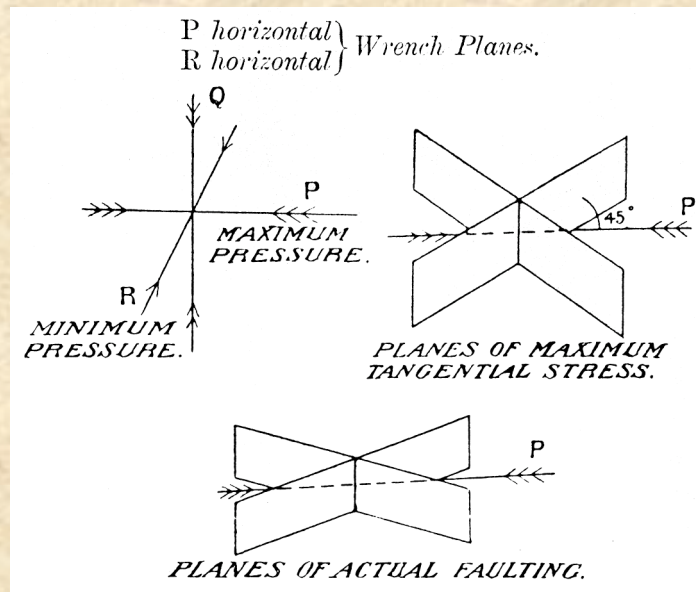
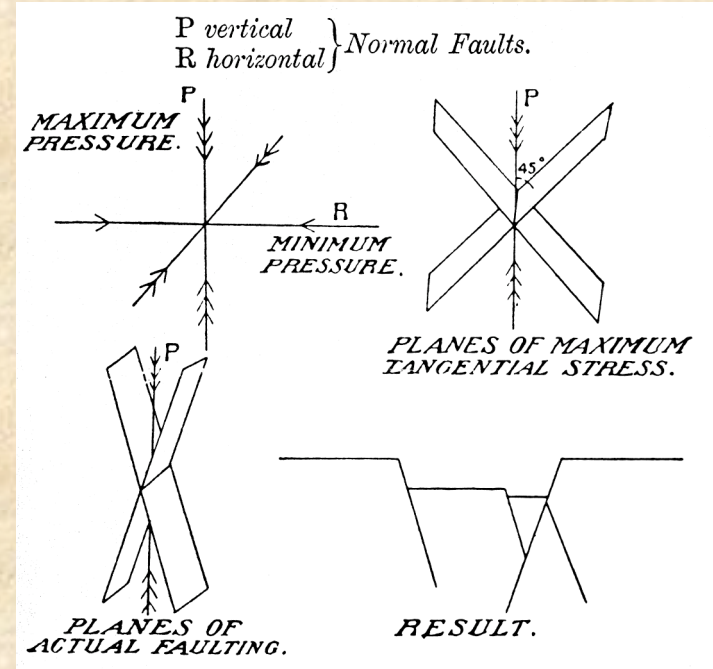
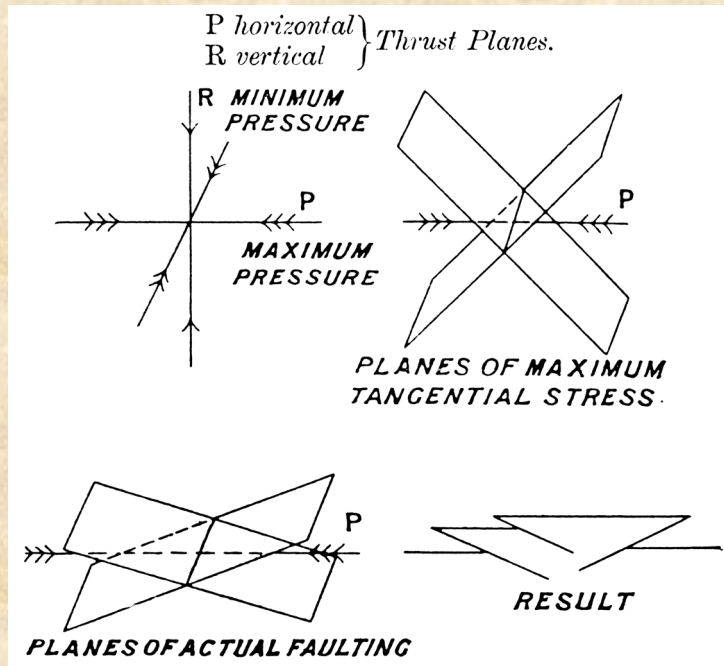
$$\varphi_1 = \frac{\varphi_0}{2} + \frac{\pi}{4} \approx 60^\circ$$

$$\varphi_2 = \frac{\pi}{4} - \frac{\varphi_0}{2} \approx 30^\circ$$



Stress orientation -> optimal conjugate faults
Fault & slip datum -> optimal stress orientation

The vertical is a principal stress direction



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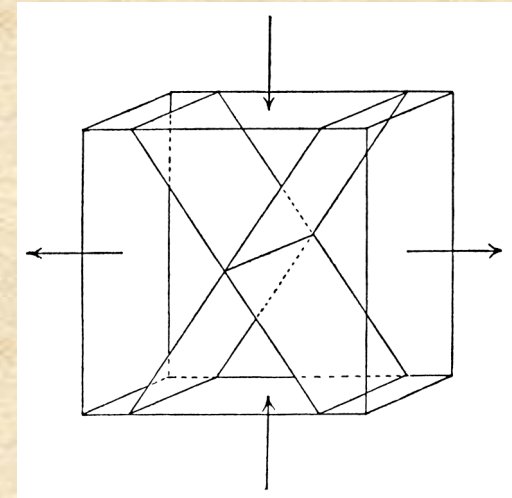
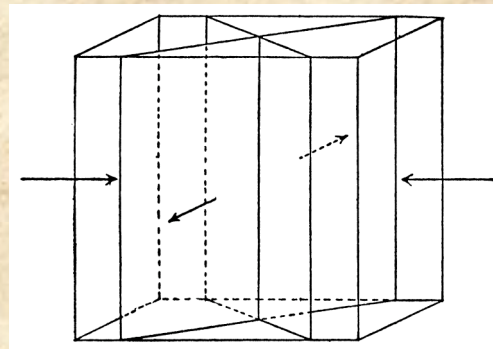
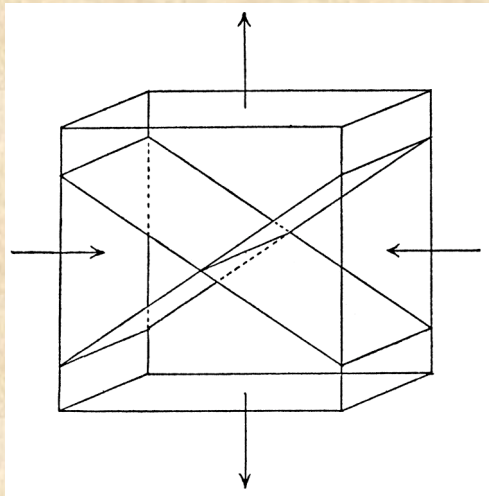
THE MECHANICAL INTERPRETATION OF JOINTS

WALTER H. BUCHER
University of Cincinnati

PART II

OUTLINE

MOHR'S THEORY
MOHR'S THEORY APPLIED TO EXPERIMENTAL DATA
THE ELLIPSOID OF STRAIN
PLANES OF SHEARING PRODUCED BY IRROTATIONAL AND ROTATIONAL STRAINS
PLANES OF SHEARING IN SHALES
HORIZONTAL COMPRESSIVE STRAINS IN GRANITE
LOW-ANGLE FAULTING



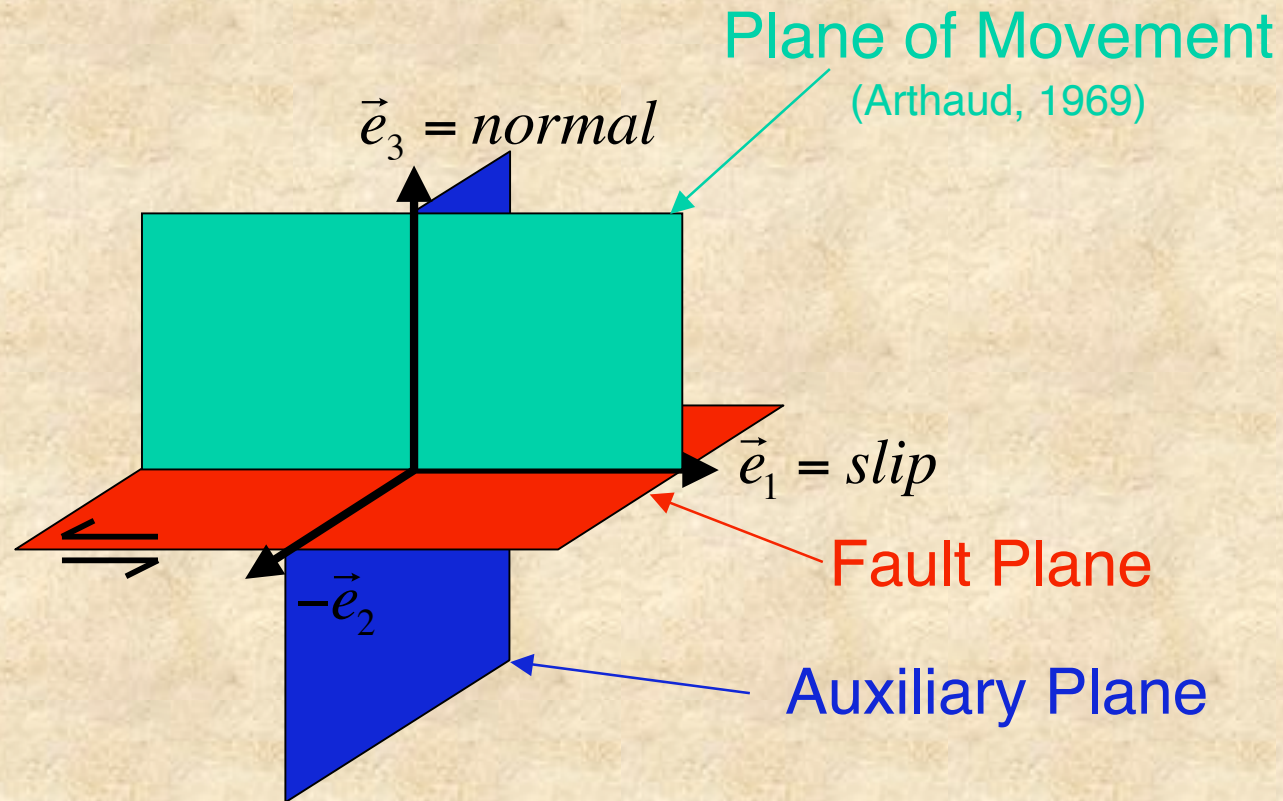
Eastern Kentucky, road cut, 1917
Hartmann (1896): Luder's lines,
Karman (1911), Daubree (1879).

Bucher, 1920-21

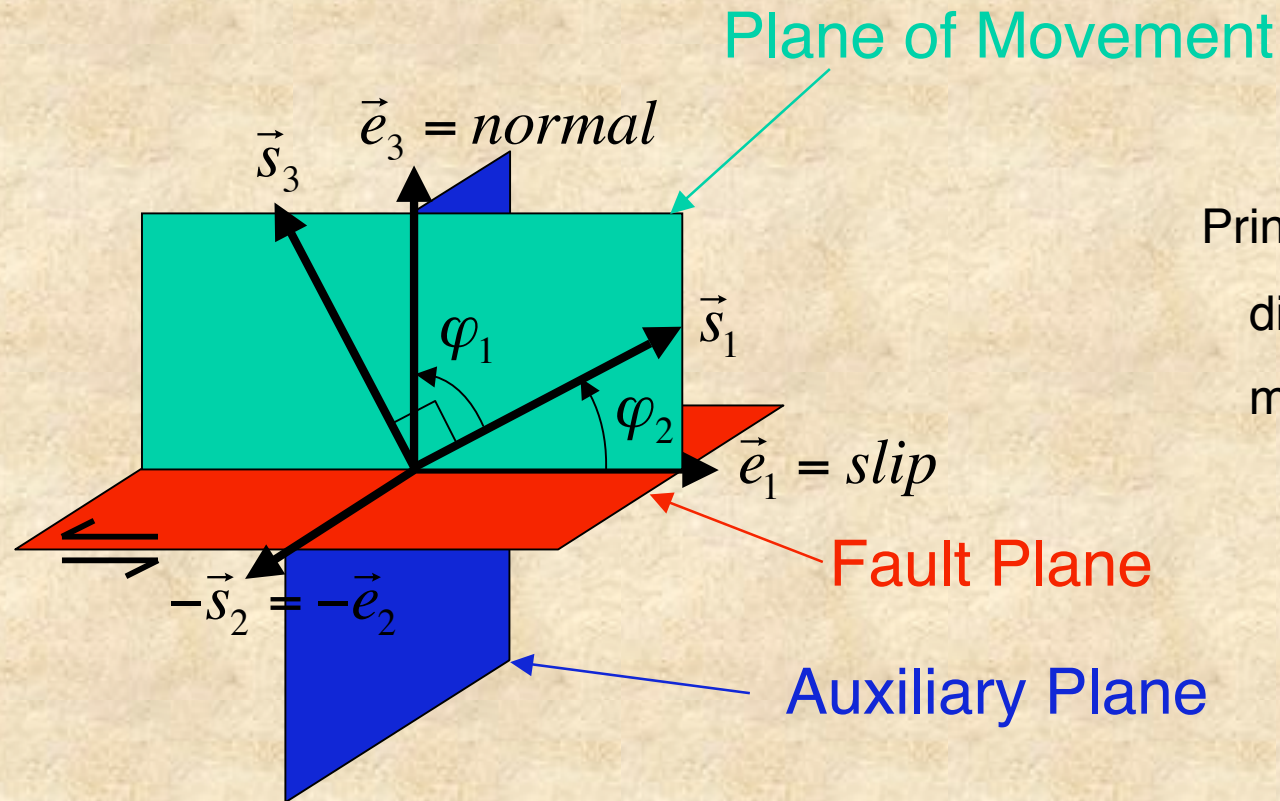
3 planes

Conjugate faults -> optimal stress orientation

Single fault & slip datum -> optimal stress orientation



optimal stress orientation



Principal stress

directions: $\vec{s}_1, \vec{s}_2, \vec{s}_3$

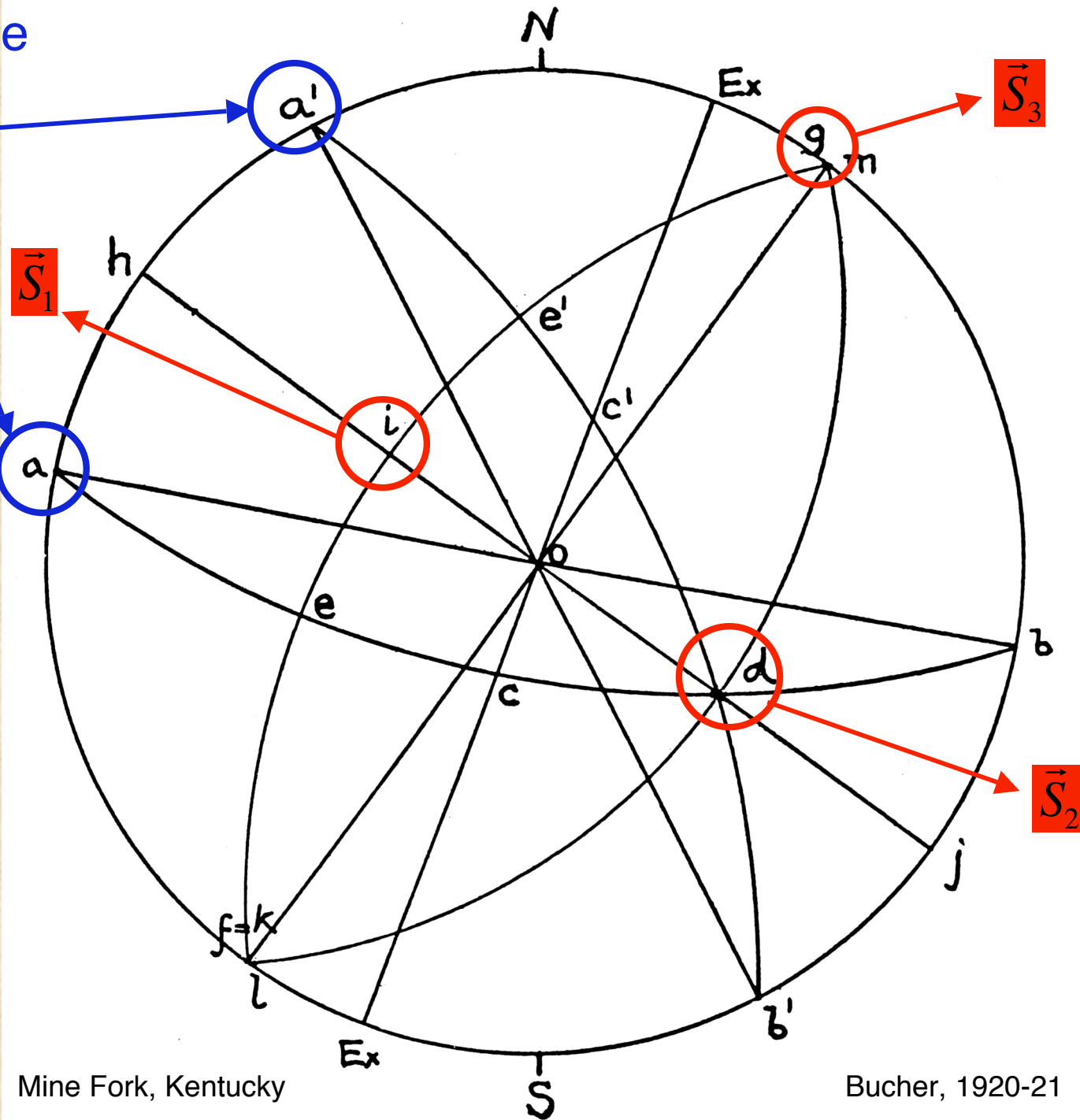
magnitudes: $\sigma_1 \geq \sigma_2 \geq \sigma_3$

$$\varphi_0 \approx 30^\circ$$

$$\varphi_1 = \frac{\varphi_0}{2} + 45^\circ \approx 60^\circ$$

$$\varphi_2 = 45^\circ - \frac{\varphi_0}{2} \approx 30^\circ$$

Conjugate faults

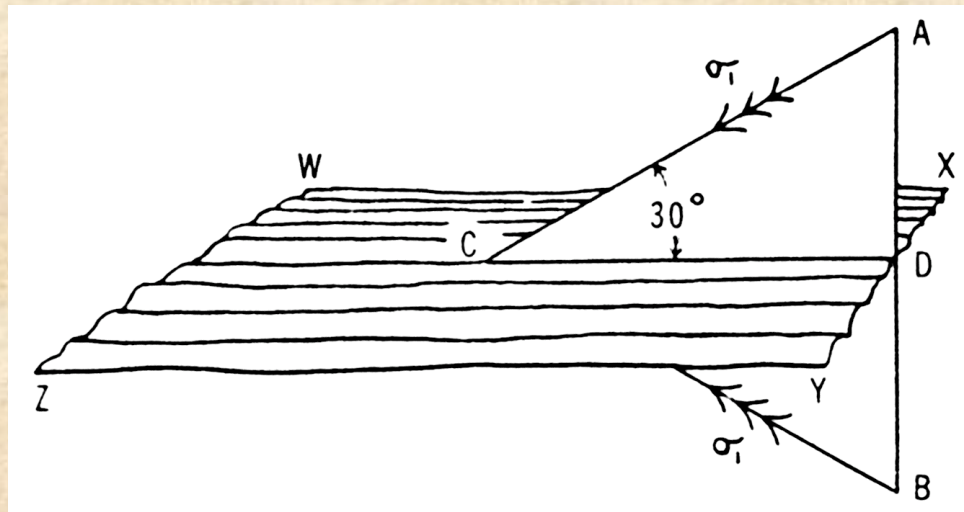


Mine Fork, Kentucky

Bucher, 1920-21

Single fault & slip datum -> optimal stress orientation

Anderson (1905)
Bucher (1921)
Turner (1953)
Compton (1966)
Raleigh et al. (1972)
Etchecopar (1984)



Compton, 1966, GSAB

Problem: non optimally oriented plane reactivation

Reactivation on non-optimally oriented planes McKenzie (1969):

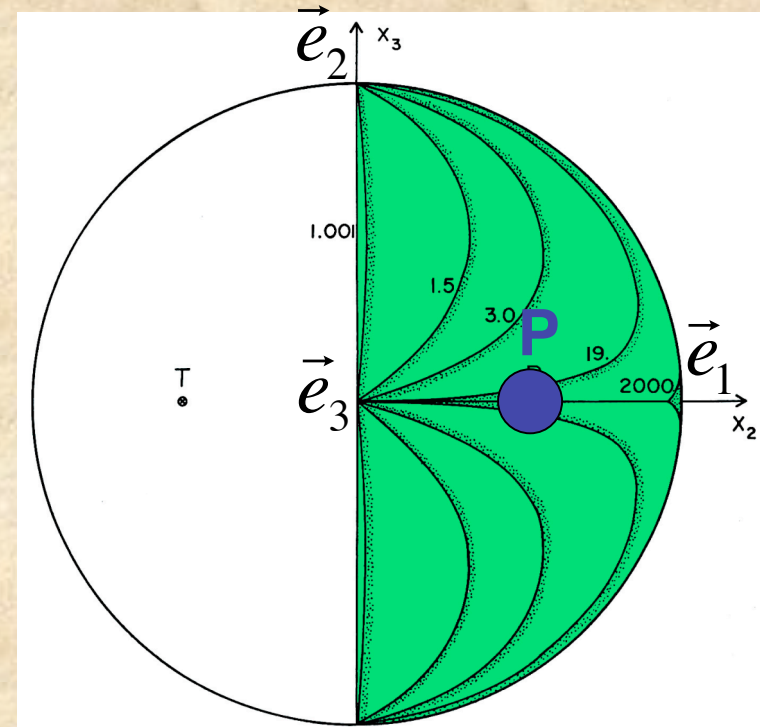
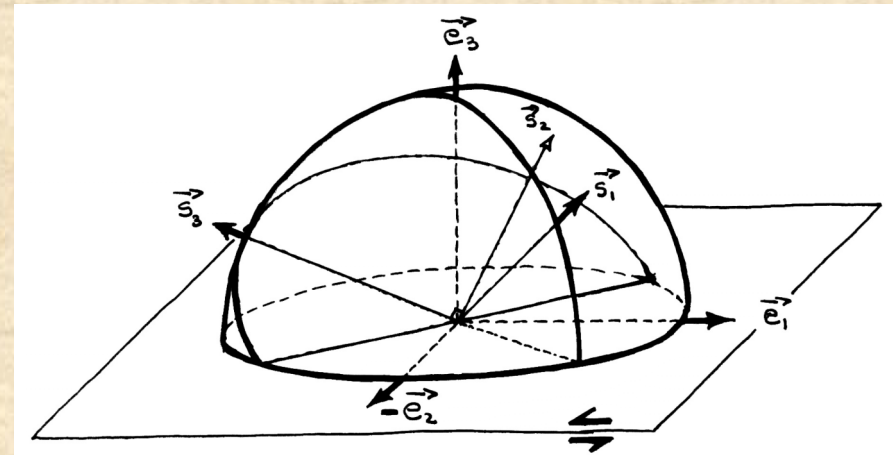
Shear stress along slip can be accommodated with s_1 anywhere within the dilatational quadrant

In the worst case, s_1 may be at right angle from P.

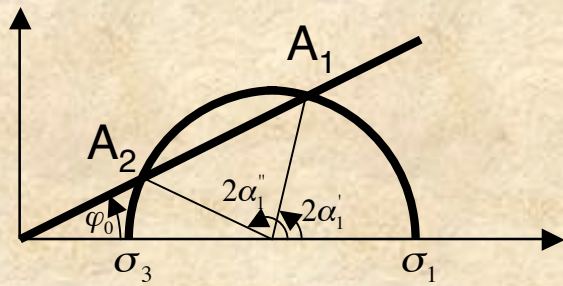
However (Jaeger, 1959, 1960):

Reactivating non-optimally oriented planes requires higher stress difference, or pore pressure, or lower friction coefficient.

Question: how frequent ?



2D frictional sliding

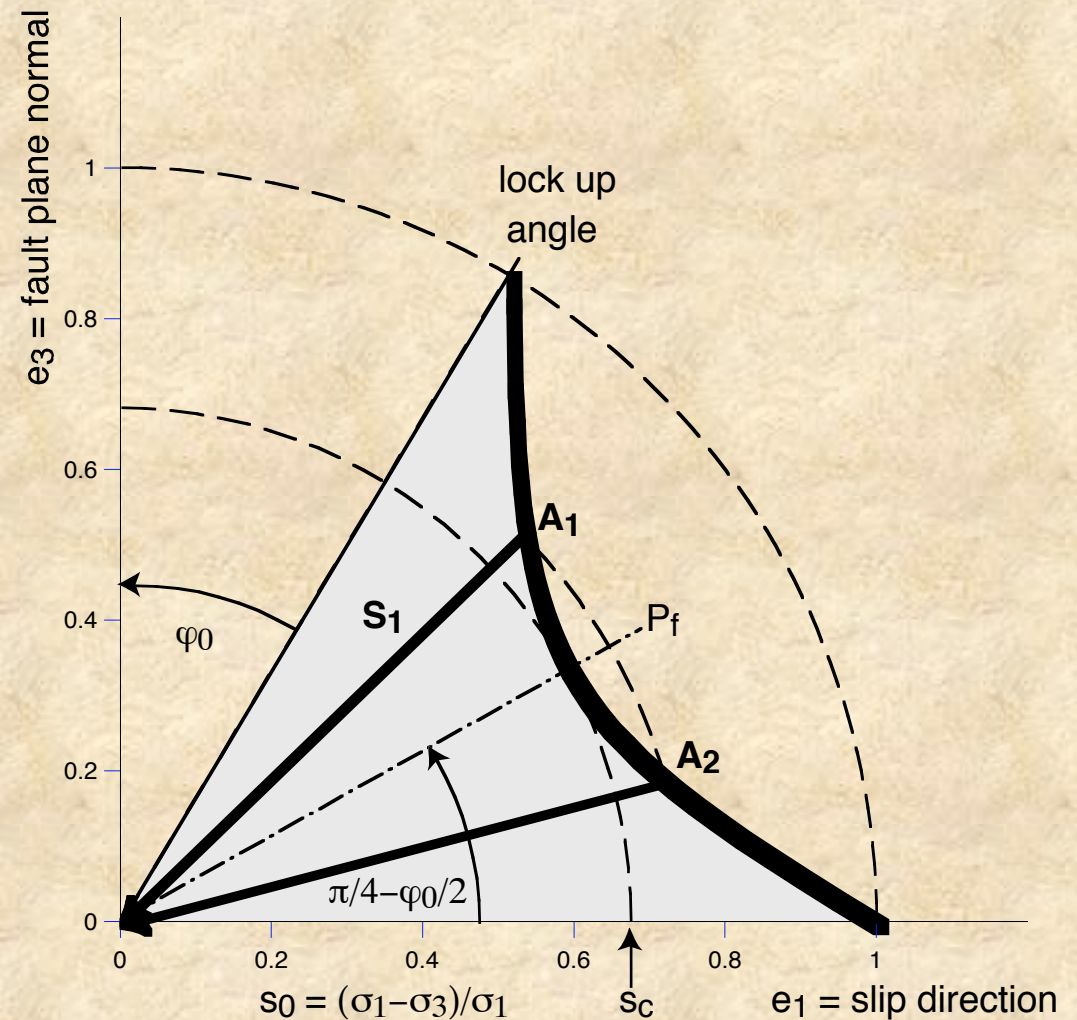


$$s_0 = \frac{\sigma'_1 - \sigma'_3}{\sigma'_1}$$

$$s_0 = \frac{2 \sin \varphi_0}{\sin(2\beta_1 + \varphi_0) + \sin \varphi_0}$$

$$s_c = \frac{2 \sin \varphi_0}{1 + \sin \varphi_0}$$

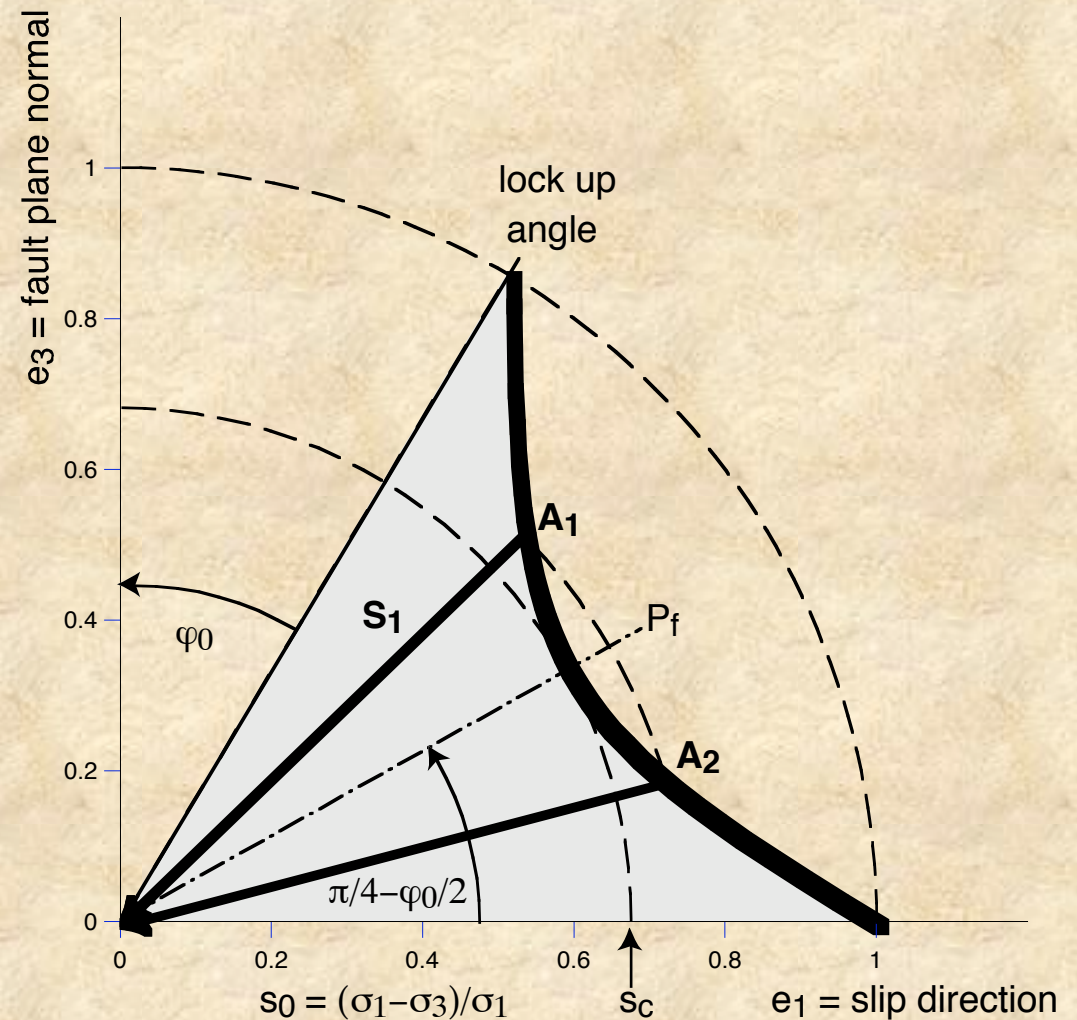
$$\varphi_0 = 31^\circ \quad s_c = 0.68$$



2D frictional sliding

Conclusions:

- S_1 away from P_f requires higher s_0 : either higher stress difference or higher pore pressure (lower σ'_1)
- Optimal stress direction P_f is relevant.

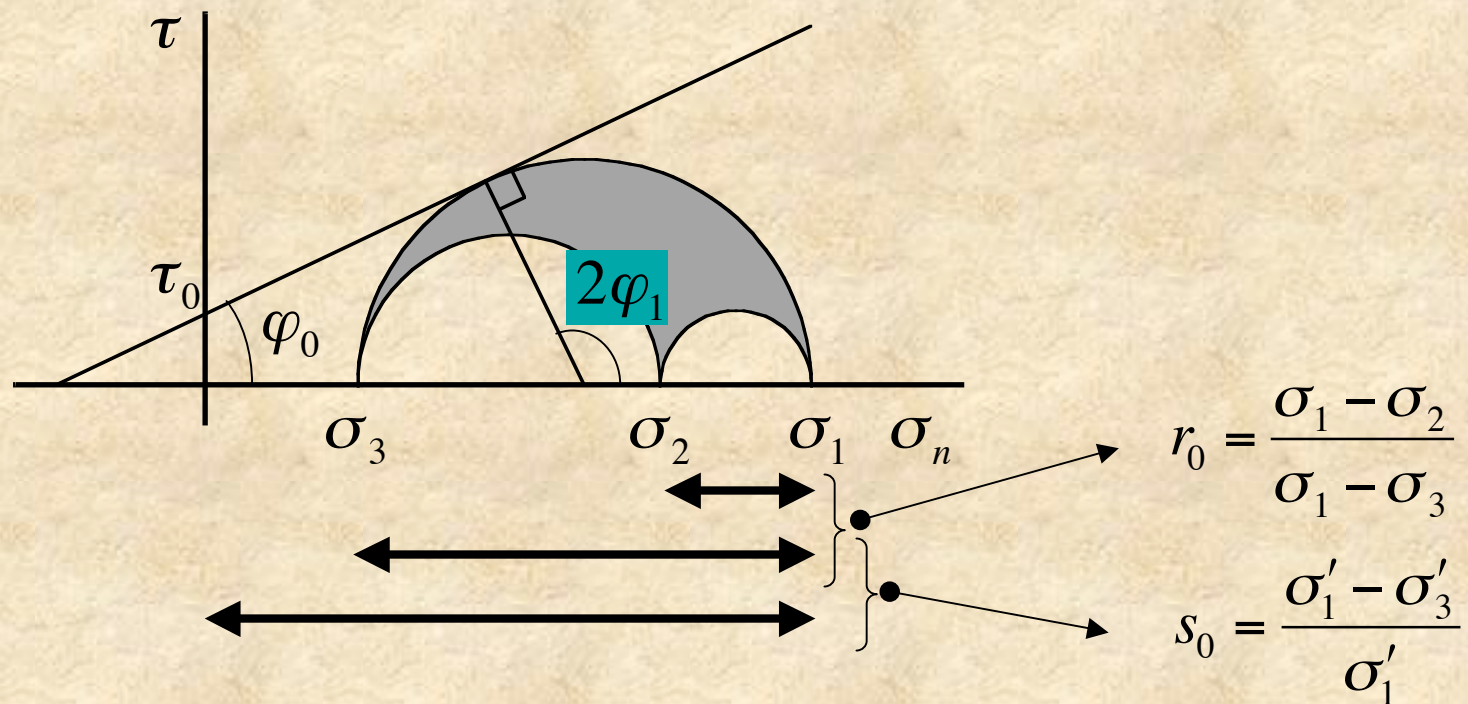


3D frictional sliding

Requirements:

slip along shear stress
satisfy a friction law

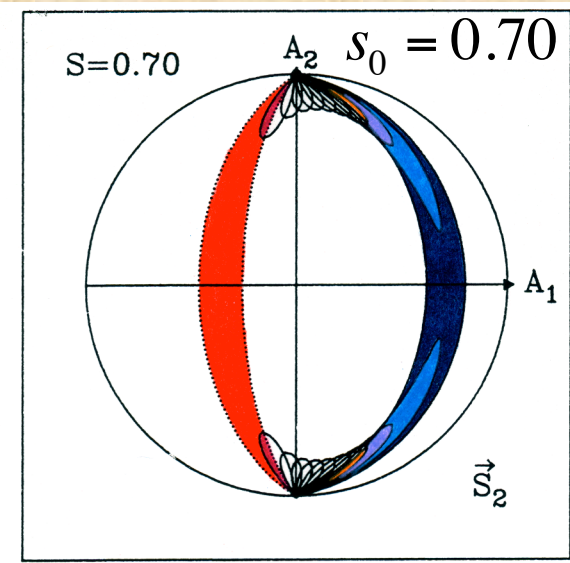
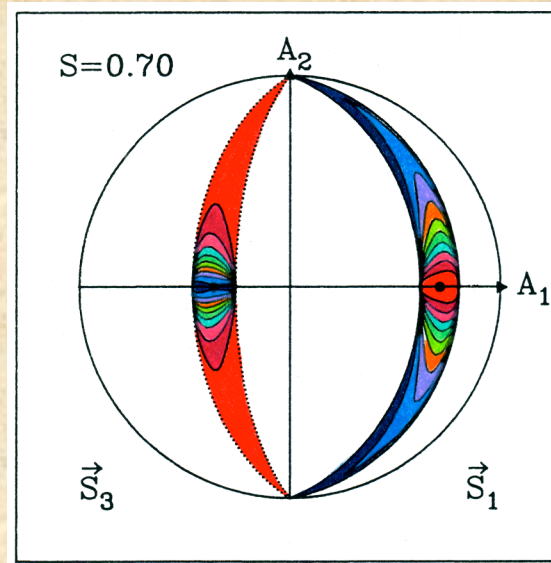
Define two parameters:



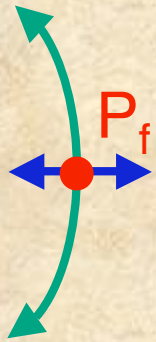
Can reduce the study to $\tau_0 = 0$ (Jaeger & Rosengren, 1969)

Trajectories of S_1, S_2, S_3 ,
satisfying both

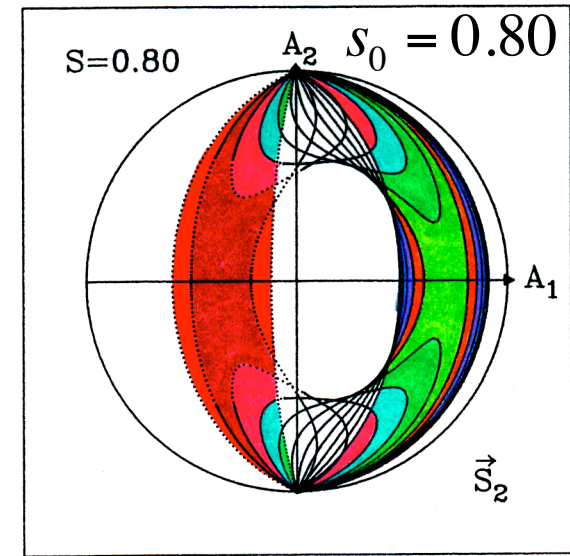
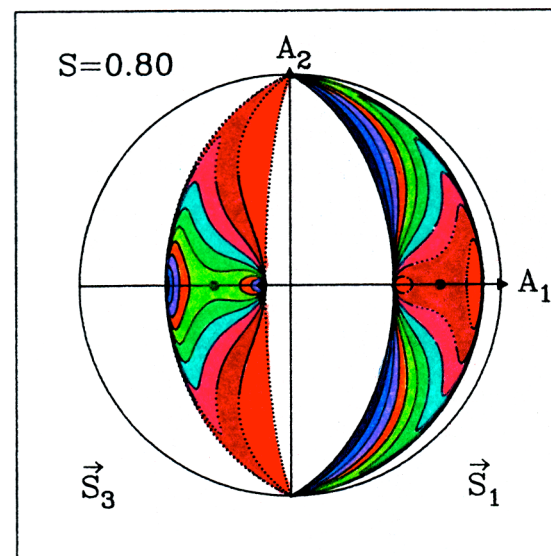
- shear stress along slip
- friction law



$r_0 \rightarrow 0.0$

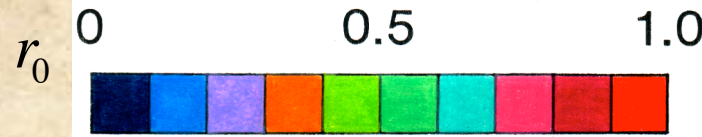


$s_0 \rightarrow 1.0$



$$s_0 = \frac{\sigma'_1 - \sigma'_3}{\sigma'_1}$$

$$r_0 = \frac{\sigma_1 - \sigma_2}{\sigma_1 - \sigma_3}$$



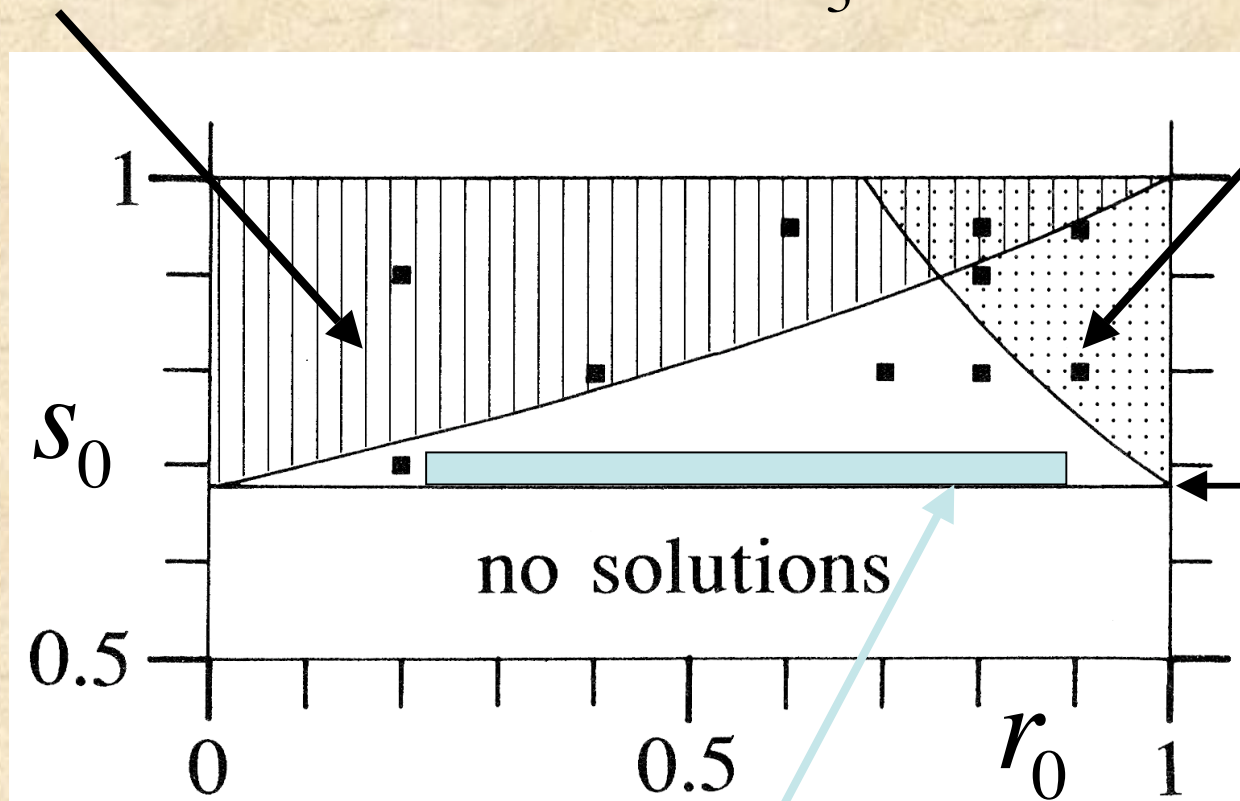
Celerier, 1988

$\vec{S}_1$ can lie in the fault plane

$\vec{S}_3$ can lie in the fault plane

$$s_0 = \frac{\sigma'_1 - \sigma'_3}{\sigma'_1}$$

$$r_0 = \frac{\sigma_1 - \sigma_2}{\sigma_1 - \sigma_3}$$



$$s_c = \frac{2 \sin \varphi_0}{1 + \sin \varphi_0}$$

s_c

$$\varphi_0 = 31^\circ$$

$$s_c = 0.68$$

Conclusion:

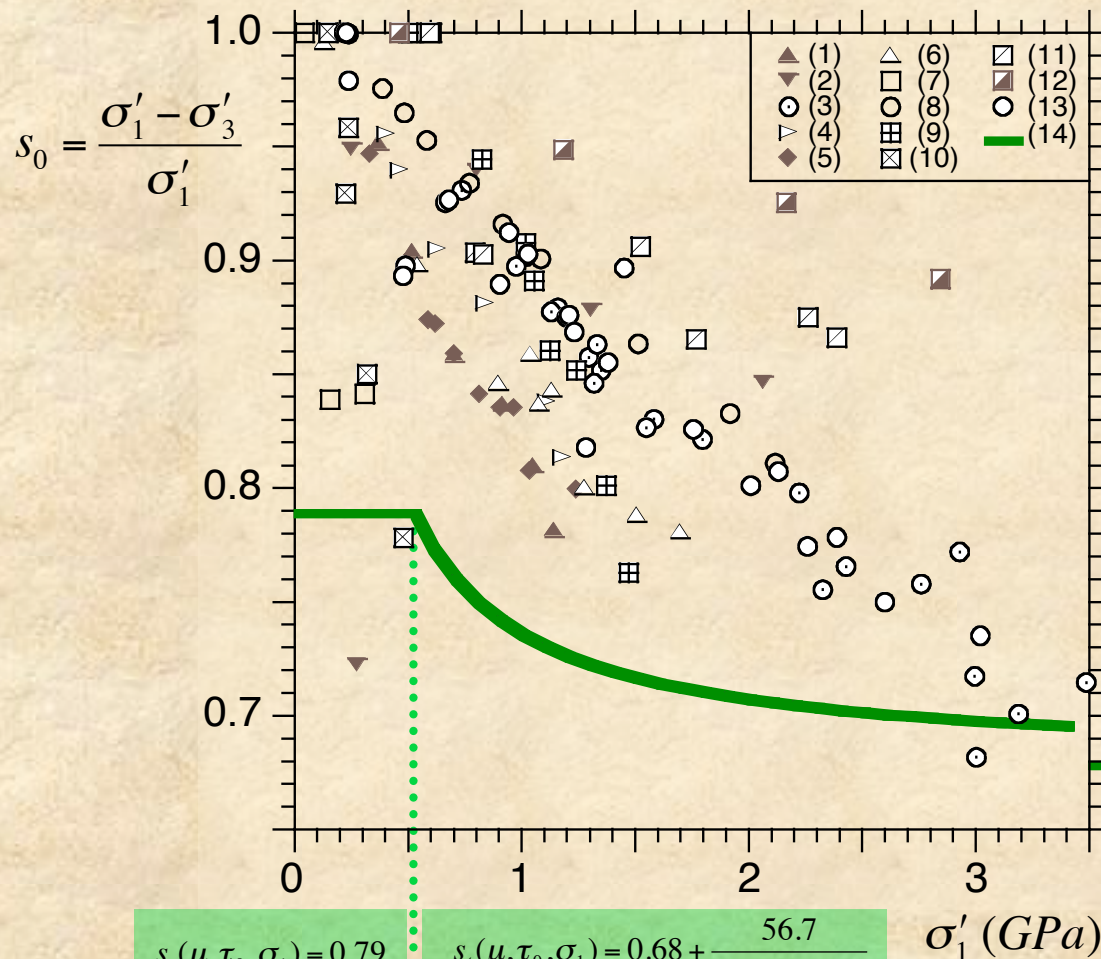
in states of stress where

- s_0 close to s_c

- r_0 remote from 0 or 1

optimal stress are relevant for faults with

- μ close to 0.6



- (1) Orikabe Diorite [Mogi, 1965]
- (2) Frederick Diabase [Brace, 1964]
- (3) Westerly Granite [Byerlee, 1967]
- (4) Mannari Granite [Mogi, 1965]
- (5) Haruyama Peridotite [Mogi, 1965]
- (6) Kitashirakawa Granite [Matsushima, 1959, 1960]
- (7) Marble [Brace et al., 1966]
- (8) Westerly Granite [Mogi, 1966a, 1966b]
- (9) Blair Dolomite [Brace, 1964]
- (10) Webatuk Dolomite [Brace, 1964]
- (11) Aplite [Brace et al., 1966]
- (12) Cheshire Quartzite [Brace, 1964]
- (13) Westerly Granite [Brace et al., 1966]
- (1-13) Also in Ohnaka [1973] & Sheorey [1997]
- (14) Reactivation of optimally oriented fracture with standard frictional properties [Byerlee, 1978]

Without cohesion:

$$s_c(\mu) = \frac{2 \sin \varphi_0}{1 + \sin \varphi_0} = 2\mu(\sqrt{1 + \mu^2} - \mu)$$

With cohesion:

$$s_t(\mu, \tau_0, \sigma_1) = \left(1 + \frac{\tau_0}{\mu \sigma_1}\right) s_c(\mu)$$

$$s_t(\mu, \tau_0, \sigma_1) = 0.79$$

$$s_c(\mu) = 0.79$$

$$\sigma_1 \leq 500 \text{ MPa}$$

$$\varphi_0 = 40^\circ$$

$$\mu = 0.85$$

$$\tau_0 = 0$$

$$\sigma_n \leq 200 \text{ MPa}$$

$$s_t(\mu, \tau_0, \sigma_1) = 0.68 + \frac{56.7}{\sigma_1 \text{ [in MPa]}}$$

$$s_c(\mu) = 0.68$$

$$\sigma_1 \geq 500 \text{ MPa}$$

$$\varphi_0 = 31^\circ$$

$$\mu = 0.6$$

$$\tau_0 = 50 \text{ MPa}$$

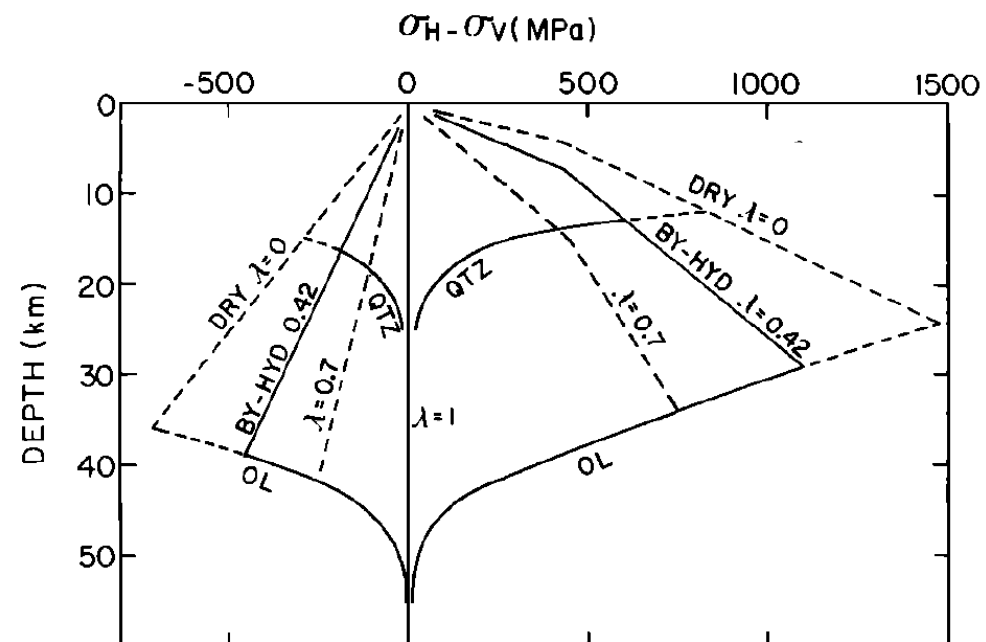
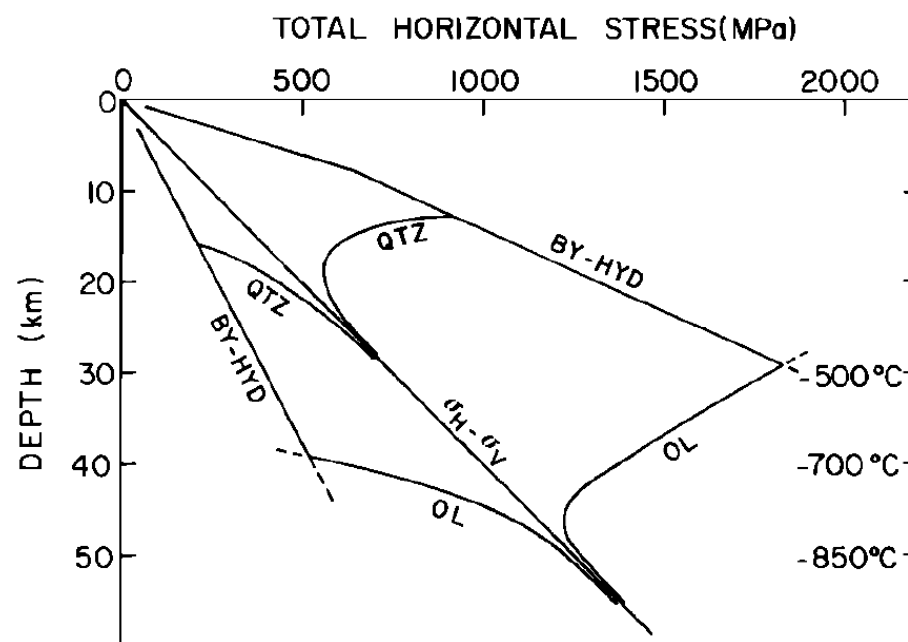
$$\sigma_n \geq 200 \text{ MPa}$$

[Byerlee, 1978]

$$\sigma_v = \sigma_1$$

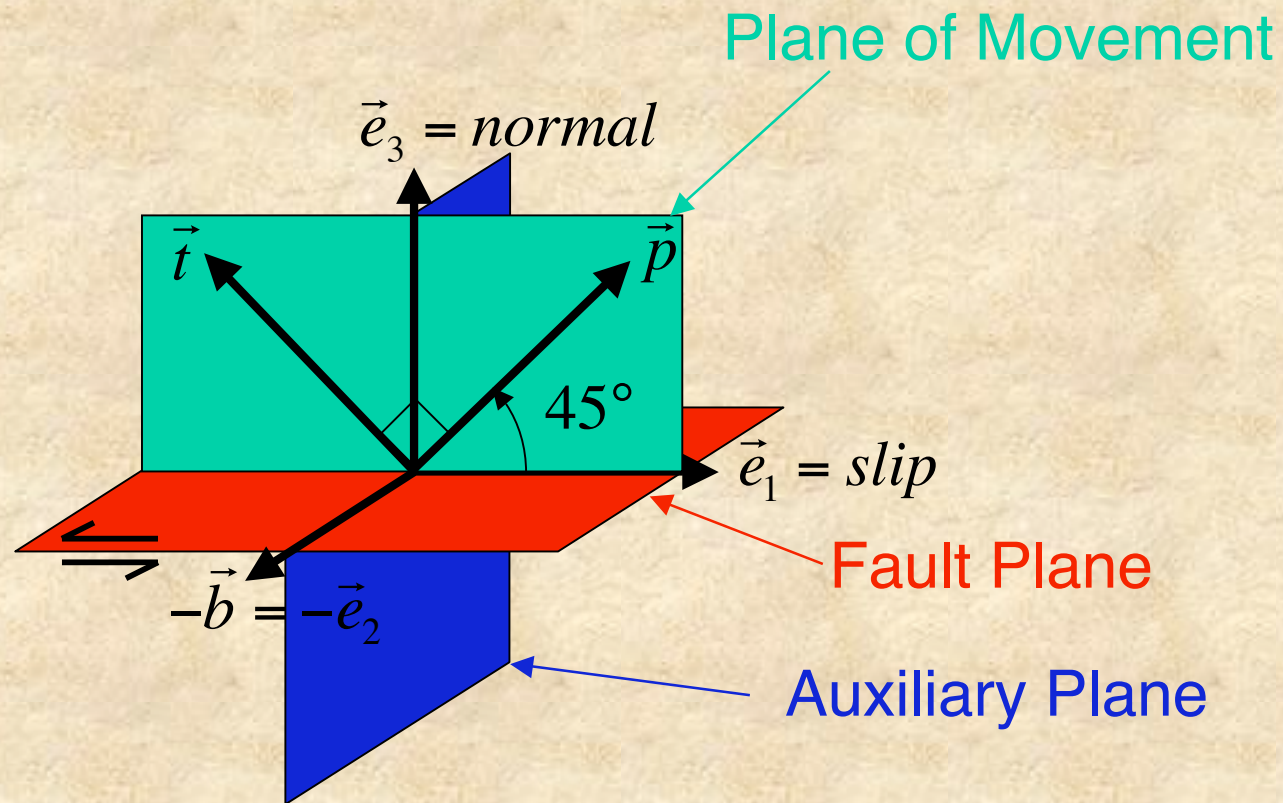
$$\alpha = 0 - 1$$

$$120 - 180 \text{ km}$$

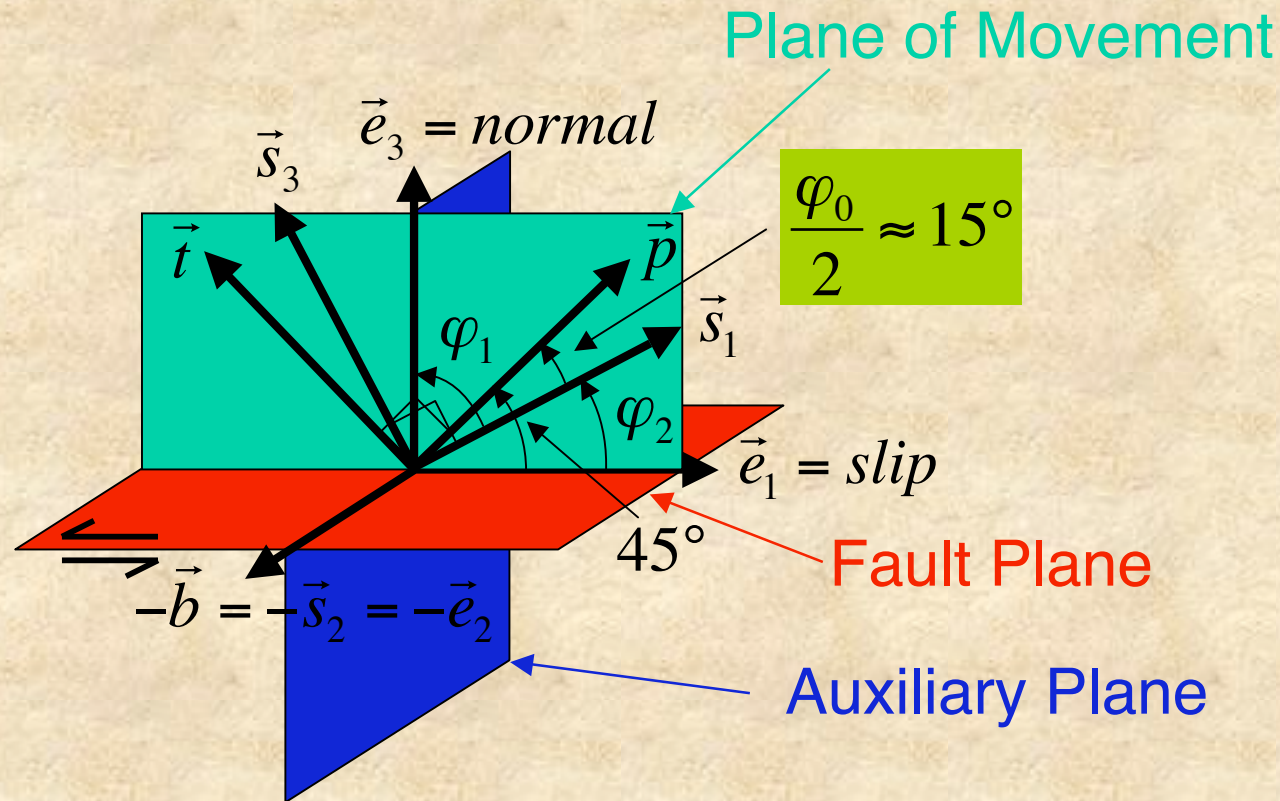


Brace & Kohlstedt, JGR Nov. 1980

P, B, T



optimal stress orientation close to P, B, T



$$\varphi_0 \approx 30^\circ$$

$$\varphi_1 = \frac{\varphi_0}{2} + 45^\circ \approx 60^\circ$$

$$\varphi_2 = 45^\circ - \frac{\varphi_0}{2} \approx 30^\circ$$

Triangular diagrams

Original definition (Frohlich, 1992, 2001)

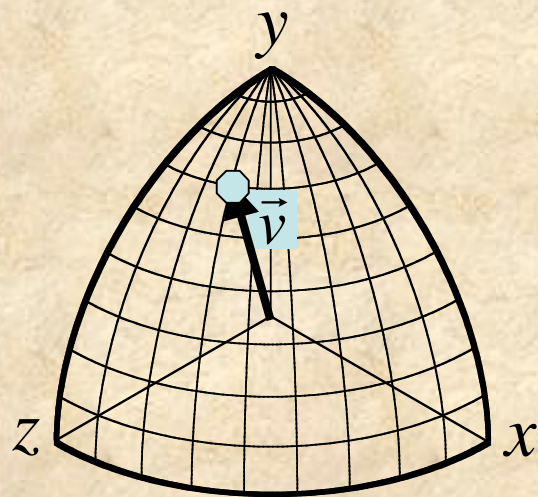
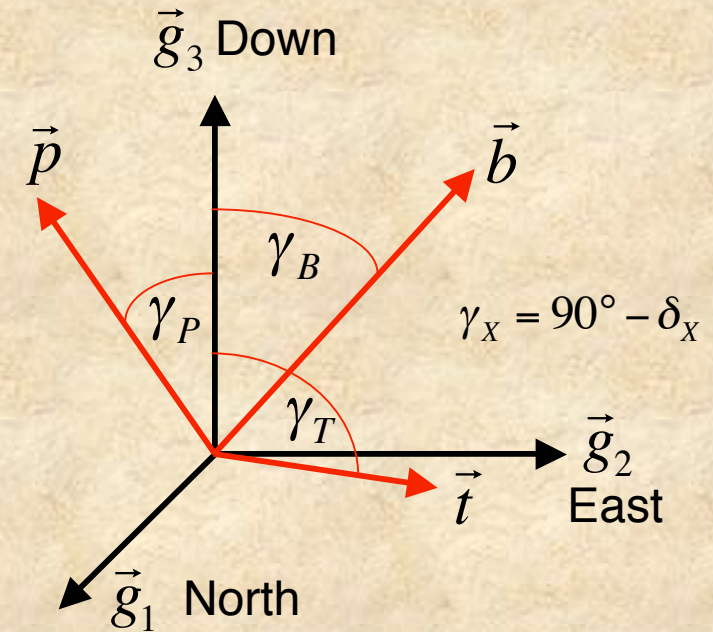
Geographical frame $G = (\vec{g}_1, \vec{g}_2, \vec{g}_3)$

P,B,T frame $Q = (\vec{p}, \vec{b}, \vec{t})$

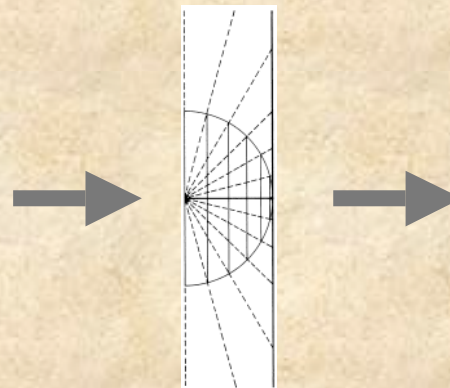
Plunges of P,B,T: $\delta_P, \delta_B, \delta_T$ in $[0, 90^\circ]$

$$Q^G = \begin{bmatrix} \vec{p} & \vec{b} & \vec{t} \\ q_{11} & q_{12} & q_{13} \\ q_{21} & q_{22} & q_{23} \\ \boxed{q_{31} & q_{32} & q_{33}} \end{bmatrix} \rightarrow \vec{v} = \begin{bmatrix} \sin \delta_P \\ \sin \delta_B \\ \sin \delta_T \end{bmatrix} = \pm \begin{bmatrix} q_{31} \\ q_{32} \\ q_{33} \end{bmatrix}$$

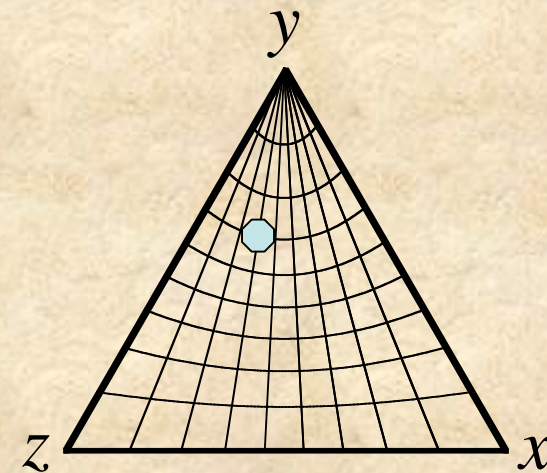
$$\|\vec{v}\| = 1$$



Gnomonic projection



Great circles -> lines
Seismic rays -> lines

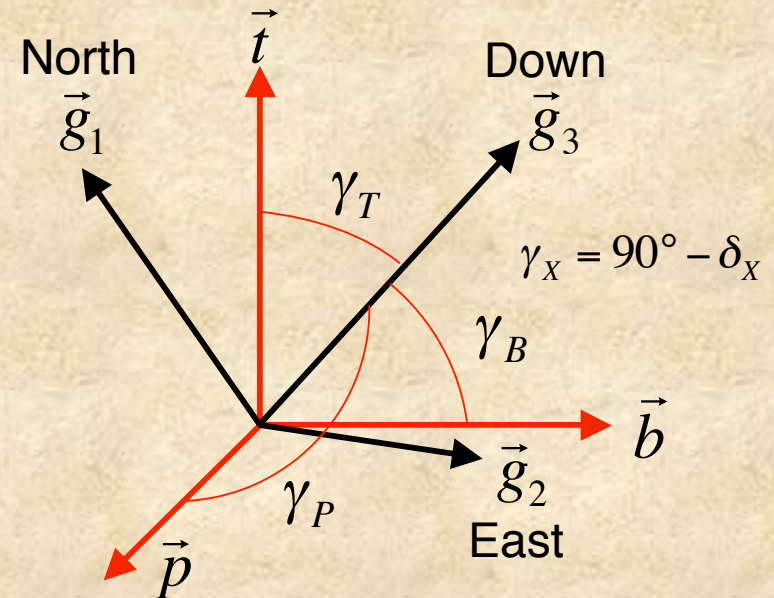


Triangular diagrams

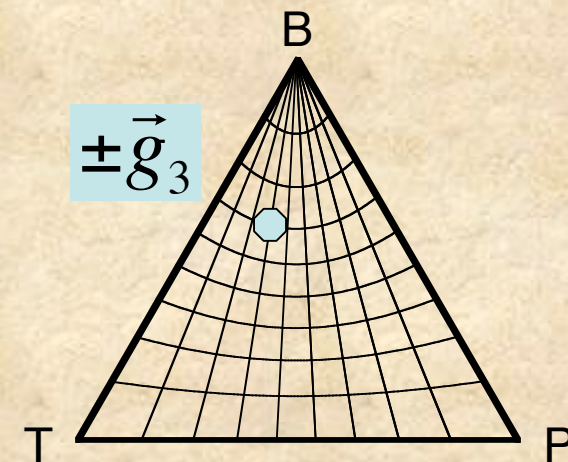
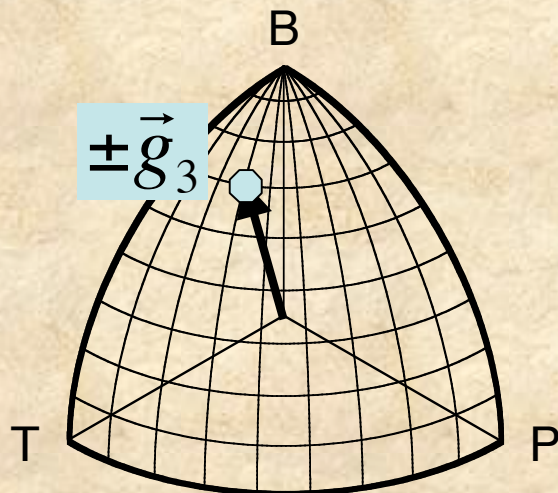
Alternate interpretation

$$G^Q = \begin{bmatrix} g_{11} & g_{12} & \boxed{g_{13}} \\ g_{21} & g_{22} & \boxed{g_{23}} \\ g_{31} & g_{32} & \boxed{g_{33}} \end{bmatrix} \quad \vec{g}_3 = \begin{bmatrix} g_{13} \\ g_{23} \\ g_{33} \end{bmatrix} = \begin{bmatrix} q_{31} \\ q_{32} \\ q_{33} \end{bmatrix} = \pm \begin{bmatrix} \sin \delta_P \\ \sin \delta_B \\ \sin \delta_T \end{bmatrix}$$

$$G^Q = (Q^G)^{-1} = {}^t Q^G$$

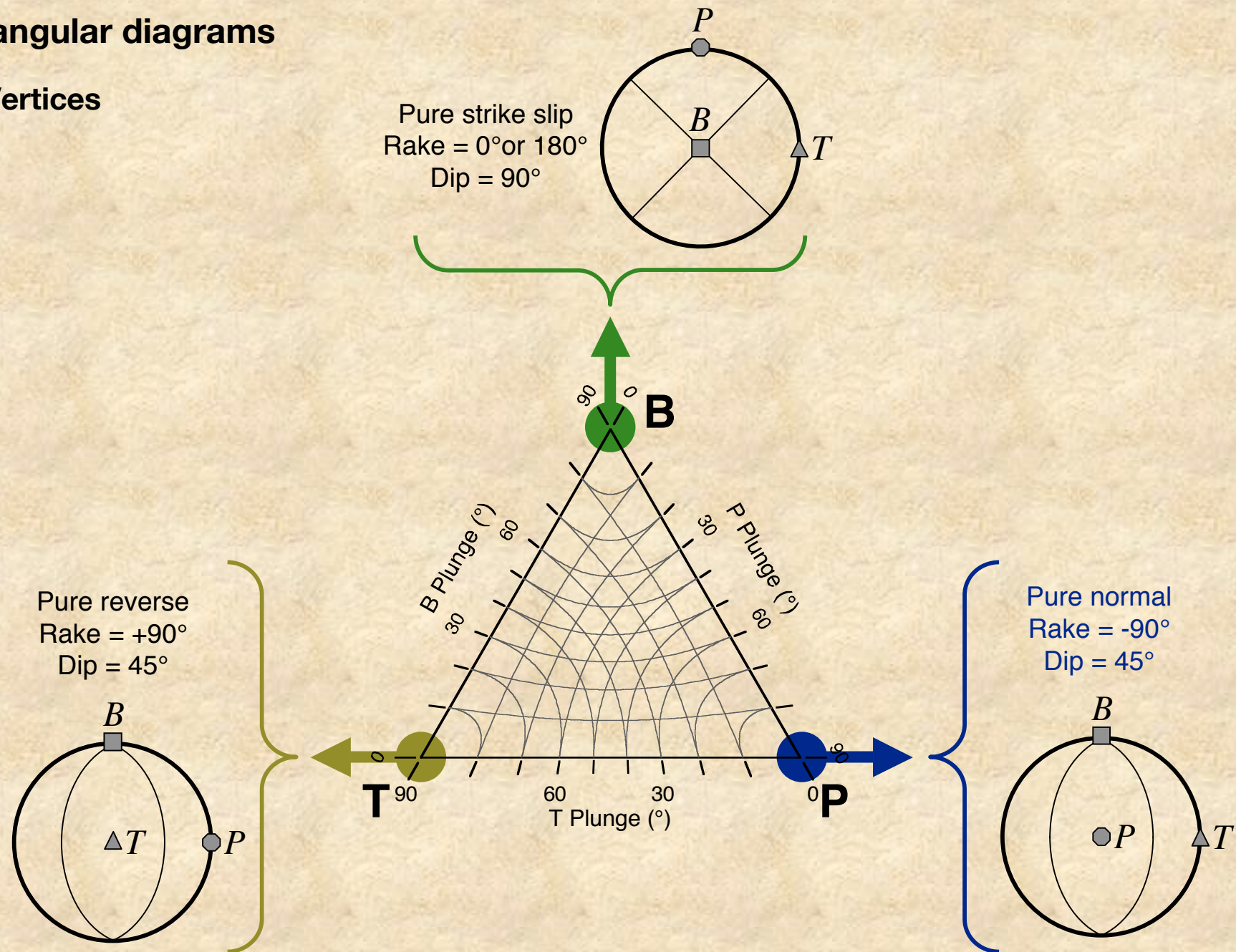


$\vec{v} = \pm \vec{g}_3 \Rightarrow$ The triangular diagram represents the upgoing or downgoing vertical within the P,B,T frame



Triangular diagrams

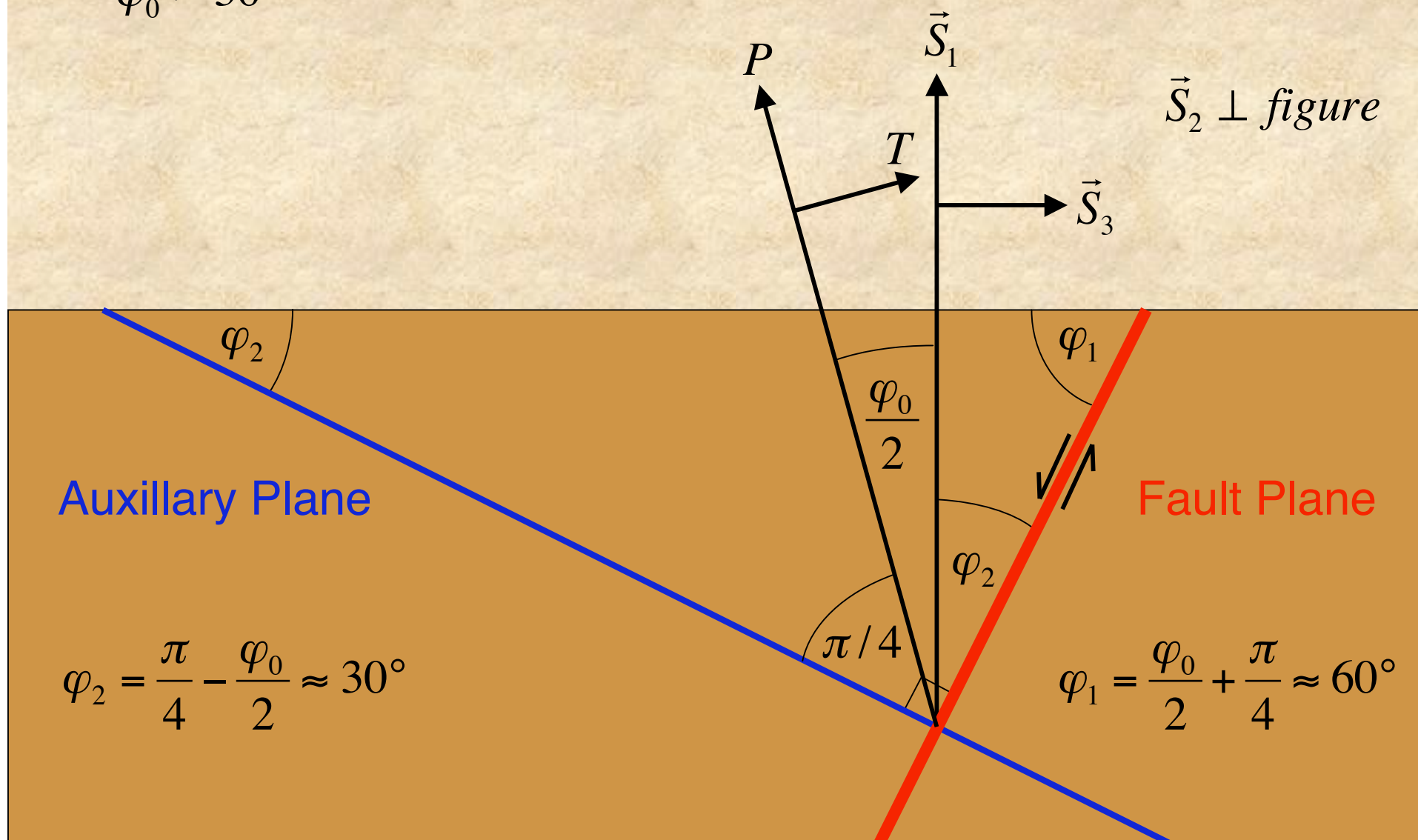
Vertices



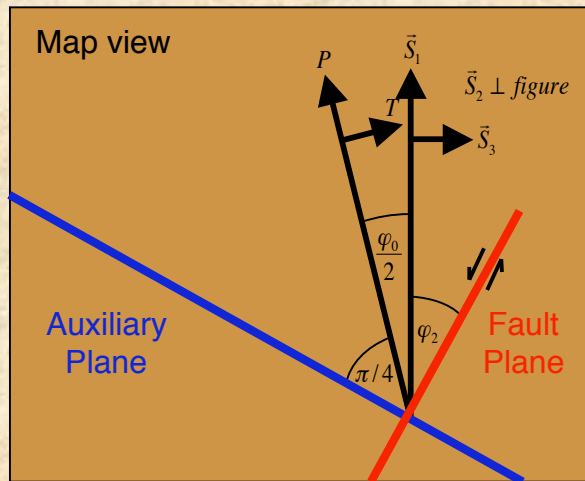
Anderson's Normal Faulting

Cross section

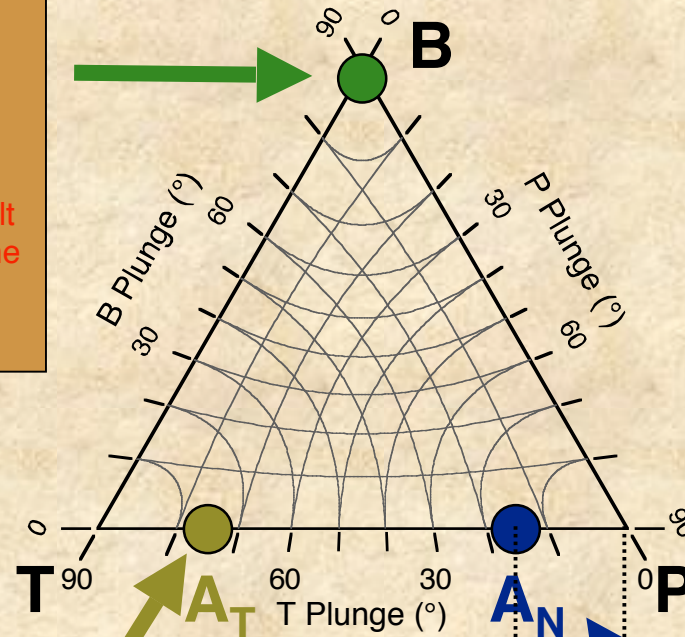
$$\varphi_0 \approx 30^\circ$$



location of Anderson faulting



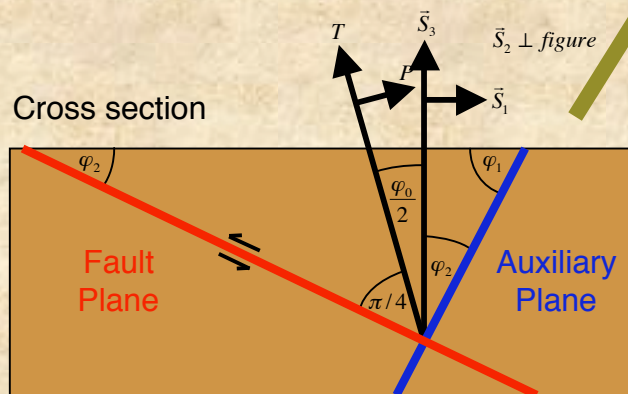
Anderson's Strike-slip Faulting



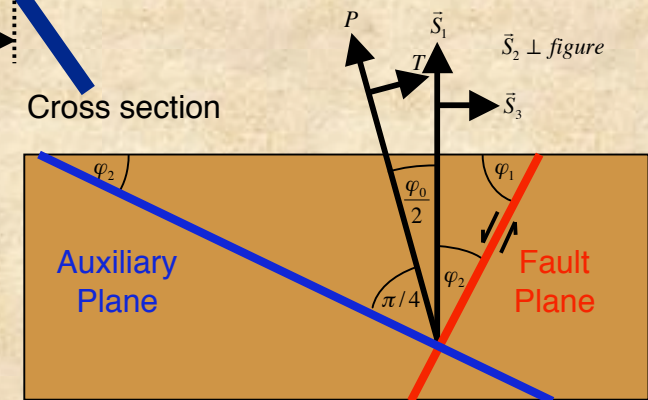
$$\varphi_0 \approx 30^\circ$$

$$\varphi_1 = \frac{\varphi_0}{2} + \frac{\pi}{4} \approx 60^\circ$$

$$\varphi_2 = \frac{\pi}{4} - \frac{\varphi_0}{2} \approx 30^\circ$$



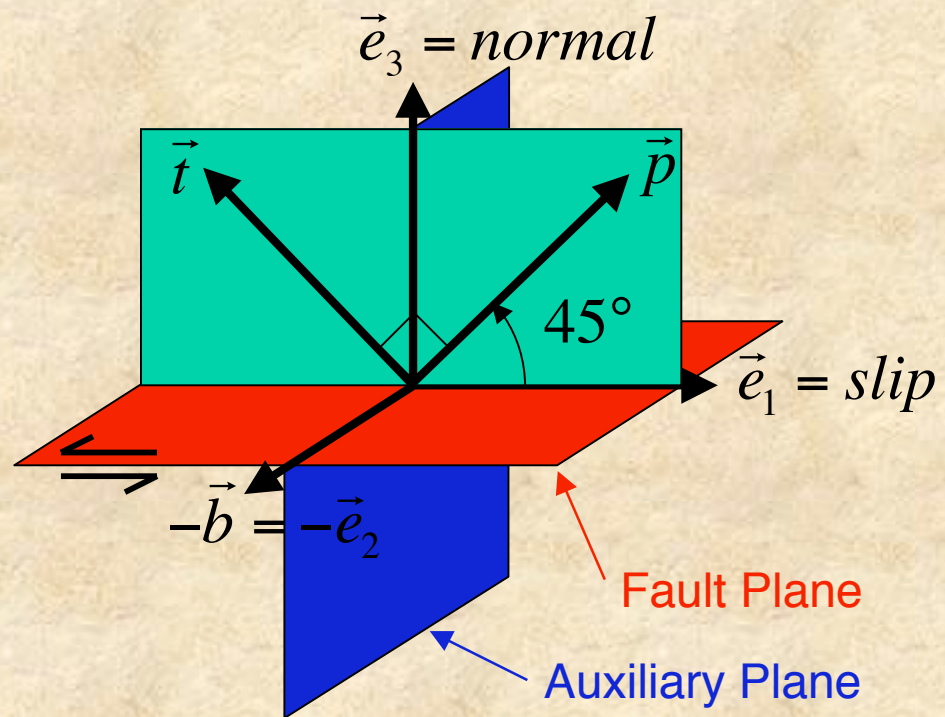
Anderson's Reverse Faulting



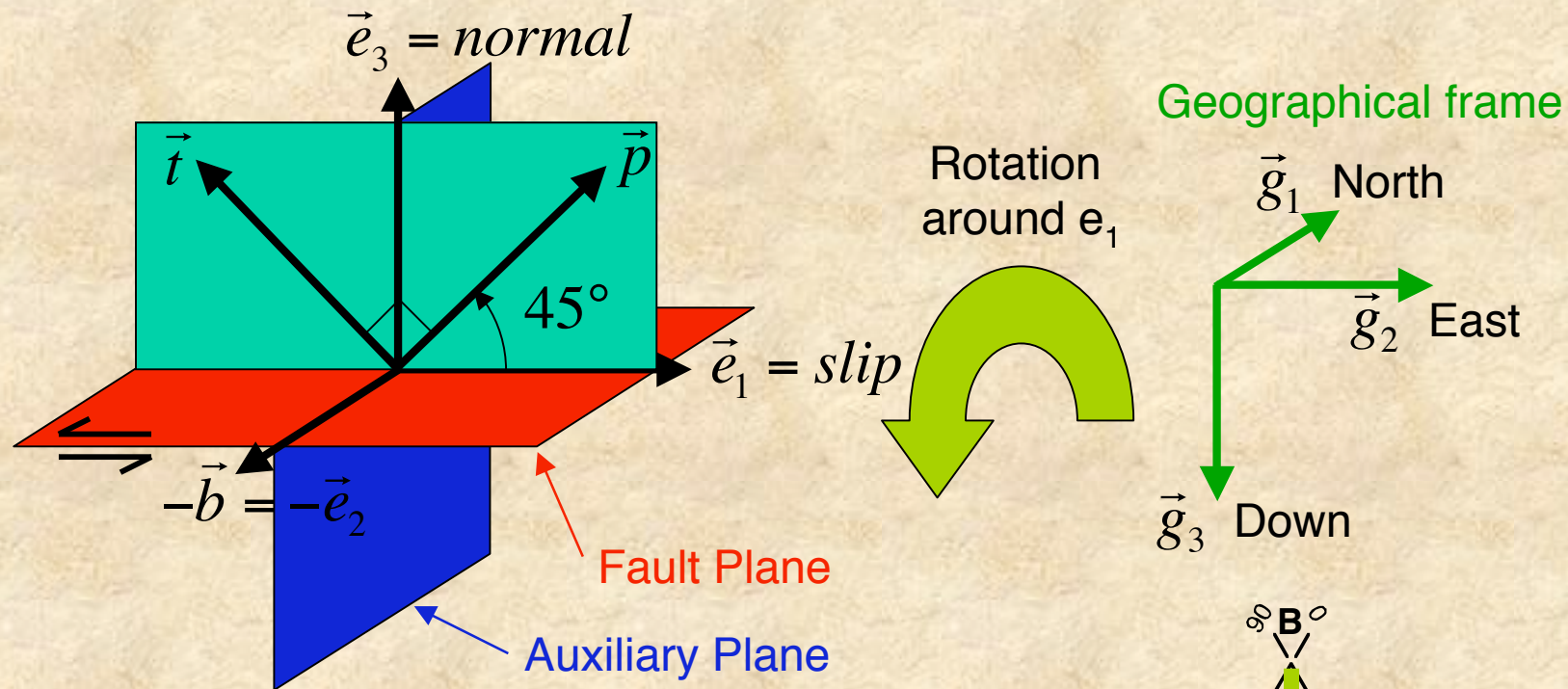
Anderson's Normal Faulting

Frohlich, Geophys. J. Int., 2001
C  lerier, Rev. Geophysics, 2008

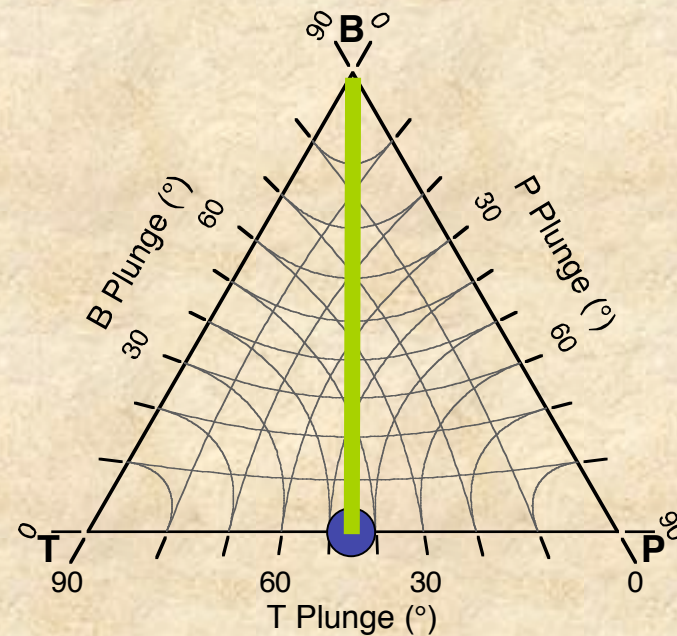
P,B,T plunges versus slip: geometry



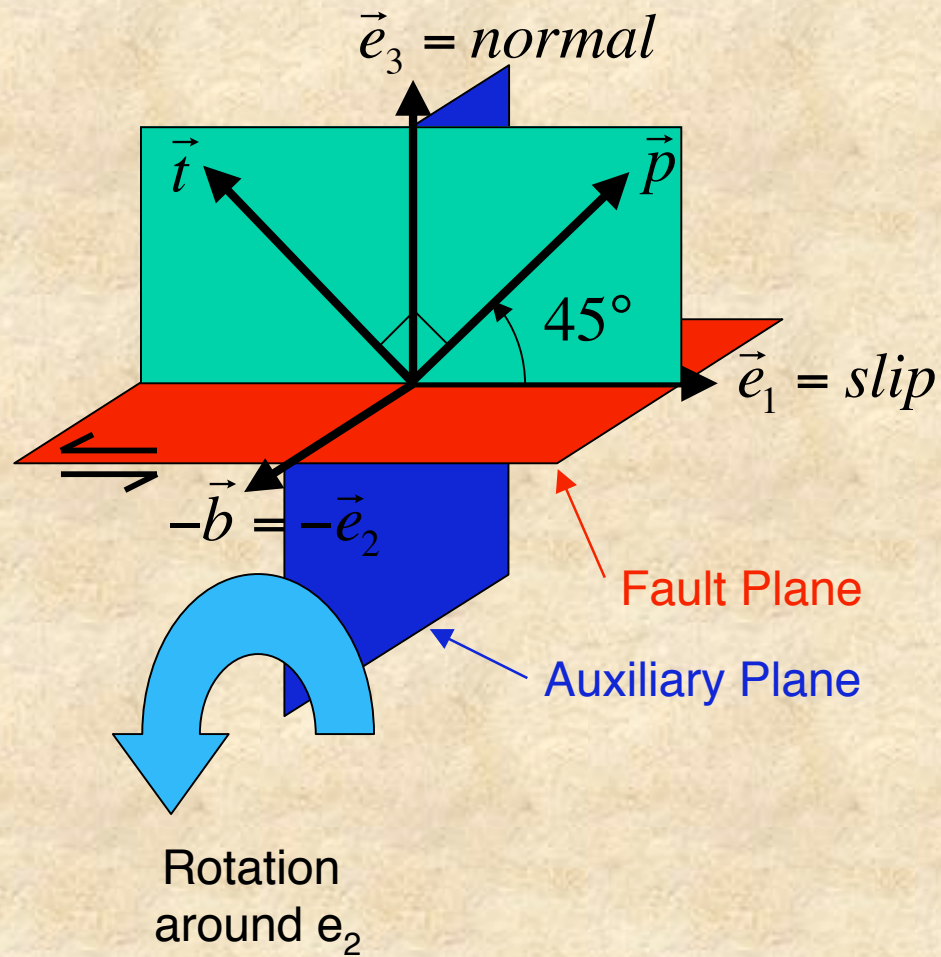
P,B,T plunges versus strike-slip



B plunge varies from 0° to 90°
 P and T plunges remain equal
 Fault plane remains pure strike-slip

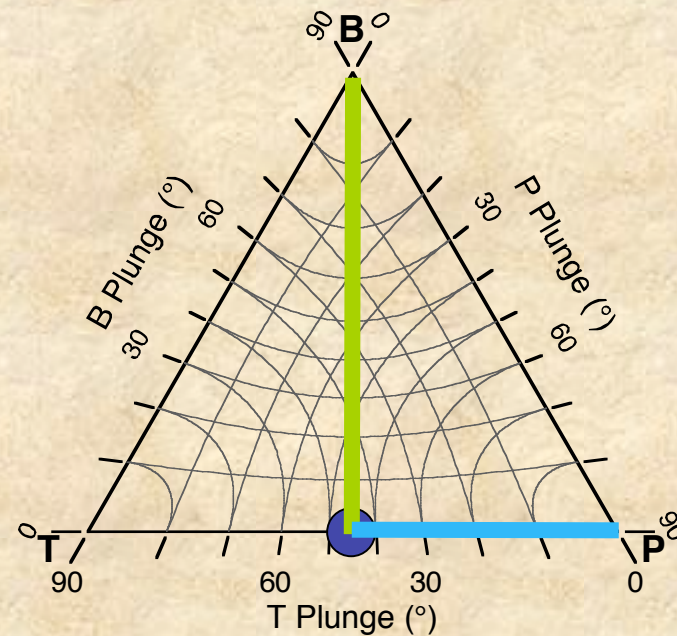
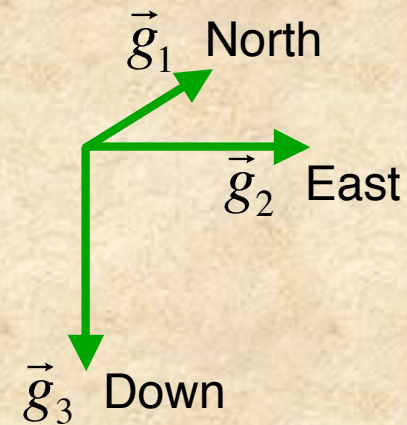


P,B,T plunges versus normal slip

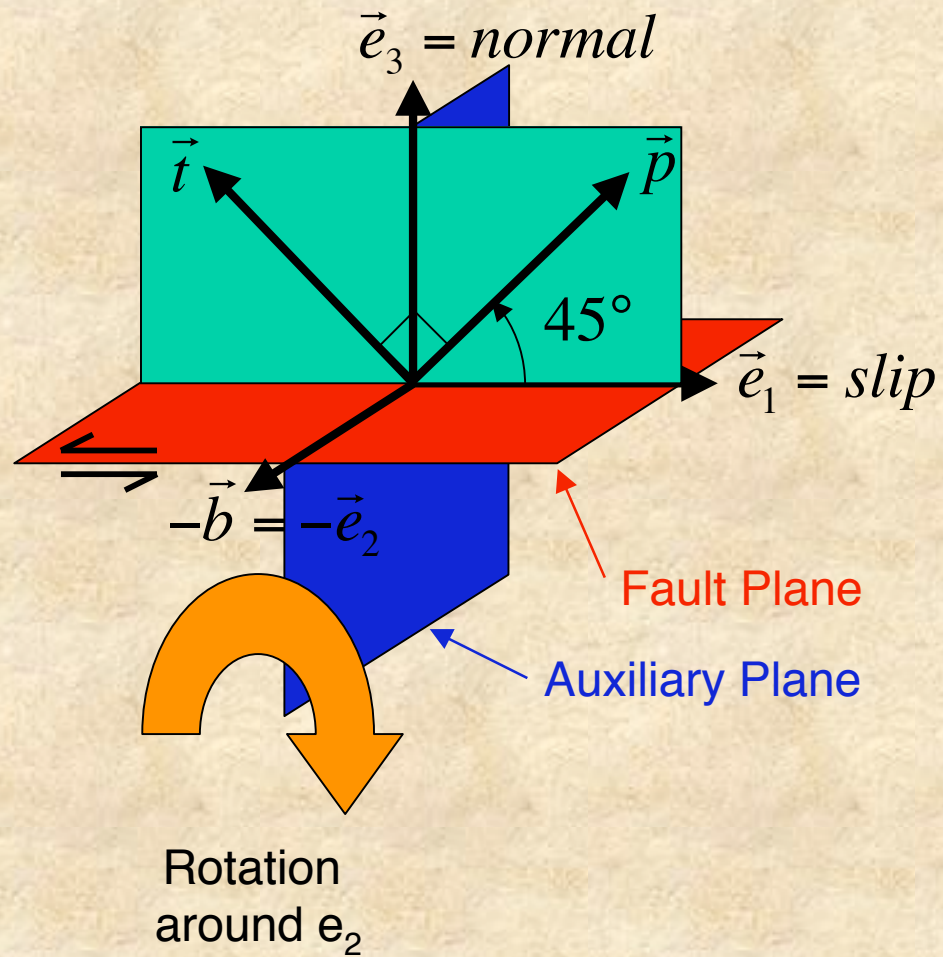


B plunge remains 0°
 P plunge varies from 45° to 90°
 Fault plane is pure normal slip

Geographical frame

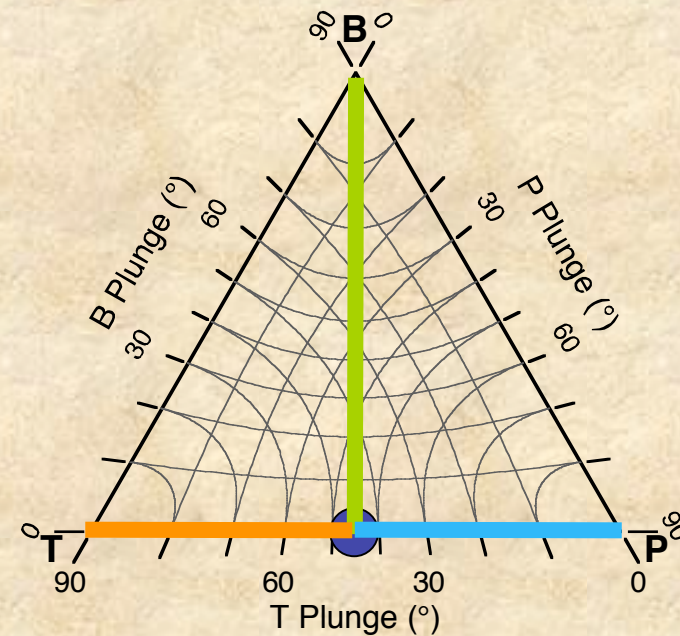
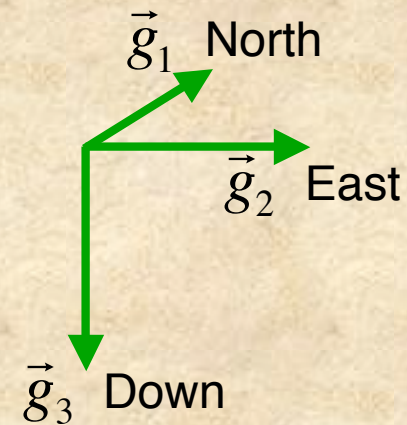


P,B,T plunges versus reverse slip



B plunge remains 0°
 T plunge varies from 45° to 90°
 Fault plane is pure reverse slip

Geographical frame



P,B,T plunges versus dip or strike slip: conclusions

Both nodal planes:

strike slip $\Leftrightarrow$ B plunge = 90° ●
 normal slip $\Leftrightarrow$ P plunge = 90° ●
 reverse slip $\Leftrightarrow$ T plunge = 90° ●

One nodal plane :

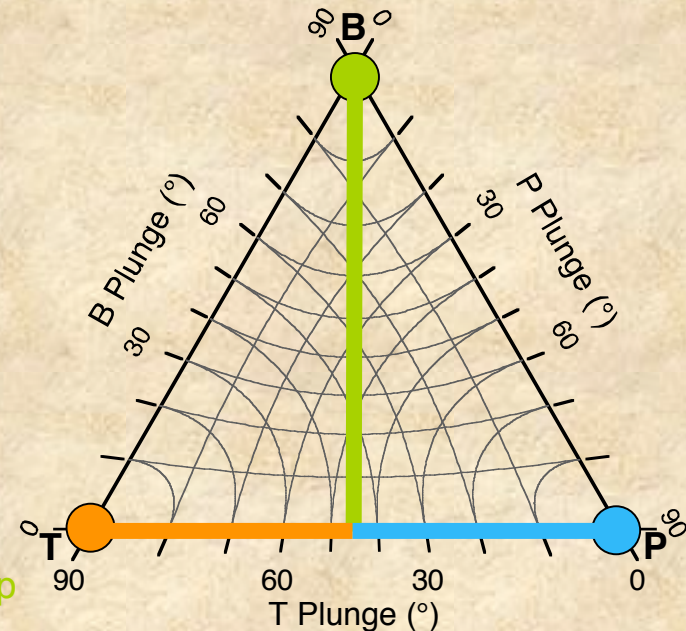
dip slip $\Leftrightarrow$ B plunge = 0°
 strike slip $\Leftrightarrow$ P plunge = T plunge

strike slip **does not require** steep B plunge

dip slip **does not require** steep P or T plunge

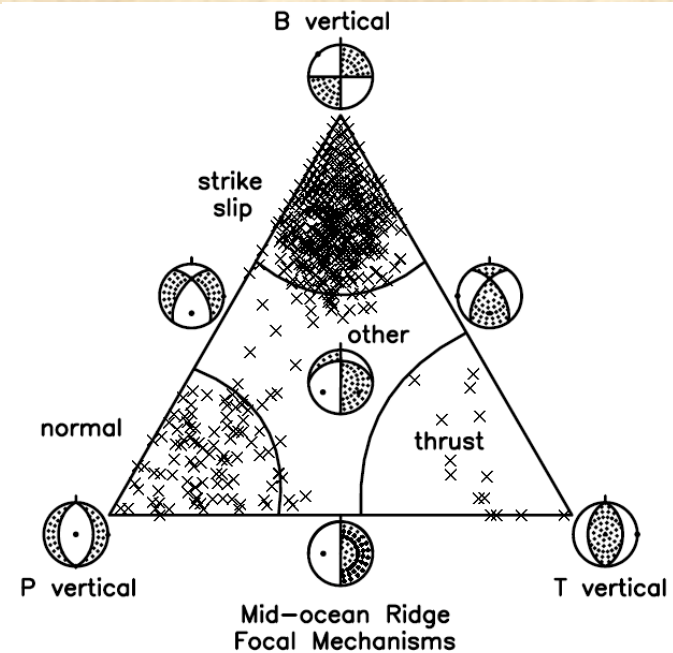
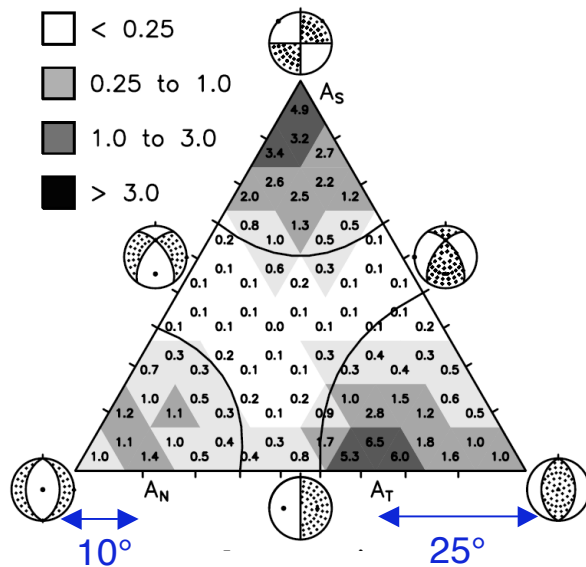
shallow B: best proxy for dip slip

steep B: not a good proxy for strike slip



Frohlich , GJI, 2001

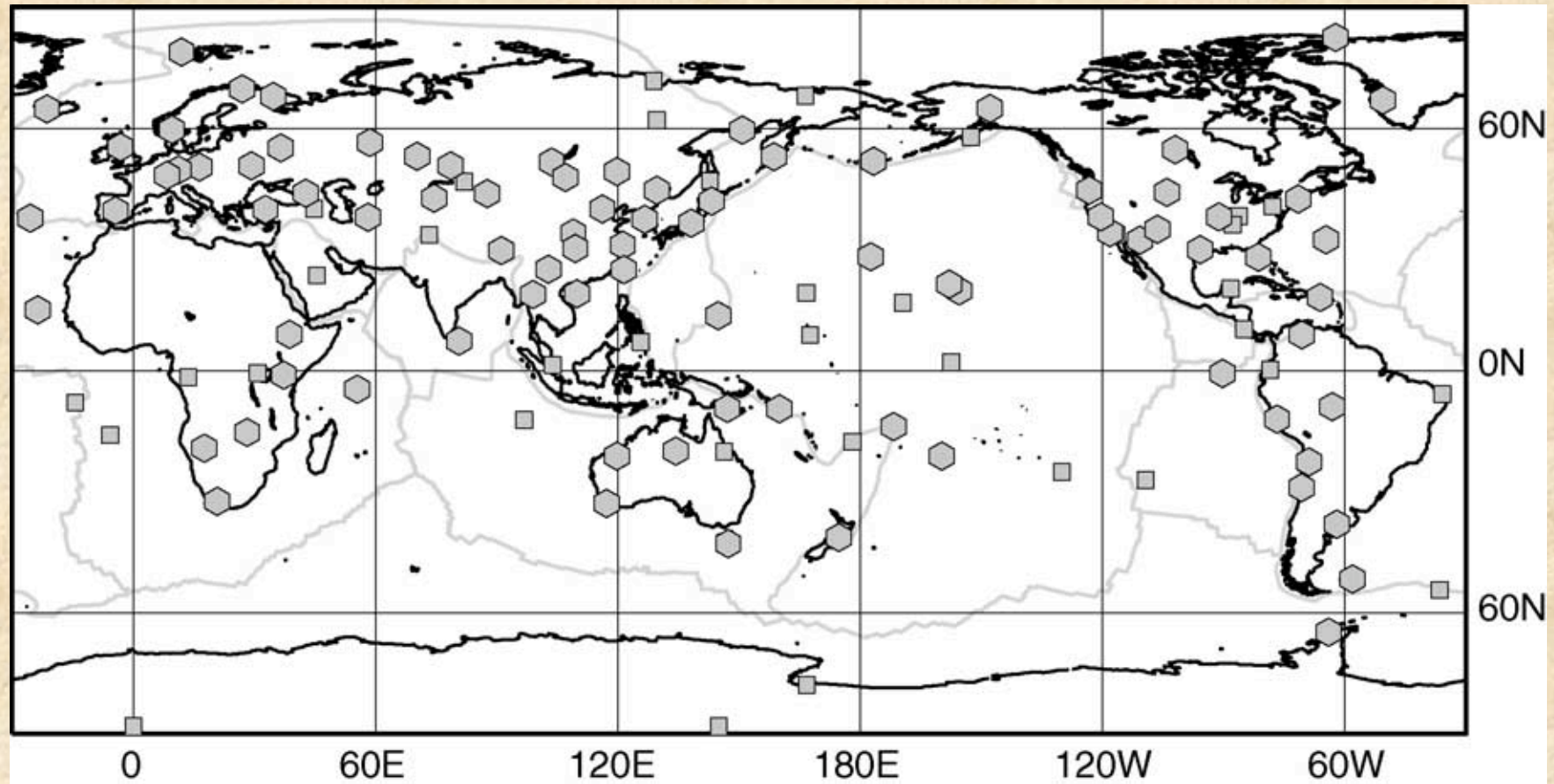
- CMT 1977-Oct 1999 16410
- Focal depth (centroid ?) ≤ 30 km 8687
- Reliability standards (Frohlich & Davis (1999)) 3625
 - $fclvd \leq 0.2$
 - $IIDMII/IIIMII \leq 15\%$
 - $nfree = 6$
- Near oceanic ridge earthquake 637



- **Global catalog of moment tensors**
 - Hosted at Lamont Doherty Earth Observatory: www.globalcmt.org
 - Ex Harvard CMT
 - Funded by the National Science Foundation since its inception
- **Method: Dziewonski et al. (1981)**
 - Digital stations => Filtered $T > 45s$ + Sampled 1 Hz
 - Coupled inversion for moment tensor and hypocenter
- **Dziewonski et al. (1983):**
 - Centroid location different from PDE hypocenter
 - $\Delta h \sim 50$ km, $\Delta z \sim 12$ km
 - $Z < 15$ km => $Z = 15$ km (PDE $Z = 10$ km or 33 km)
 - $M_w \geq 5.2$ $M_0 \geq 10^{17}$ Nm
- **History**
 - systematic since 1981 (Dziewonski & Woodhouse, 1983)
 - 2003 report: Ekström et al., PEPI, 2005
 - backtrack to 1977: 5 digital stations (Dziewonski et al., 1987)
 - 1976 for $M_w \geq 6$ (Ekström, & Nettles, 1997)
 - Deep earthquakes 1907-1976 (Huang et al., 1994, 1997, 1998)
- **Database used**
 - 1976-2004 for analysis
 - Use also 2003 report: Ekström et al., PEPI, 2005

GCMT

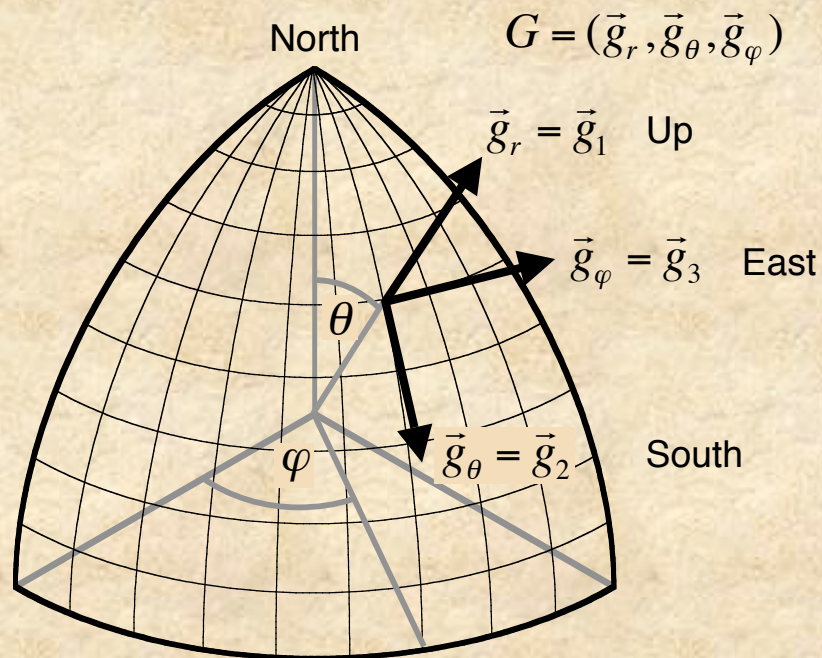
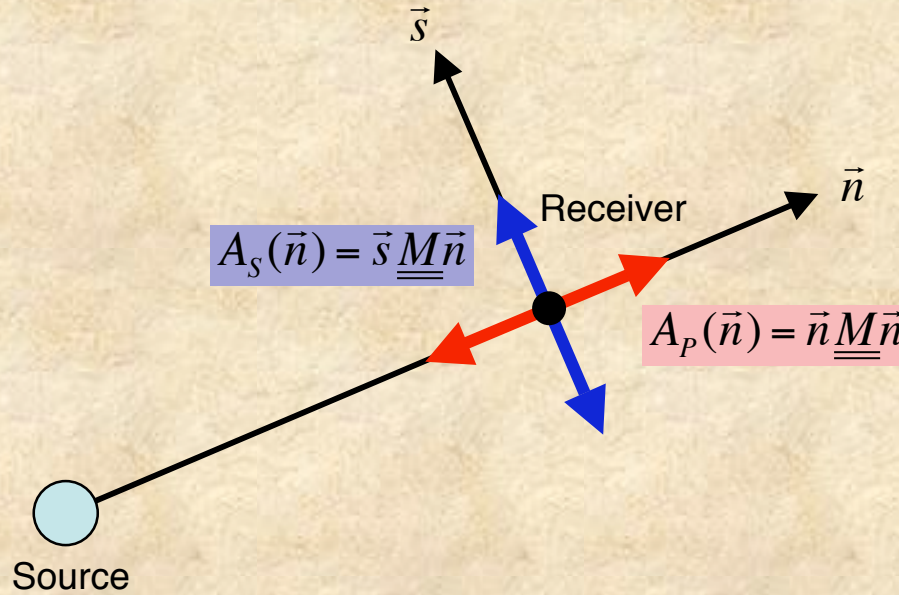
Digital seismic network



Stations (octagon > 200 events)

GCMT

Moment Tensor $\underline{\underline{M}}$



$$M^G = \begin{bmatrix} m_{rr} & m_{rs} & m_{re} \\ m_{rs} & m_{ss} & m_{se} \\ m_{re} & m_{se} & m_{ee} \end{bmatrix}$$

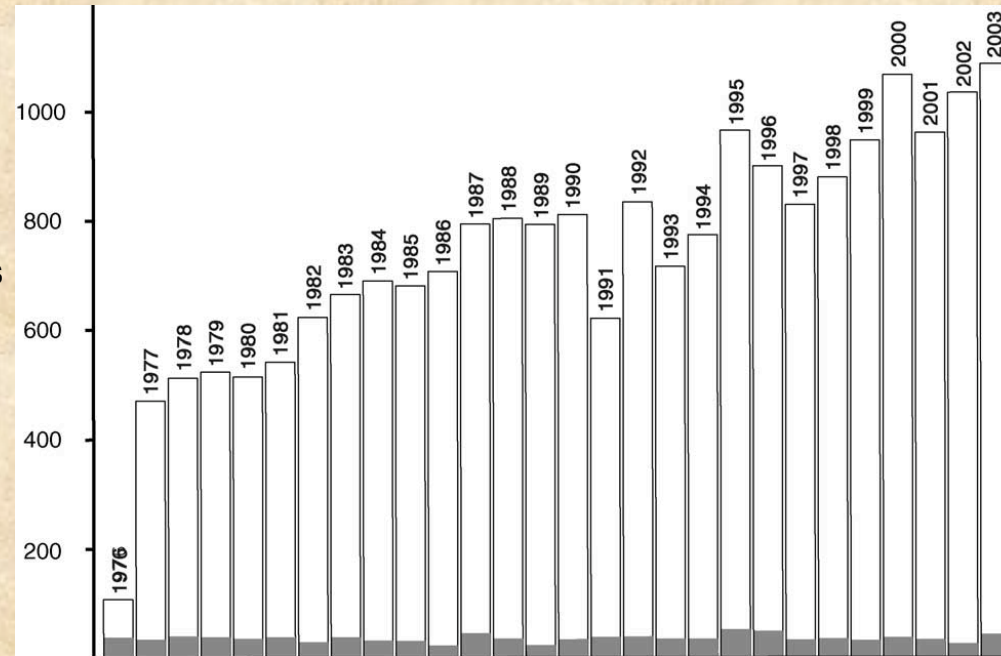
$$M_0 = \frac{1}{\sqrt{2}} \sqrt{\sum_{ij} m_{ij}^2}$$

$$= \mu \Delta \bar{u} S \text{ (dble cple)}$$

GCMT

Catalog

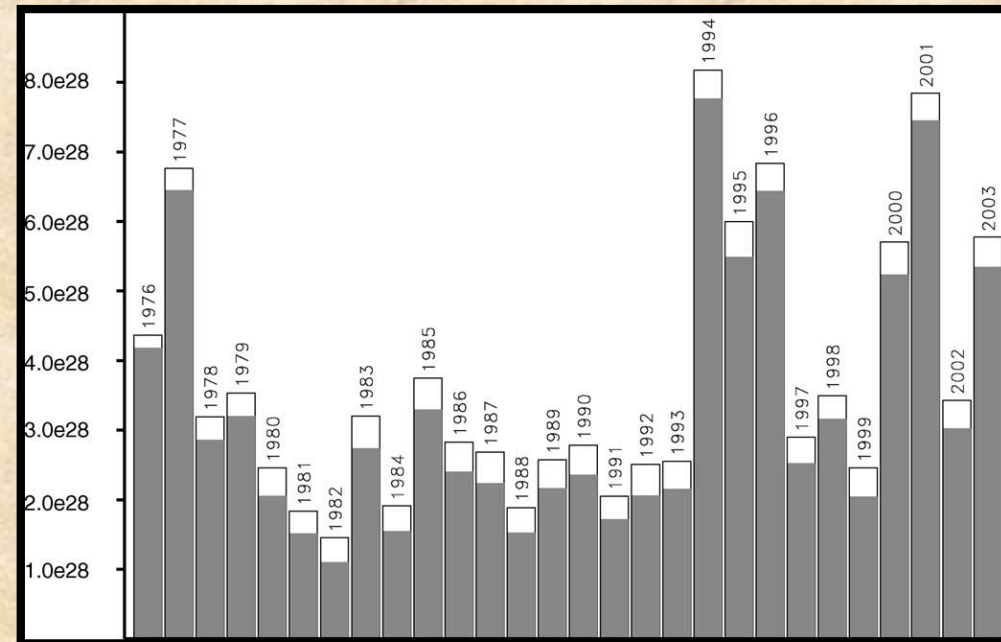
Number of events



Grey $\Rightarrow$ $M_w \geq 6.5$

2003: 43 events

Mo (dyne.cm)



Ekstrom et al, PEPI , 2005

GCMT

Relate M_0 to E and M_w

Kanamori, JGR, 1977

E = released strain energy

$$E = \frac{1}{2} \Delta \bar{\sigma} \Delta \bar{u} S$$

Kostrov, 1974

M_0 = seismic moment

$$M_0 = \mu \Delta \bar{u} S$$

Aki, 1966

$$E = \frac{\Delta \bar{\sigma}}{2\mu} M_0$$

$$E \approx M_0 / 20\,000$$

$$\mu \approx 200 - 300 \text{ kb}$$

$$\Delta \bar{\sigma} \approx 30 - 60 \text{ b}$$

$$\frac{\Delta \bar{\sigma}}{2\mu} \approx \frac{1}{20\,000}$$

M_w = moment magnitude

$$\log_{10} (E) = 1.5 M_s + 4.8$$

E (Joules)

Gutenberg Richter, 1956

$$\log_{10} (E) = 1.5 M_w + 4.8$$

E (Joules)

$$\log_{10} (E) = \log_{10} (M_0) - 4.3$$

$$M_w = 2/3 \log_{10} (M_0) - 6.1$$

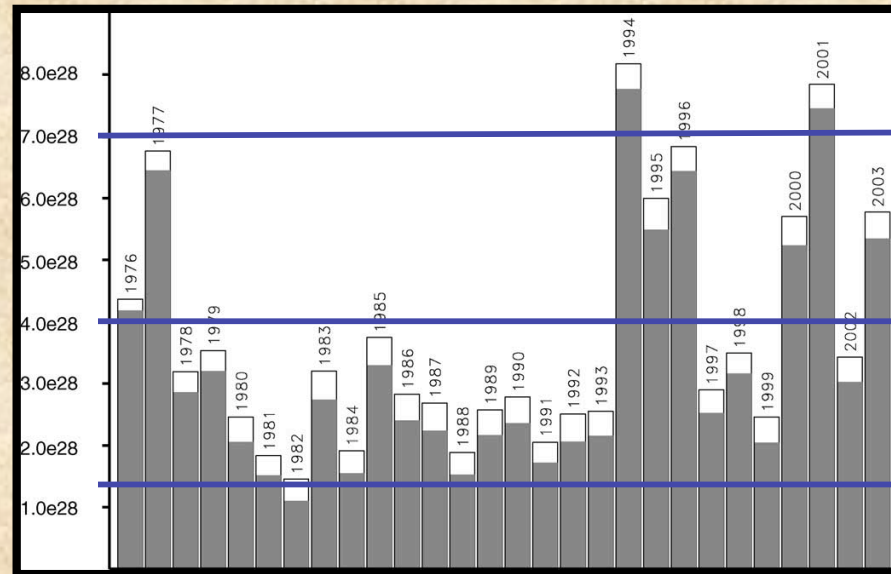
M_0 (N m)

GCMT

Relate M_0 to E and M_w

erg = dyne cm
Joule = Newton m
1 erg = 10^{-7} Joule

M_0 (dyne.cm)



Ekstrom et al, PEPI , 2005

— $M_0 = 4 \times 10^{29}$ $M_w = 9$

— $5 \times (M_w = 8)$

$\sum M_0 \approx 4 \times 10^{28}$ dyne cm = 4×10^{21} N m

$\sum E \approx \sum M_0 / 20000 = 2 \times 10^{17}$ Joules

≈ 8 nuclear power plants (2003: 43 events $M_w \geq 6.5$)

— $M_0 = 1.4 \times 10^{28}$ $M_w = 8$

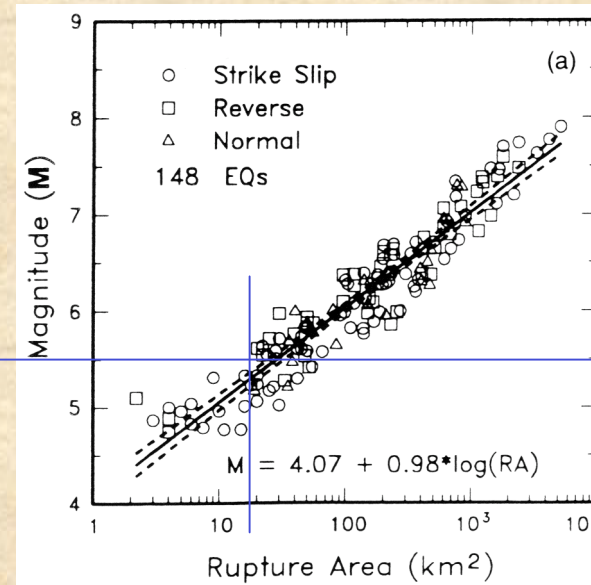
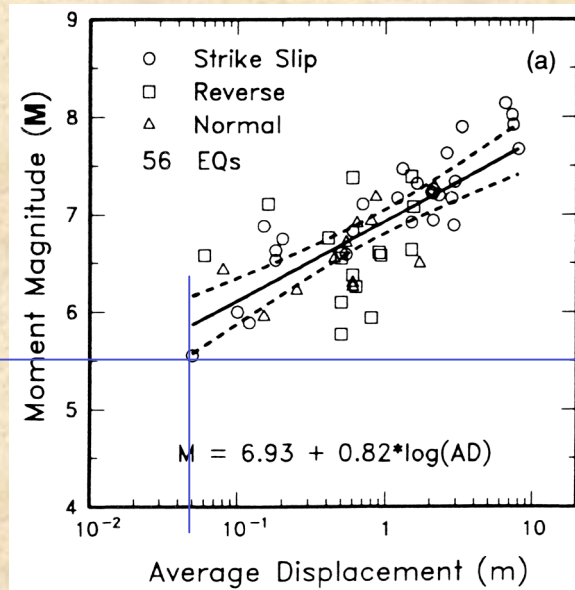
800 MW nuclear power plant one year production:

1 year = 3.15×10^7 s

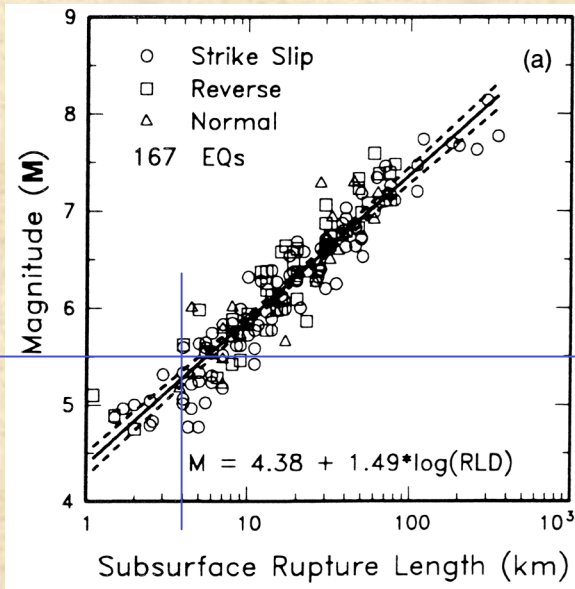
$E \approx 8 \times 10^8 \times 3.15 \times 10^7 = 2.5 \times 10^{16}$ J

GCMT

Threshold



Wells & Coppersmith, BSSA, 1994



GCMT catalog is complete for
 $M_w \geq 5.5$

$\Delta u \geq 5 \text{ cm}$
 $L \geq 4 \text{ km}$
 $A \geq 20 \text{ km}^2$

Selection

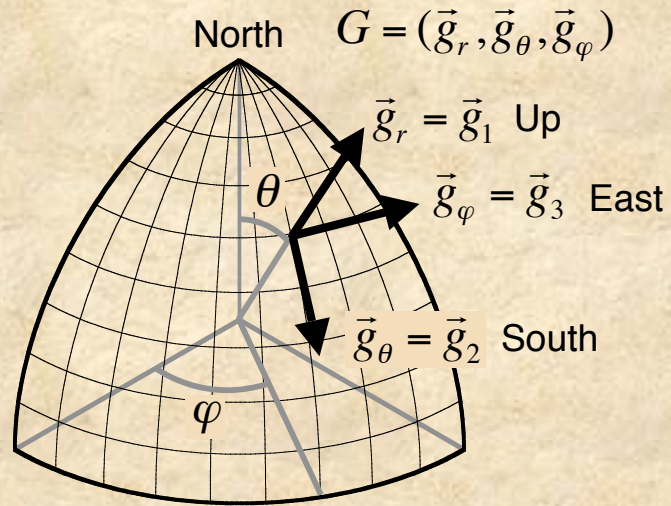
Quality selection

Frohlich & Davis, JGR, 1999

- Full or partial inversion ? (nfree)
- Error range (Erel)
- Double couple or not ? (fclvd)

Selection

Full or partial inversion ? (nfree)

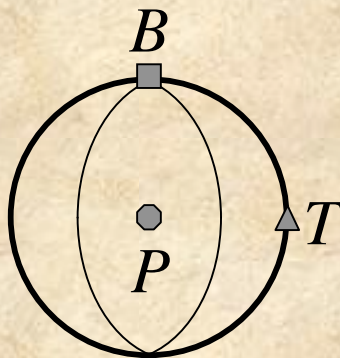


$$M^G = \begin{bmatrix} m_{rr} & m_{rs} & m_{re} \\ m_{rs} & m_{ss} & m_{se} \\ m_{re} & m_{se} & m_{ee} \end{bmatrix}$$

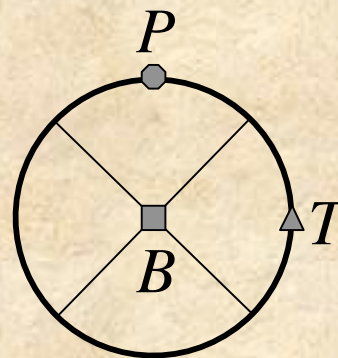
Shallow earthquakes (depth < 30 km)
 m_{rs} & m_{re} poorly constrained $\Rightarrow$ set to 0

$$M^G = \begin{bmatrix} m_{rr} & 0 & 0 \\ 0 & m_{ss} & m_{se} \\ 0 & m_{se} & m_{ee} \end{bmatrix}$$

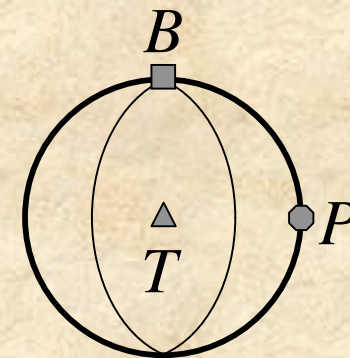
$\Rightarrow$ 1 vertical, 2 horizontal principal axes



Pure normal
 Rake = -90°
 Dip = 45°



Pure strike-slip
 Rake = 0° or 180°
 Dip = 90°



Pure reverse
 Rake = $+90^\circ$
 Dip = 45°

Selection

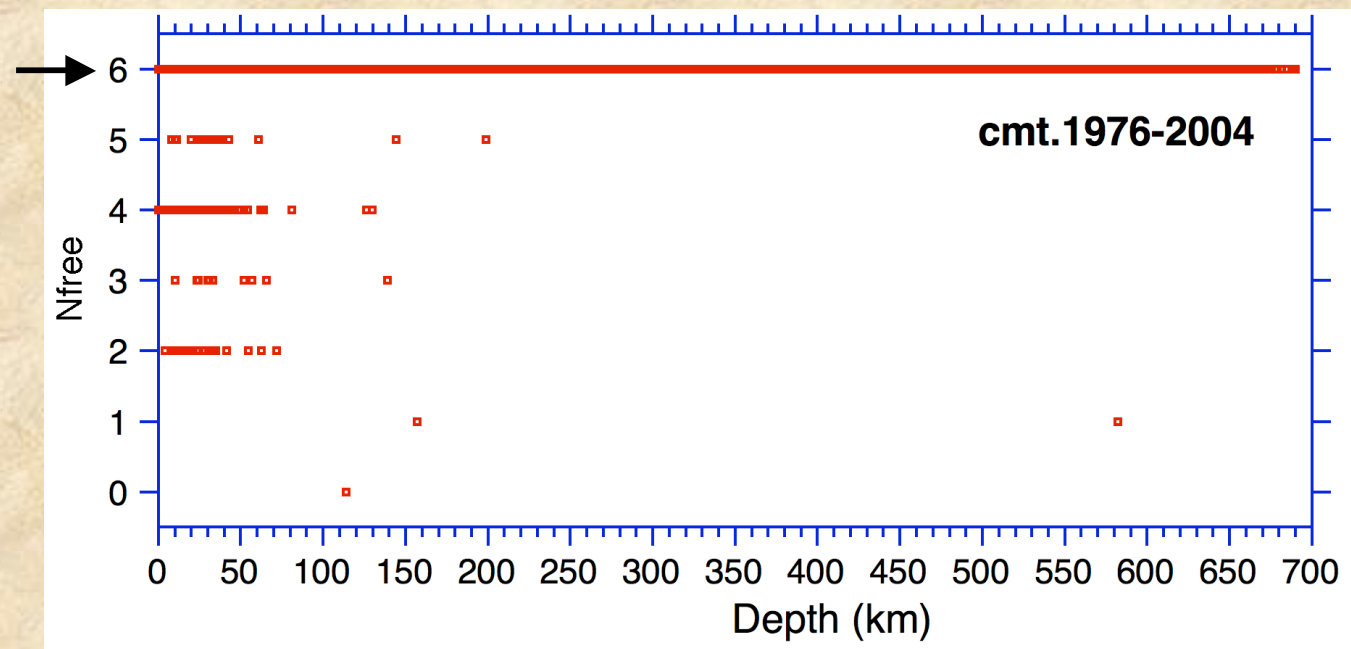
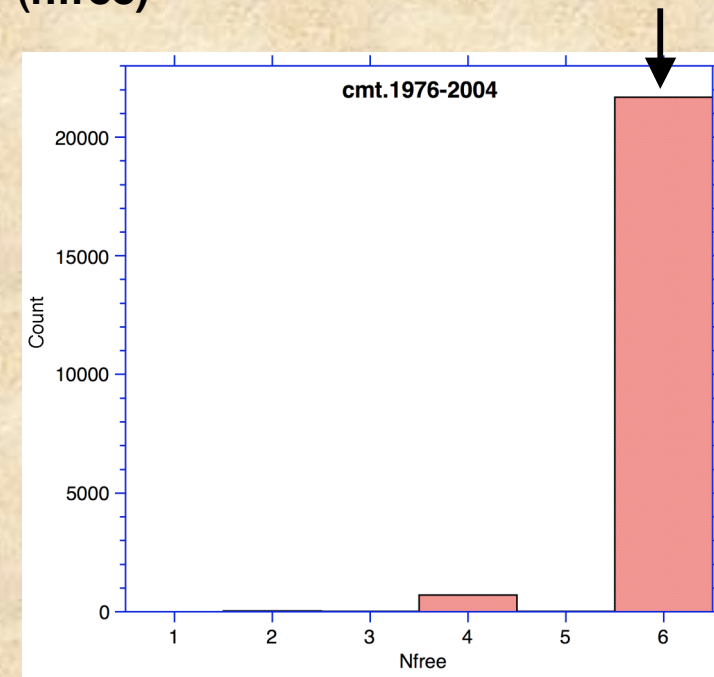
Full or partial inversion ? (nfree)

Define

nfree = number of components really inverted for

Retain only

nfree = 6 Frohlich & Davis, JGR, 1999



Selection

Error range (Erel)

Define relative error:

$$M^G = \begin{bmatrix} m_{11} & m_{12} & m_{13} \\ m_{12} & m_{22} & m_{23} \\ m_{13} & m_{32} & m_{33} \end{bmatrix}$$

$$DM^G = \begin{bmatrix} dm_{11} & dm_{12} & dm_{13} \\ dm_{12} & dm_{22} & dm_{23} \\ dm_{13} & dm_{32} & dm_{33} \end{bmatrix}$$

$$\|M\| = \sqrt{\sum_{i=1}^3 \sum_{j=1}^3 m_{ij}^2}$$

$$\|DM\| = \sqrt{\sum_{i=1}^3 \sum_{j=1}^3 dm_{ij}^2}$$

$$E_{rel} = \frac{\|DM\|}{\|M\|}$$

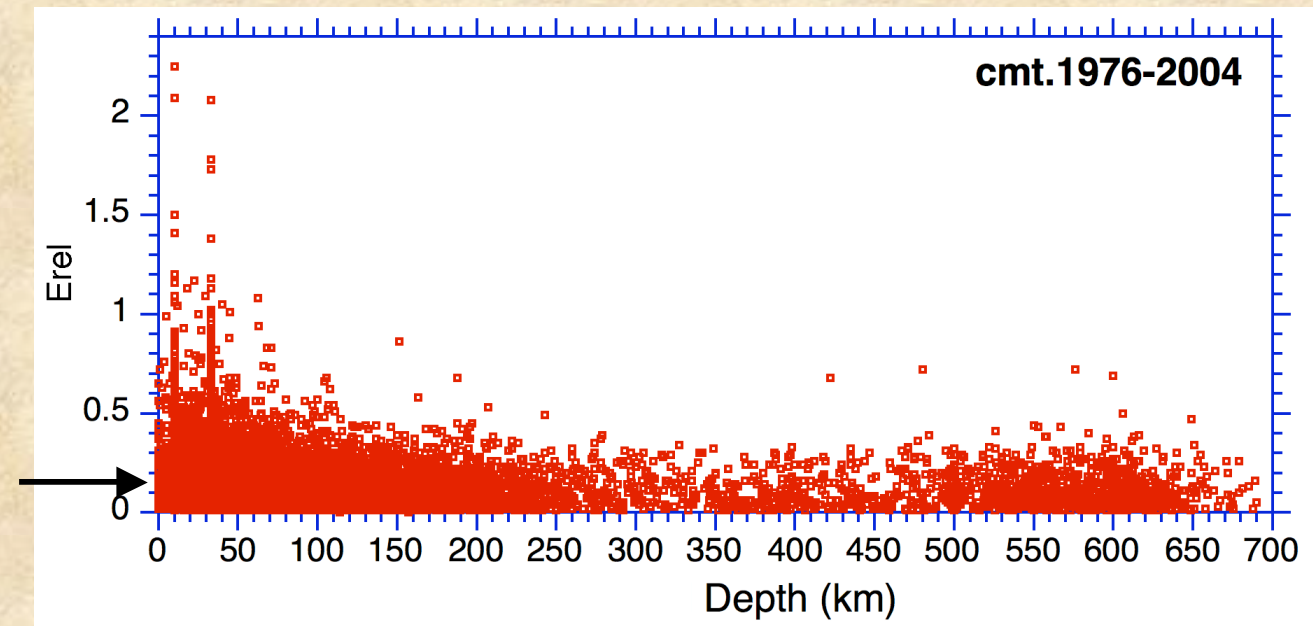
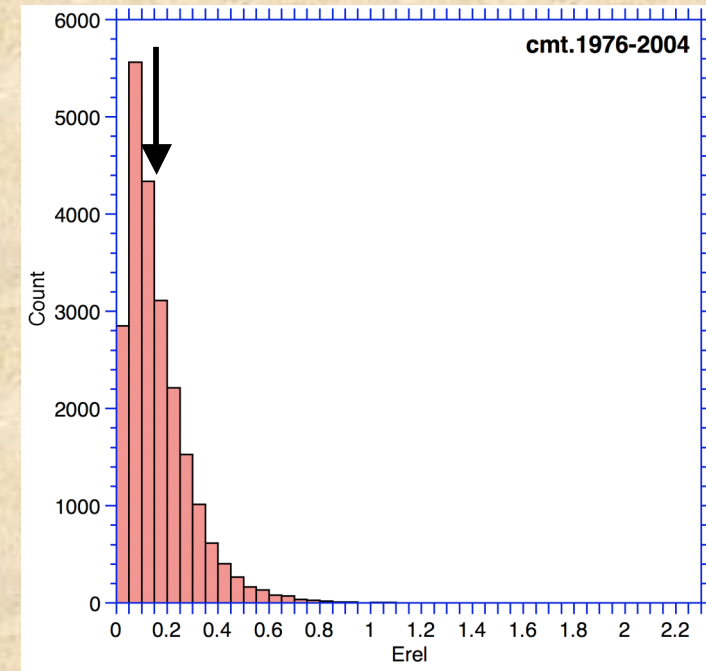
$$E_{rel} \leq 15\%$$

Frohlich & Davis, JGR, 1999

Selection

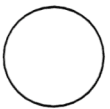
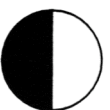
Error range (Erel)

$$E_{rel} \leq 15\% \quad \text{Frohlich \& Davis, JGR, 1999}$$



Selection

Double couple or not ? (fclvd)

Moment tensor	Beachball	Moment tensor	Beachball	
$\frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		$-\frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		Explosion Implosion
$-\frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$		$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$		
$\frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}$		$\frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix}$		Double Couple
$\frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		$\frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		
$\frac{1}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		$\frac{1}{\sqrt{6}} \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$		CLVD
$\frac{1}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$		$-\frac{1}{\sqrt{6}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$		

Selection

Double couple or not ? (fclvd)

Eigenvectors frame $A = (\vec{a}_1, \vec{a}_2, \vec{a}_3)$

$$M^A = \begin{bmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{bmatrix}$$

$$|m_1| \geq |m_2| \gg |m_3|$$

$$m_1 + m_2 + m_3 = 0$$

Decomposition into

- Double couple
- CLVD = Compensated Linear Vector Dipole

$$m_B = m_3$$

2 cases:

$$m_1 \geq 0 :$$

$$m_P = m_2$$

$$m_T = m_1$$

$$A = (T, P, B)$$

$$M^A = \begin{bmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{bmatrix} = m_1(1-2F) \begin{bmatrix} +1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + m_1 F \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

Double couple CLVD

$$F = -\frac{m_3}{m_1}$$

$F = 0 \Rightarrow$ Pure double couple

$F = 0.5 \Rightarrow$ Pure CLVD

$$m_1 \leq 0 :$$

$$m_P = m_1$$

$$m_T = m_2$$

$$A = (P, T, B)$$

$$f_{clvd} = -\frac{m_B}{\max(|m_P|, |m_T|)}$$

$f_{clvd} = 0$ Pure double couple

$|f_{clvd}| = 0.5$ Pure CLVD

$|f_{clvd}| \leq 0.2$ Quality threshold

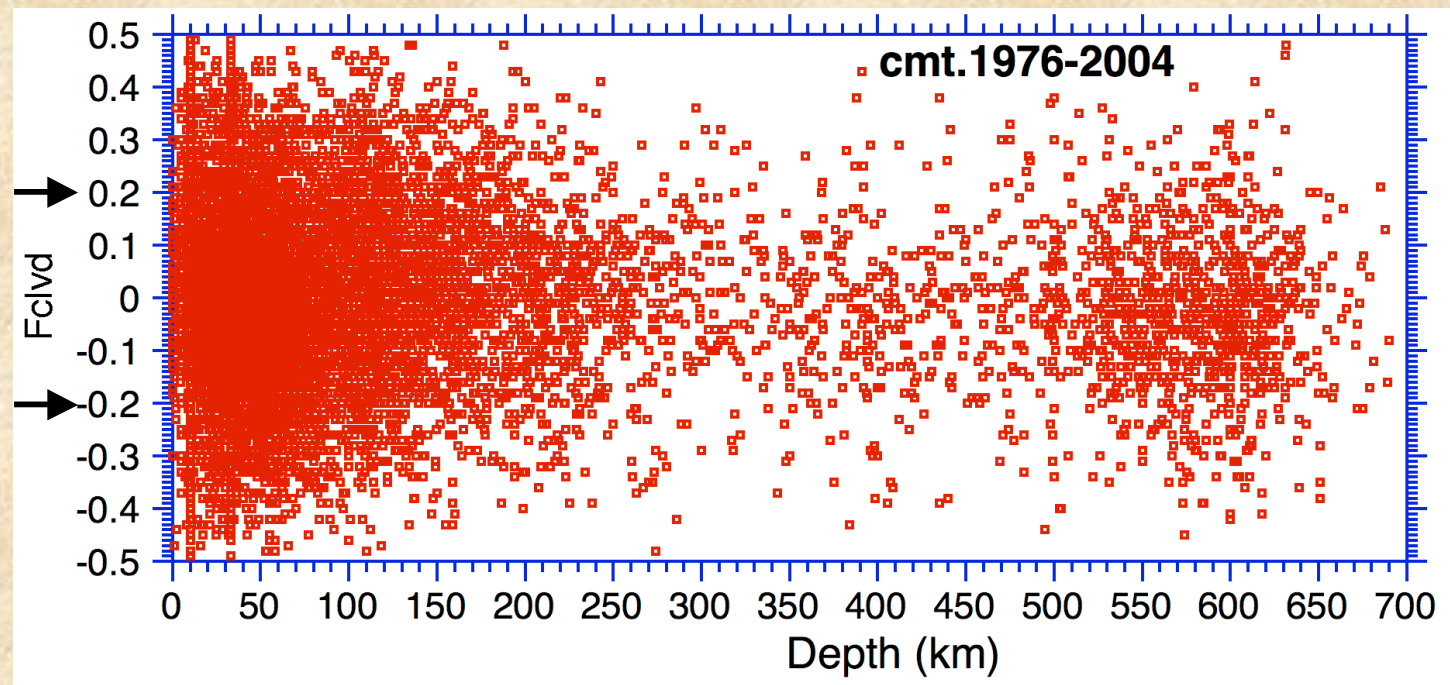
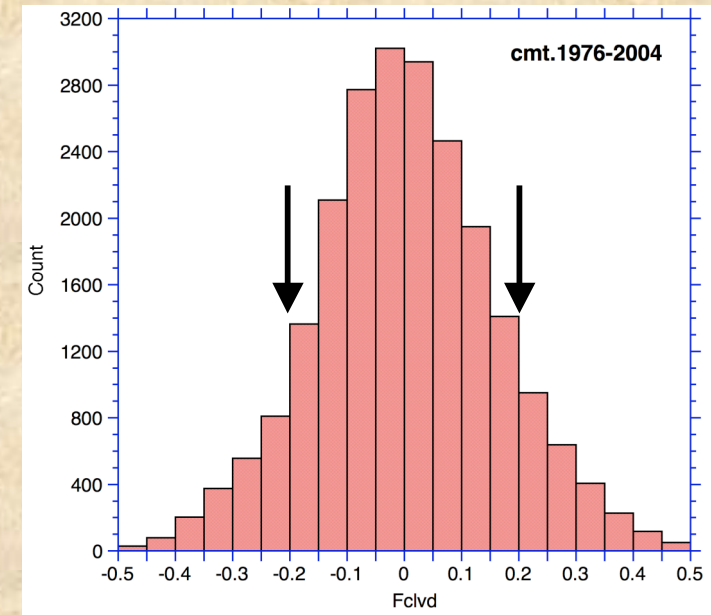
Frohlich & Davis, JGR, 1999

Selection

Double couple or not ? (fclvd)

$$f_{clvd} = -\frac{m_B}{\max(|m_P|, |m_T|)}$$

$$|f_{clvd}| \leq 0.2$$



Selection

Summary

Parameter

Quality threshold

nfree = inverted components

nfree = 6

$$E_{rel} = \frac{\|DM\|}{\|M\|}$$

$$E_{rel} \leq 15\%$$

$$f_{clvd} = -\frac{m_B}{\max(|m_P|, |m_T|)}$$

$$|f_{clvd}| \leq 0.2$$

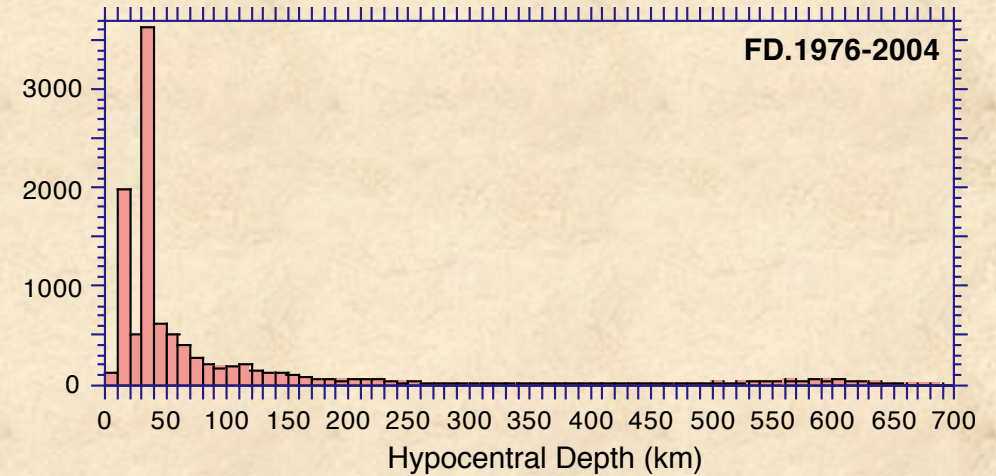
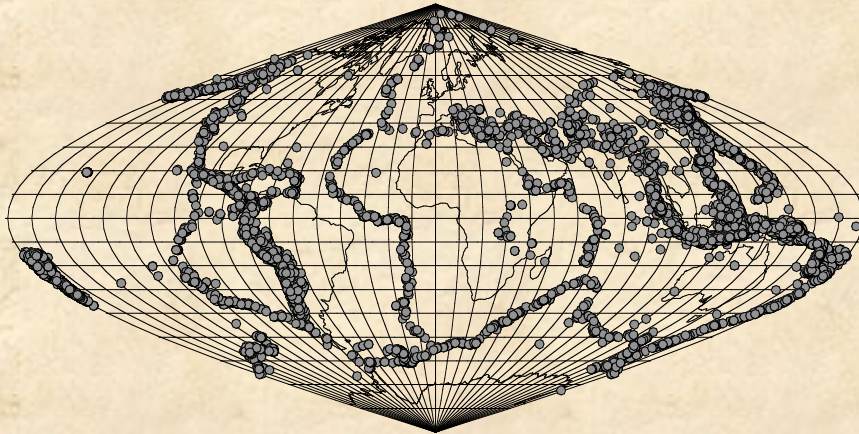
= > Angular uncertainties: 5-10°

Frohlich & Davis, JGR, 1999

Results

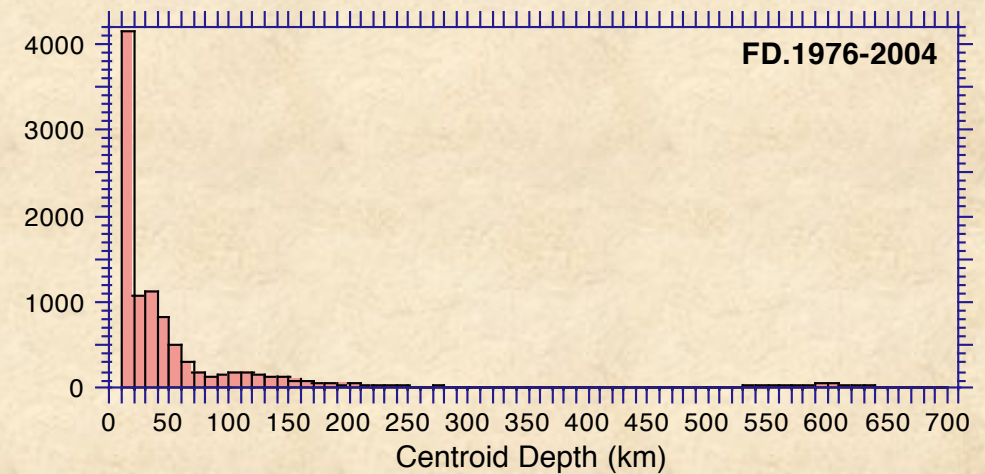
FD 0-700 km 1976-2004

N = 10709



Hypocenter depth (km)	CMT	FD (selection)	
[0,30]	6355	2685	42%
] 30,40]	8018	3619	45%
] 40,300]	6798	3609	53%
] 300,700]	1306	796	61%
[0,700]	22477	10709	48%

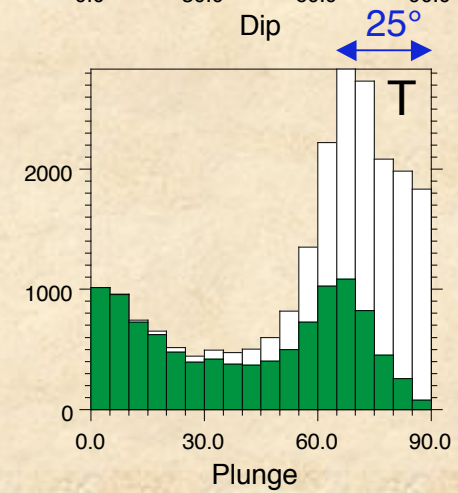
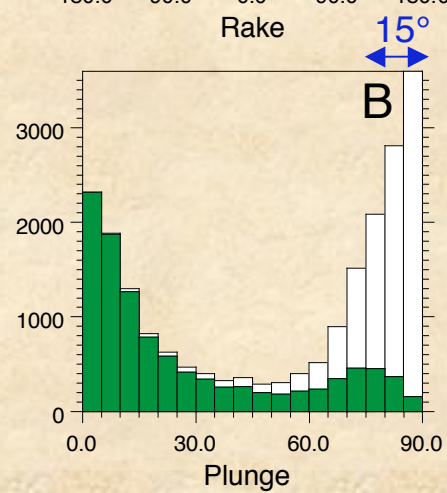
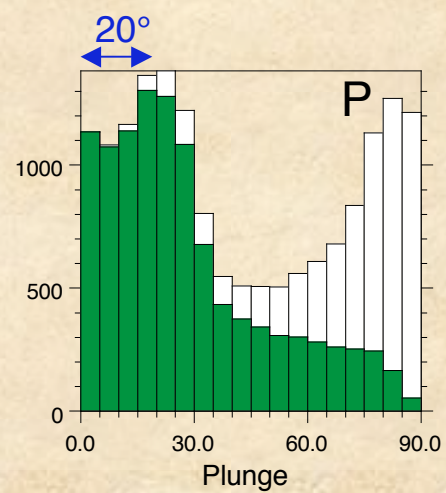
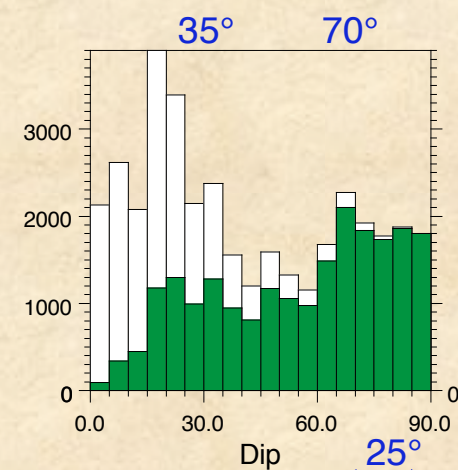
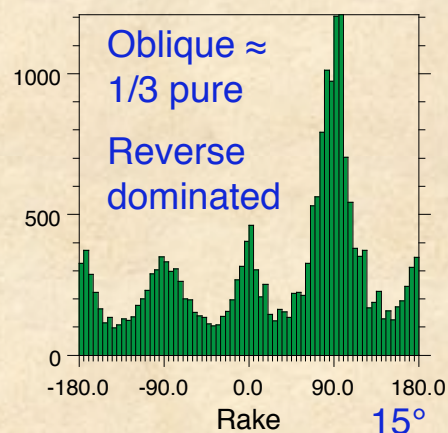
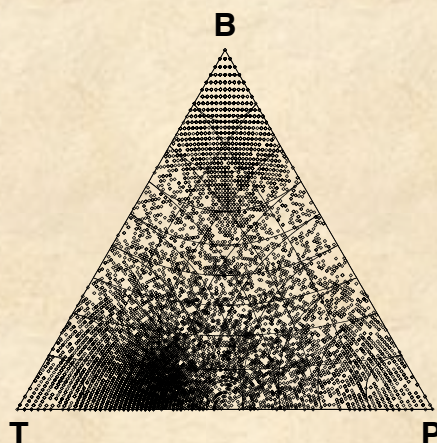
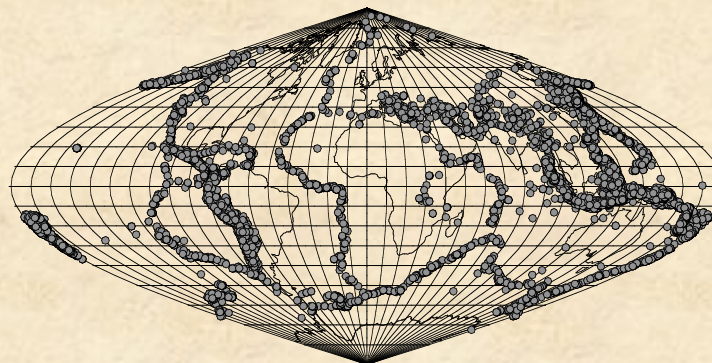
1976-2004



Results

FD 0-700 km 1976-2004

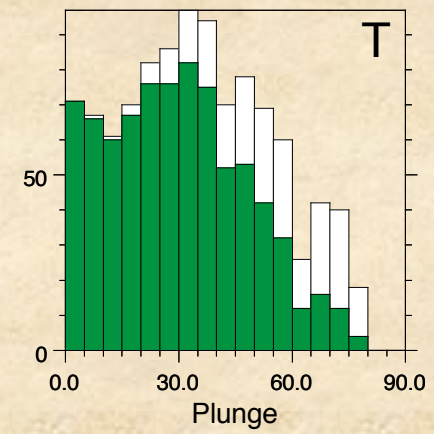
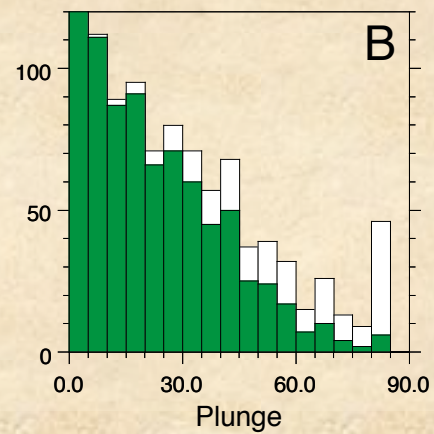
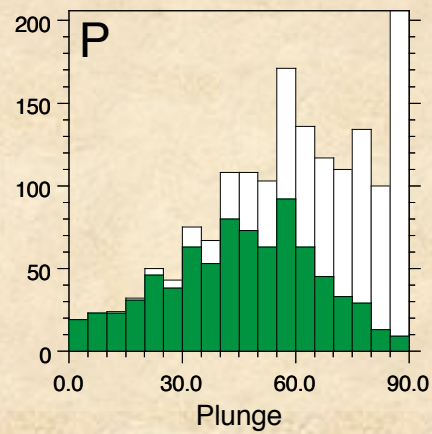
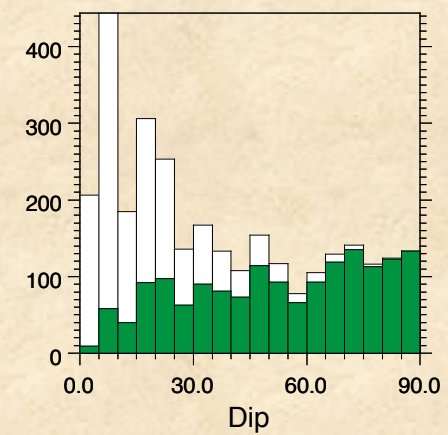
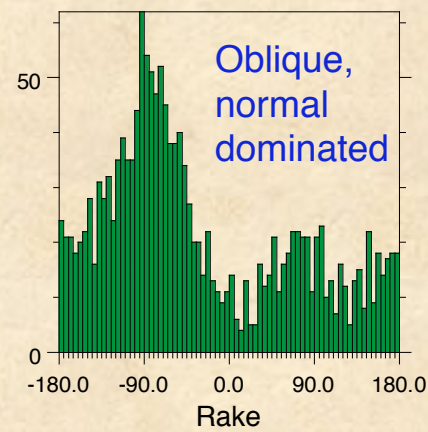
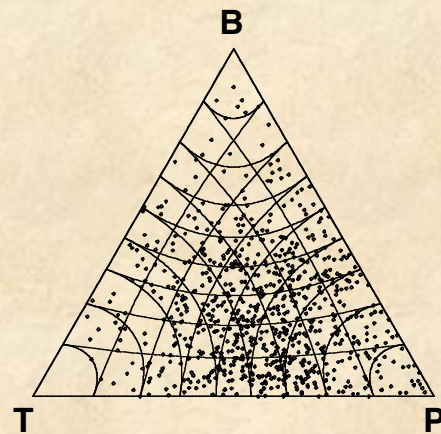
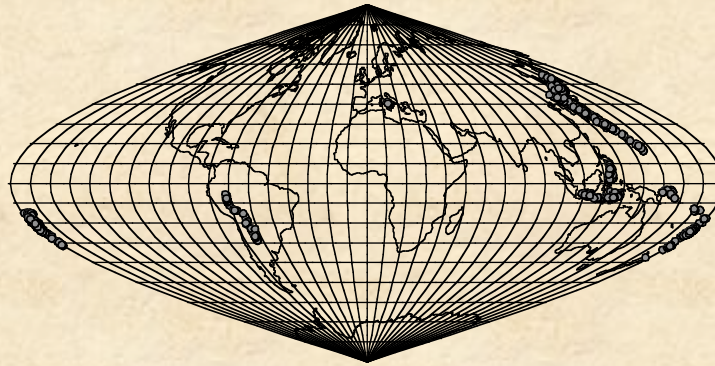
N = 10709



Results

FD 300-700 km

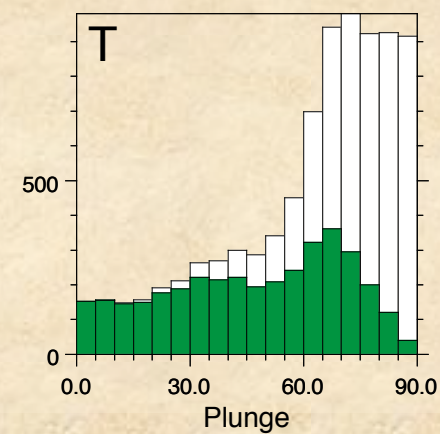
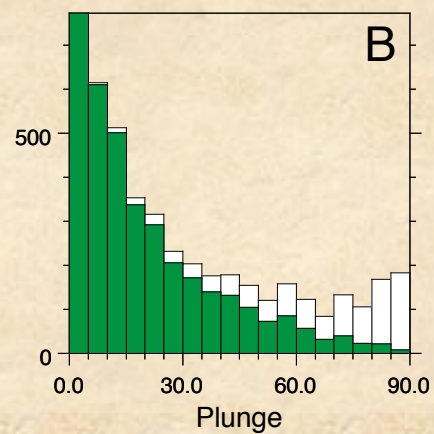
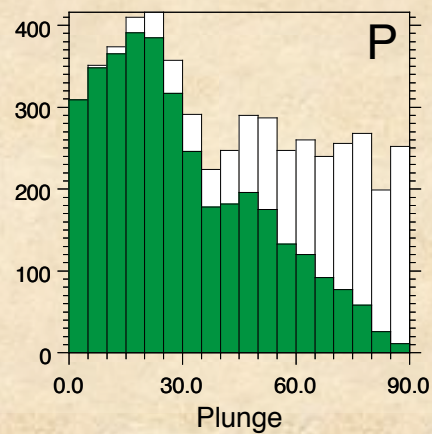
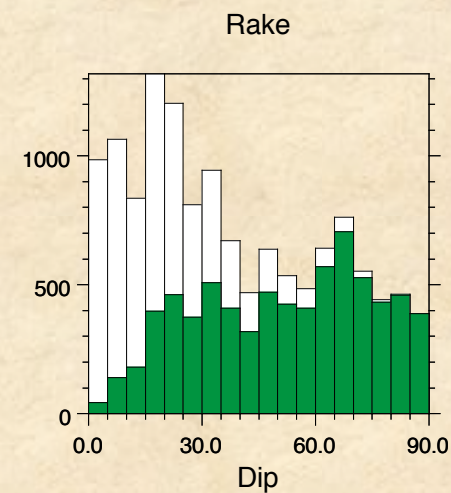
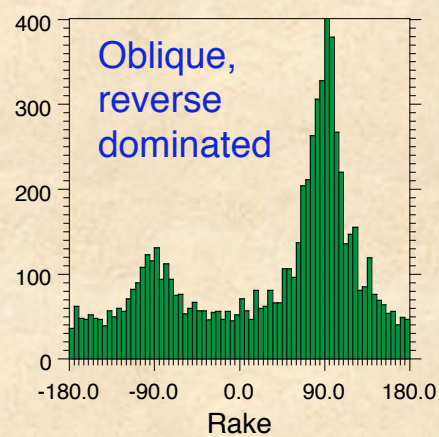
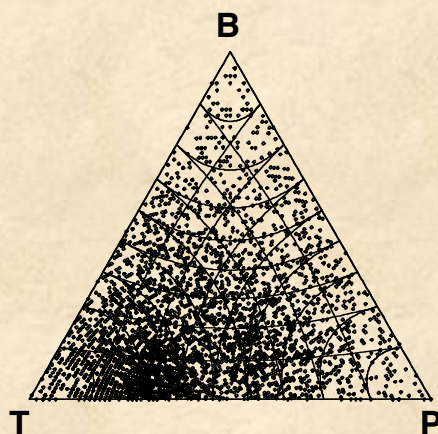
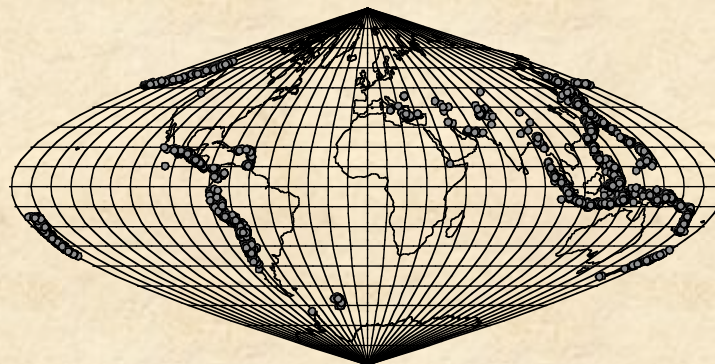
N = 796



Results

FD 40-300 km

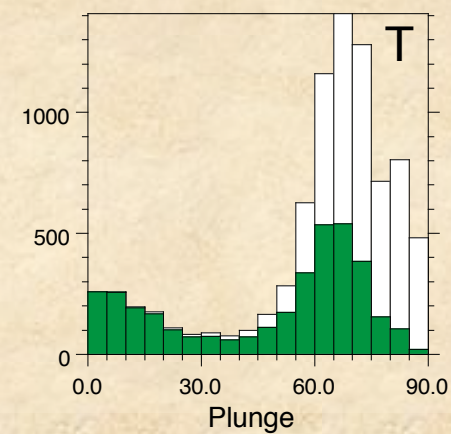
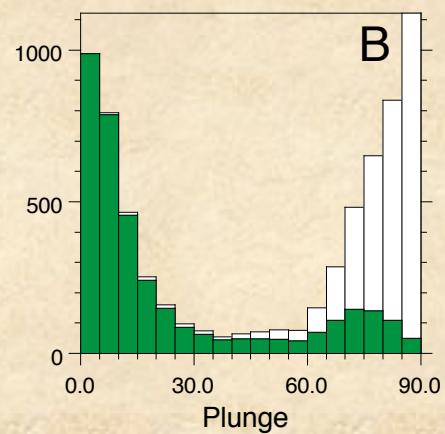
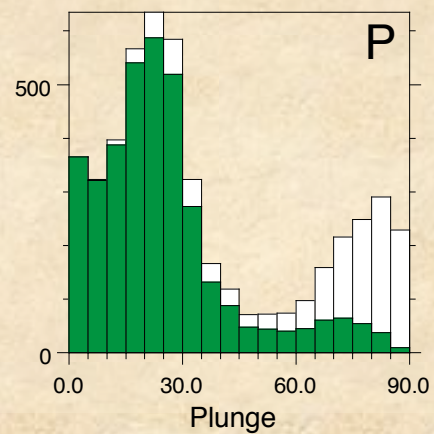
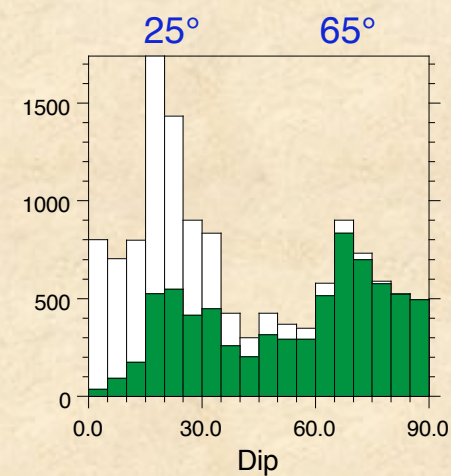
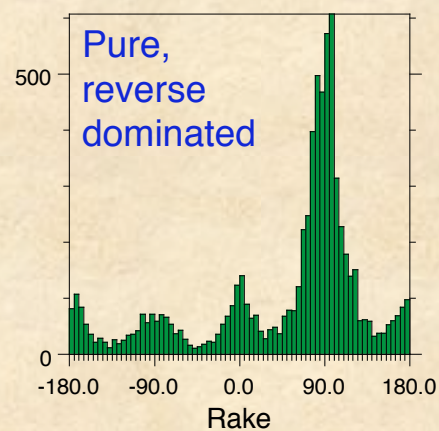
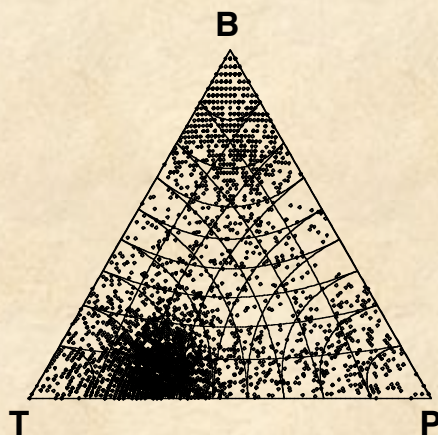
N = 3609



Results

FD 30-40 km

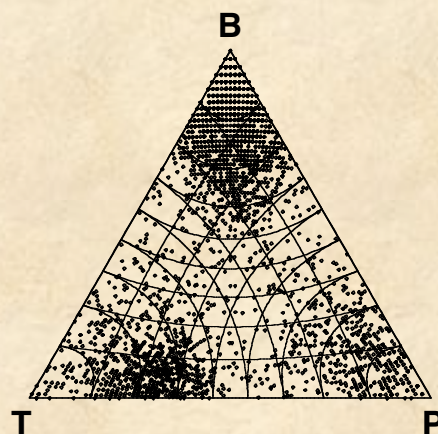
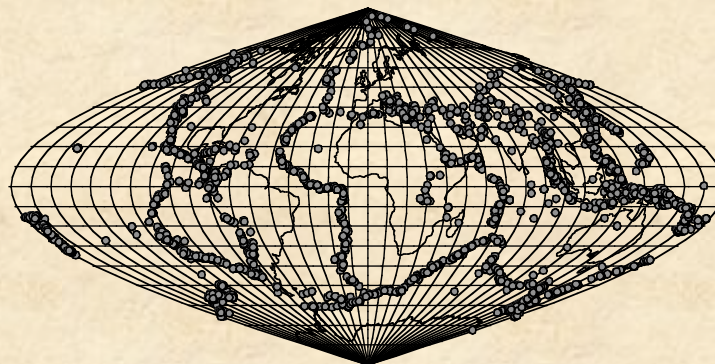
N = 3619



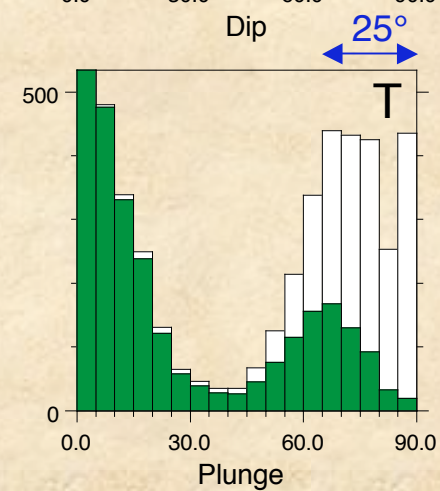
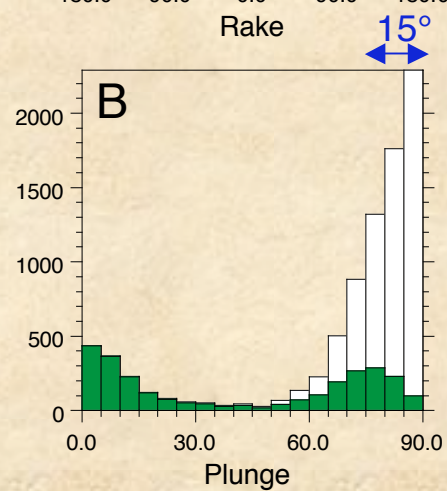
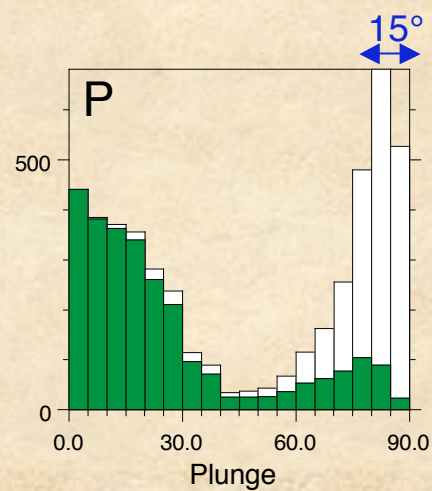
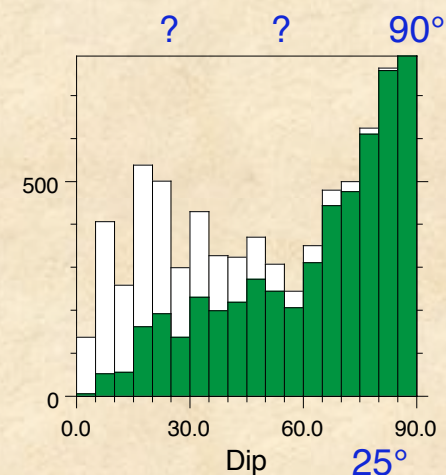
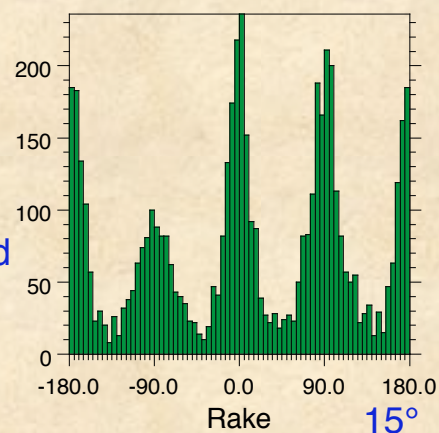
Results

FD 0-30 km

N = 2685



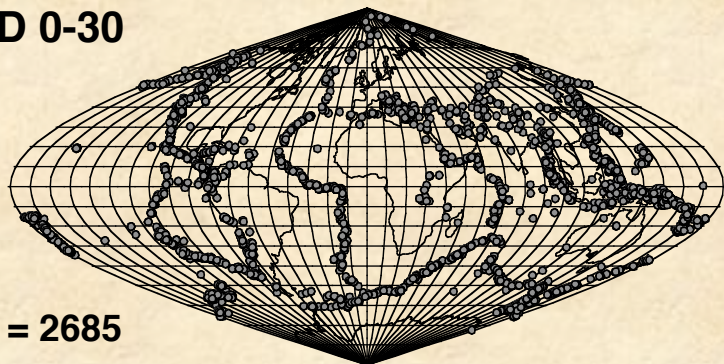
Pure,
reverse +
strike-slip
dominated



Results

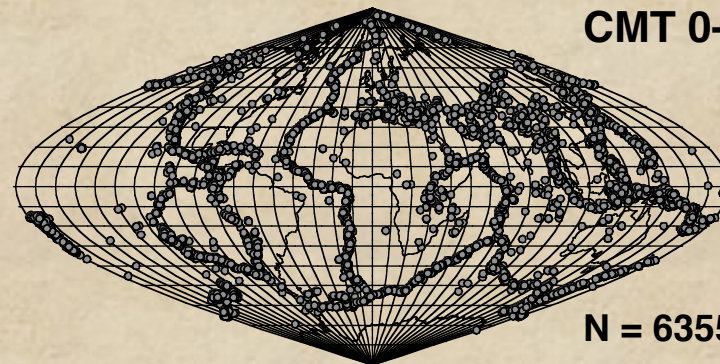
FD versus CMT 0-30 km

FD 0-30

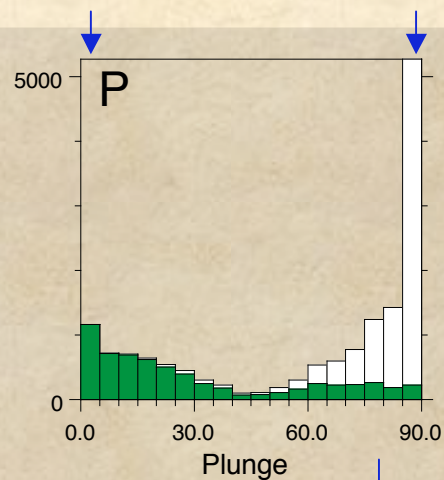


N = 2685

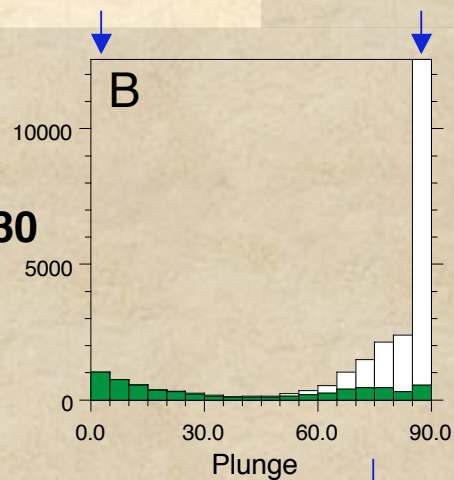
CMT 0-30



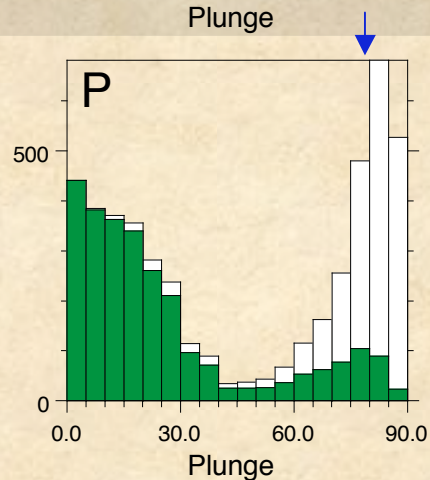
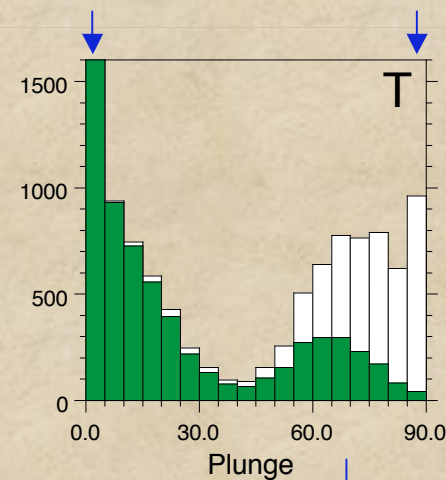
N = 6355



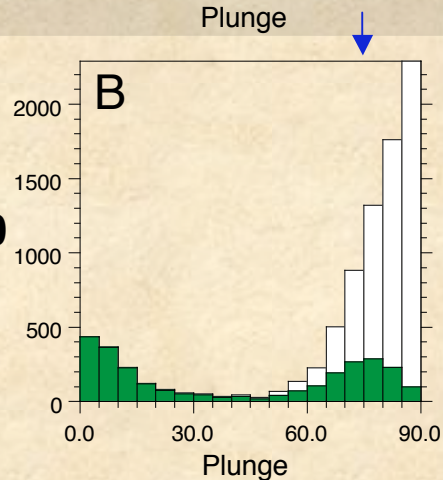
CMT 0-30



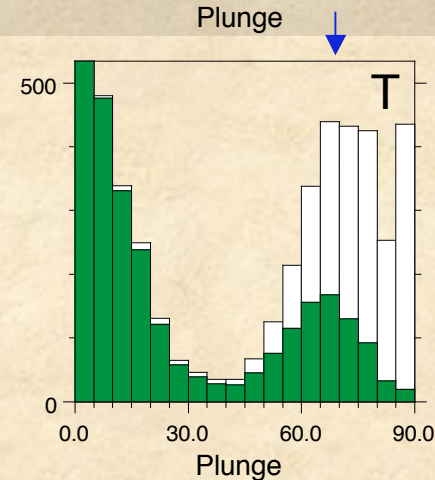
N = 6355



FD 0-30

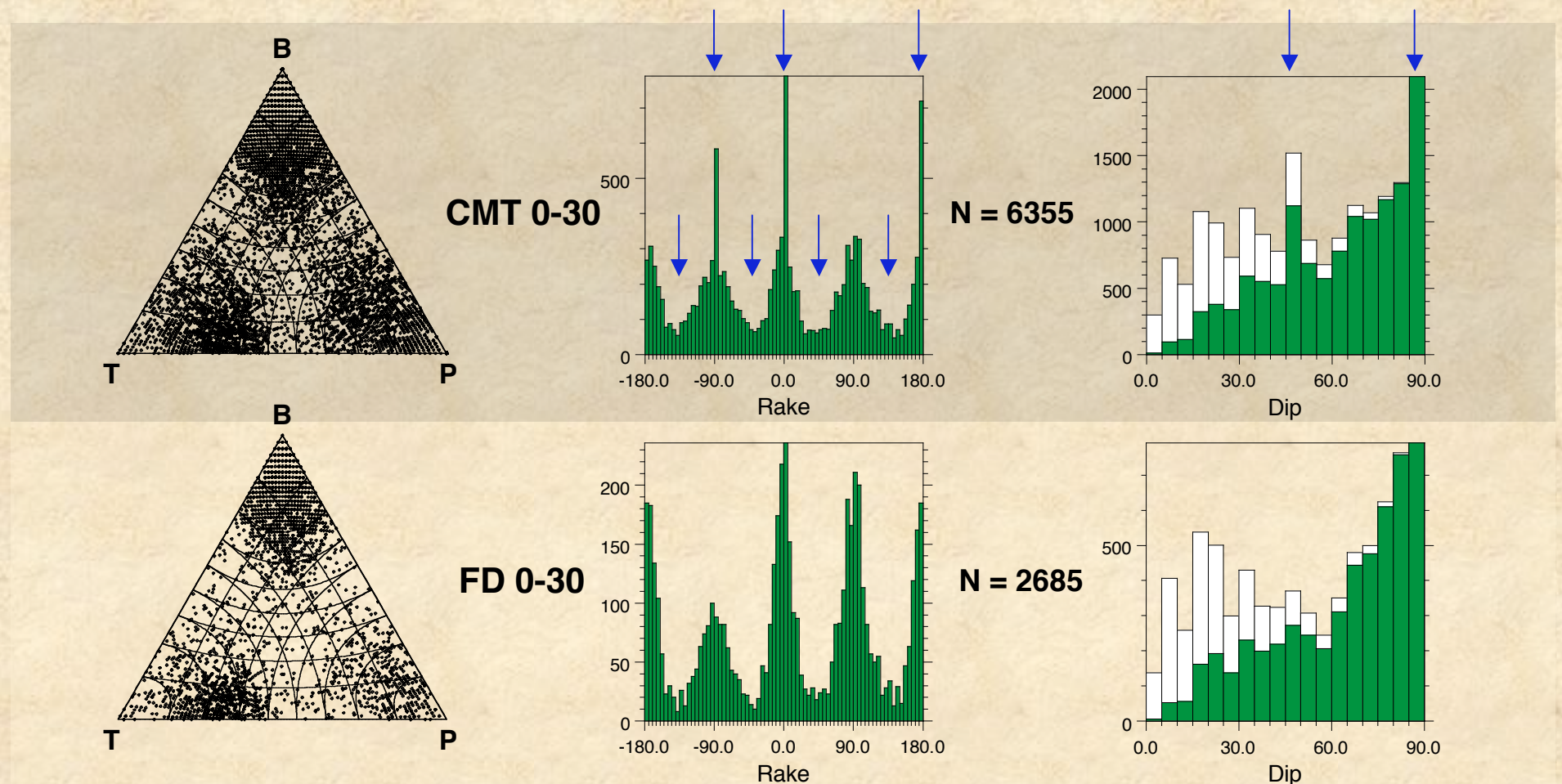


N = 2685



Results

FD versus CMT 0-30 km



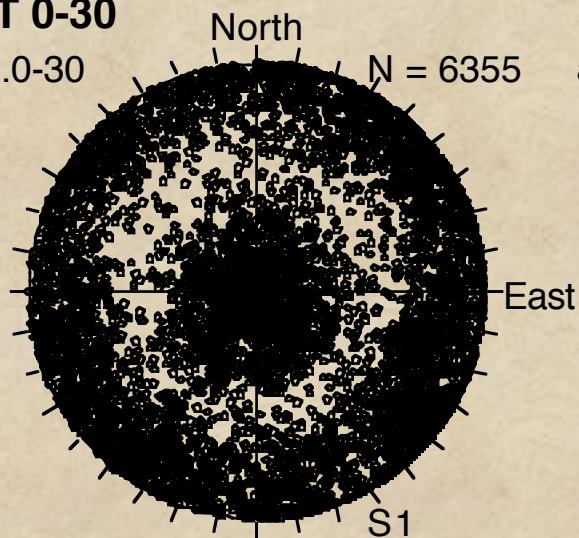
Results

FD versus CMT 0-30 km

CMT 0-30

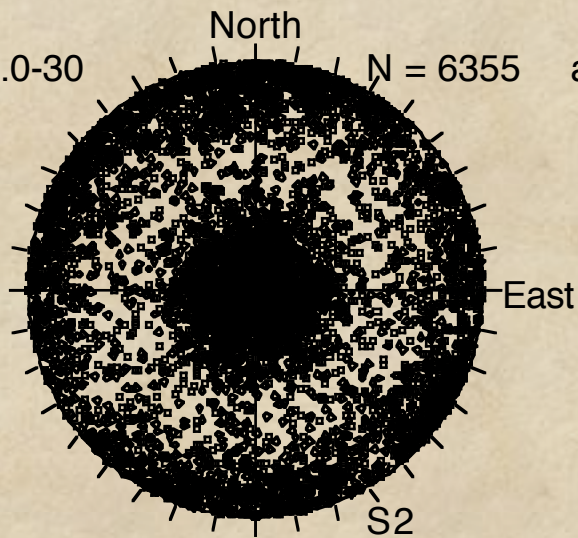
all.0-30

N = 6355



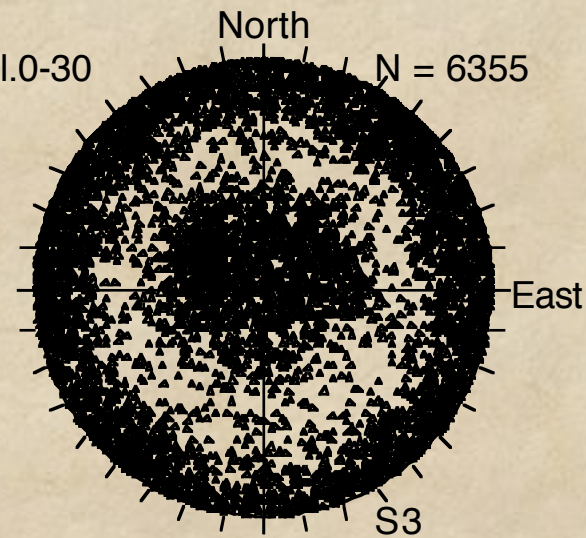
all.0-30

N = 6355



all.0-30

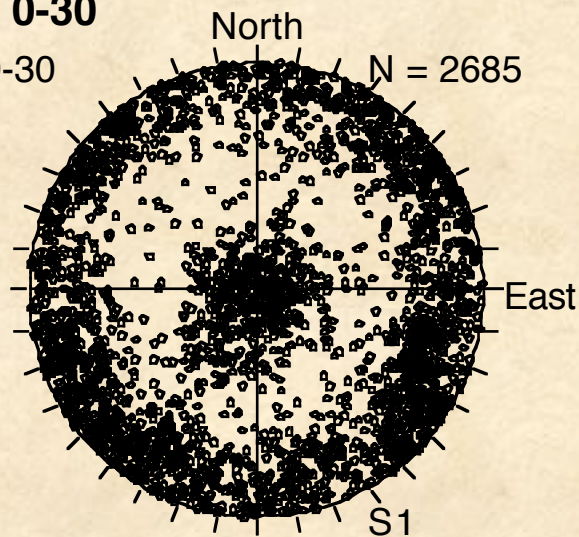
N = 6355



FD 0-30

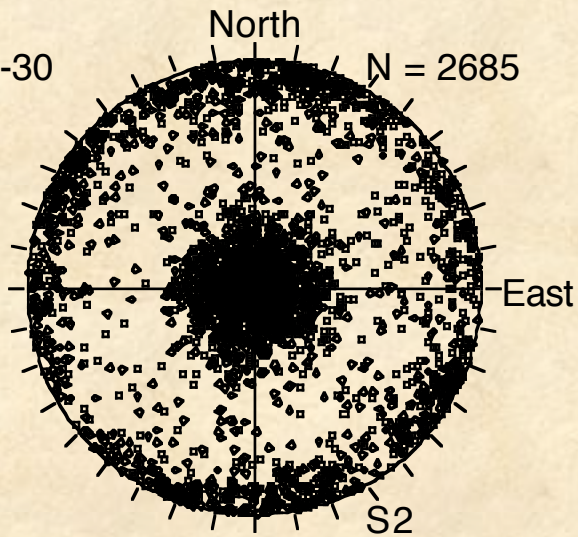
0-30

N = 2685



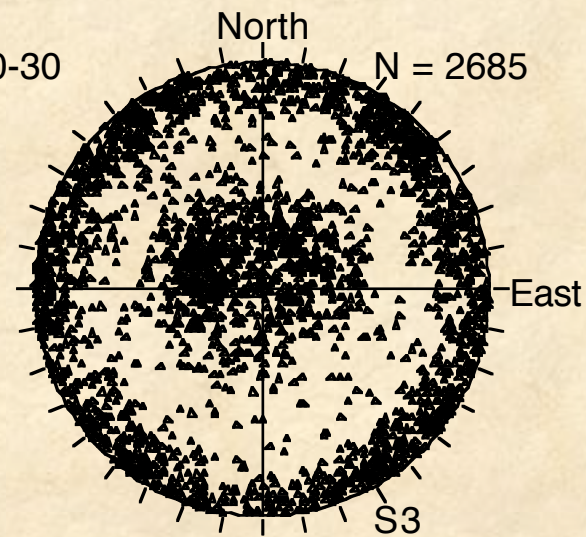
0-30

N = 2685



0-30

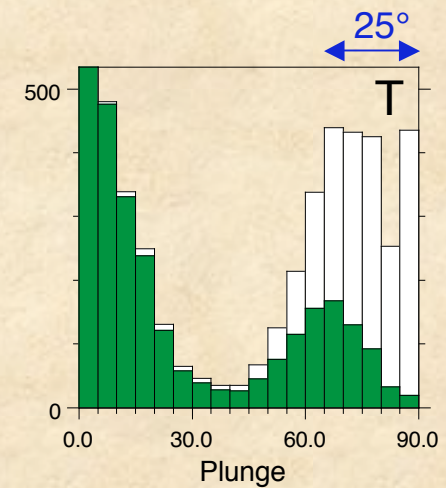
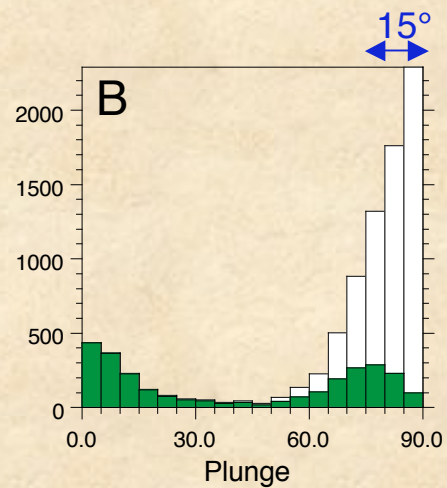
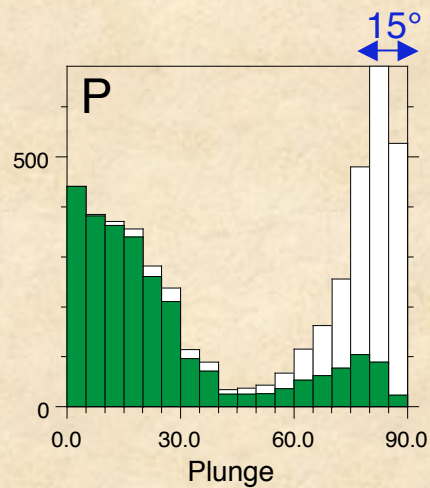
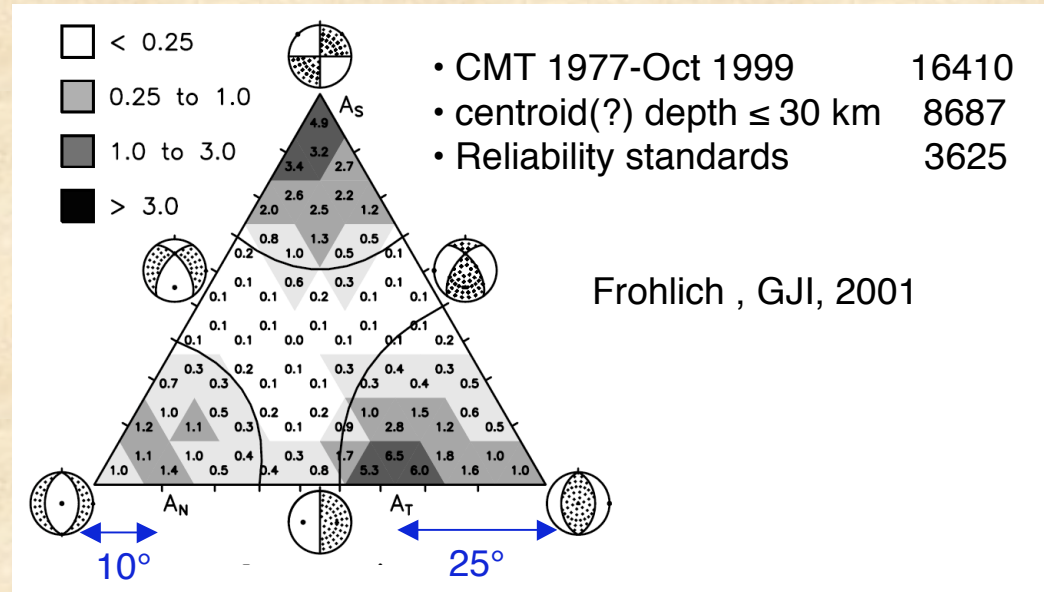
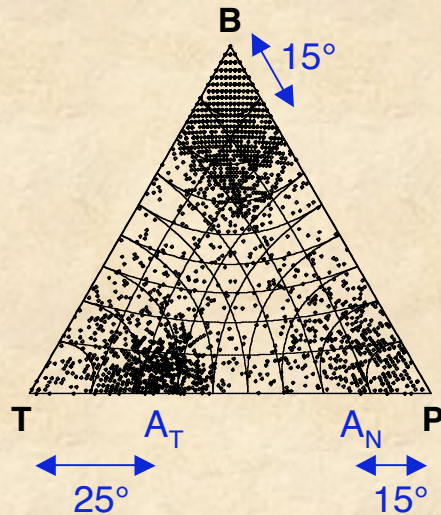
N = 2685



Results

FD 0-30 km versus Frohlich (2001)

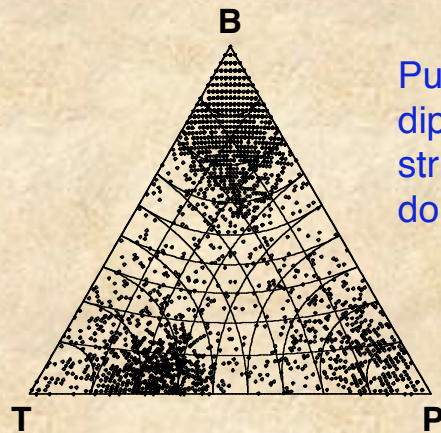
N = 2685



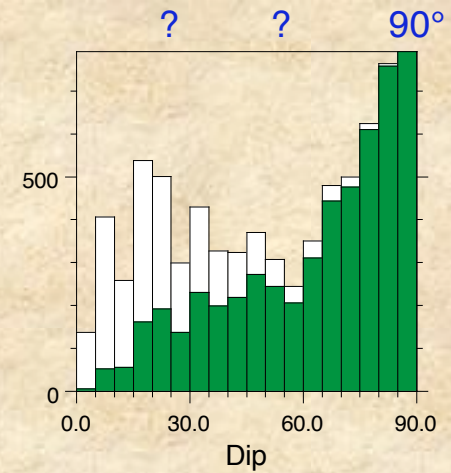
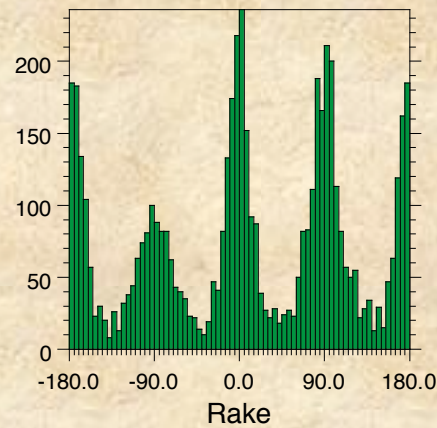
Results

FD 0-30 km

N = 2685



Pure,
dip-slip and
strike-slip
dominated



Rake, P, B, T: consistent with dominant Anderson
Dip: inconclusive for dip-slip, ok for strike slip ?

⇒ Isolate pure strike and dip-slip events
Question: selection on both nodal planes or on one at least ?

Selection

One or two nodal planes: dip slip case

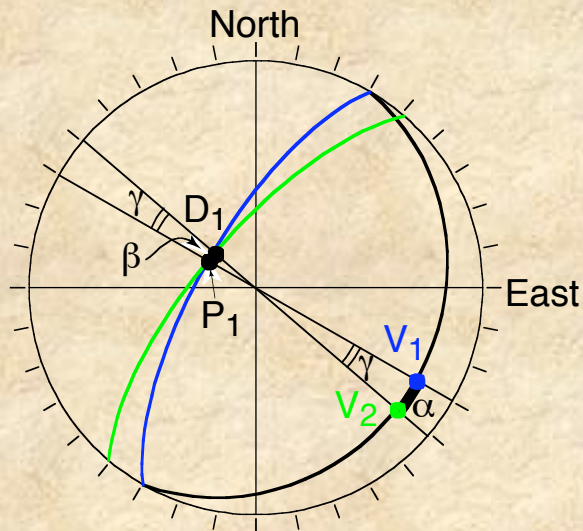
Consider two slightly different mechanisms where

- Case 1: the first nodal plane is pure dip-slip (P1,V1)
- Case 2: the same nodal plane is near dip-slip (P1,V2) and look at the second nodal plane.

	Nodal planes	
	1st	2nd
Pole	P1	V1
Slip	V1	P1
Pole	P1	V2
Slip	V2	P1

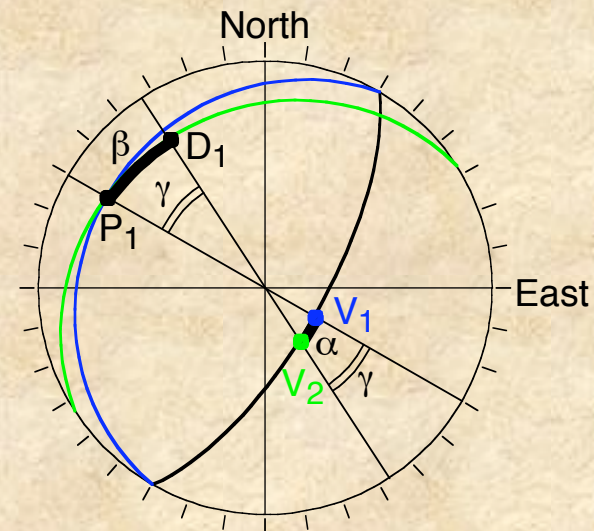
D1: down dip for plane 2, case 2

The first nodal plane has a shallow dip:



- Case 1: the second nodal plane is pure dip-slip
- Case 2: the second nodal plane is near dip-slip

The first nodal plane has a steep dip:



- Case 1: the second nodal plane is pure dip-slip
- Case 2: the second nodal plane has an oblique slip

Selection

One or two nodal planes: strike slip case

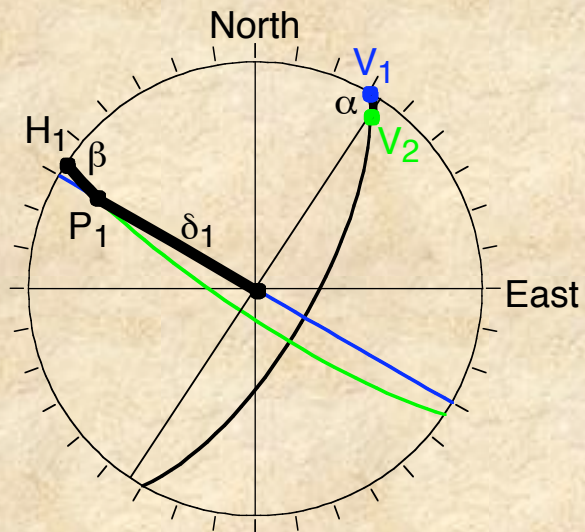
Consider two slightly different mechanisms where

- Case 1: the first nodal plane is pure strike-slip (P_1, V_1)
- Case 2: the same nodal plane is near strike-slip (P_1, V_2) and look at the second nodal plane.

	Nodal planes	
	1st	2nd
Pole	P_1	V_1
Slip	V_1	P_1
Pole	P_1	V_2
Slip	V_2	P_1

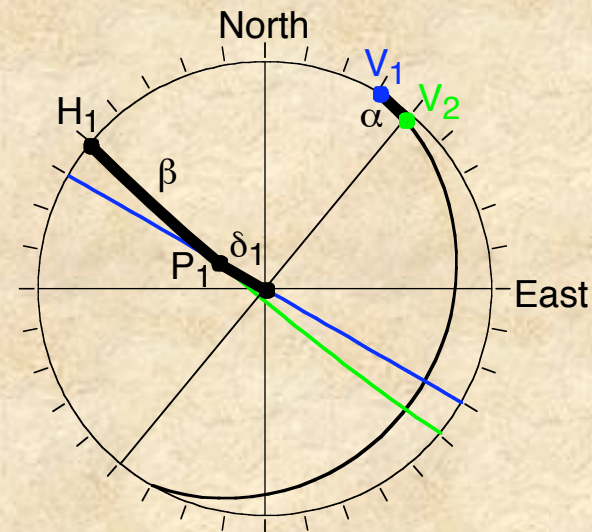
H1: along strike for plane 2, case 2

The first nodal plane has a steep dip:



- Case 1: the second nodal plane is near strike-slip
- Case 2: the second nodal plane is near strike-slip

The first nodal plane has a shallow dip:



- Case 1: the second nodal plane is near dip-slip
- Case 2: the second nodal plane is near dip-slip

Selection

One or two nodal planes ?

One near dip-slip nodal plane:

- Steep dip => oblique slip on second nodal plane
- Shallow dip => near dip-slip second plane

One near strike-slip nodal plane:

- Steep dip => near strike-slip second nodal plane
- Shallow dip => oblique slip on second plane

Select near dip-slip or strike-slip rake on at least one nodal plane:

- includes all actual fault planes with that rake
- includes also actual oblique slip fault planes

Select rake on both nodal plane:

- excludes fault planes with that rake
- includes only fault planes with that rake

Conclusions:

- no perfect solution
- investigate both 1 (1P) and 2 planes (2P)

Results

Rake within 10° of pure dip or strike slip

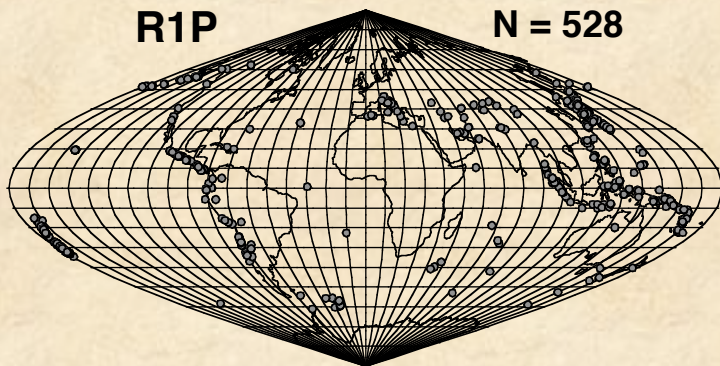
1976-2004 FD 0-30 km

Rake range	1 or 2 planes ?	Data set	Number of data
[80,100]	1 plane	R1P	528
[80,100]	2 planes	R2P	267
[-180,-170] U [-10,10] U [170,180]	1 plane	S1P	1130
[-180,-170] U [-10,10] U [170,180]	2 planes	S2P	437
[-100,-80]	1 plane	N1P	217
[-100,-80]	2 planes	N2P	147

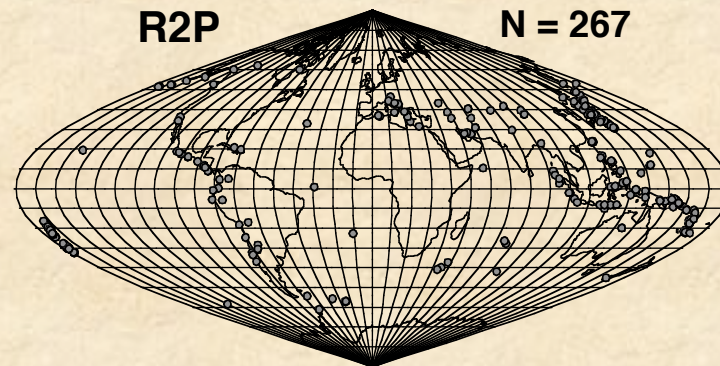
Results

Localisation

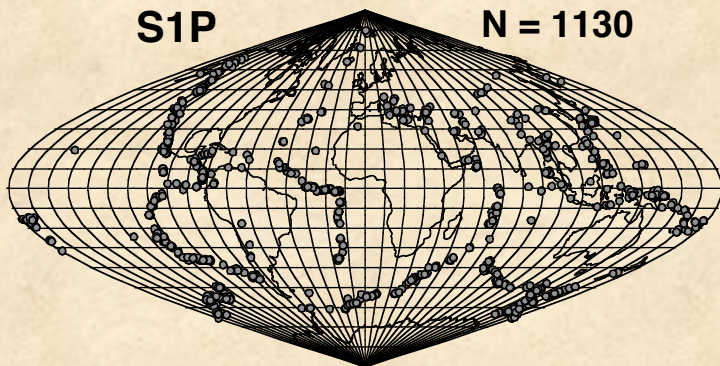
R1P N = 528



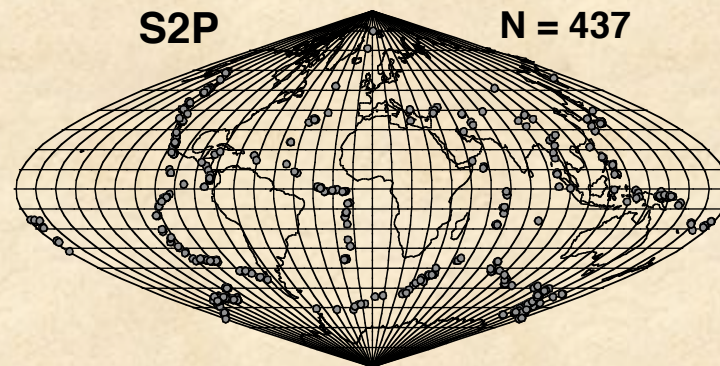
R2P N = 267



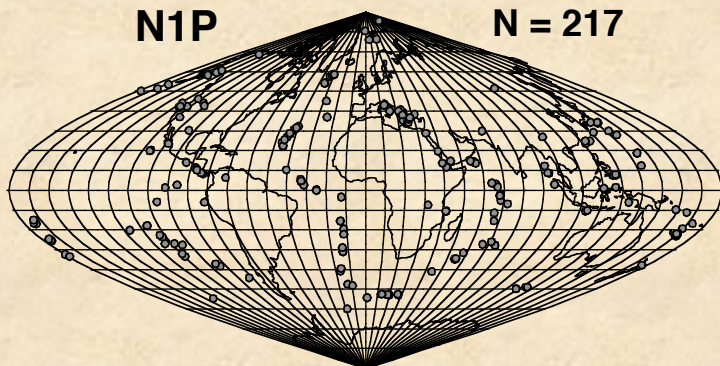
S1P N = 1130



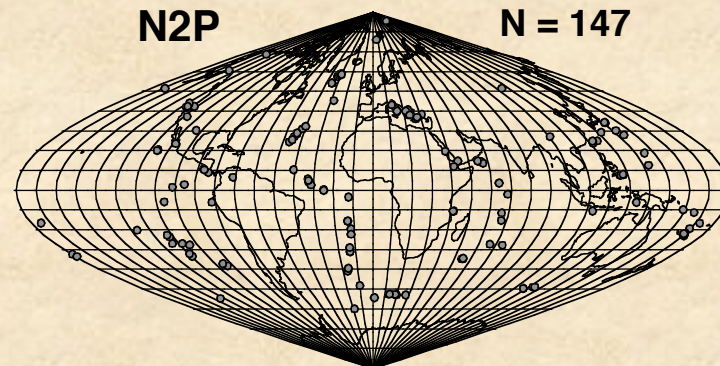
S2P N = 437



N1P N = 217

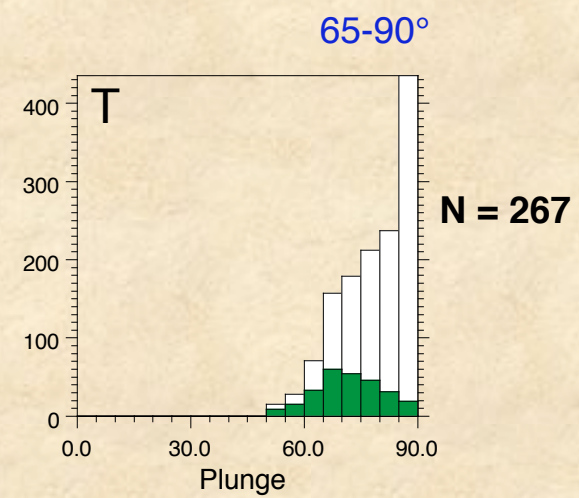
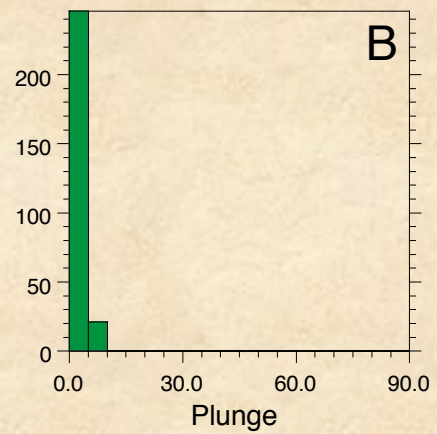
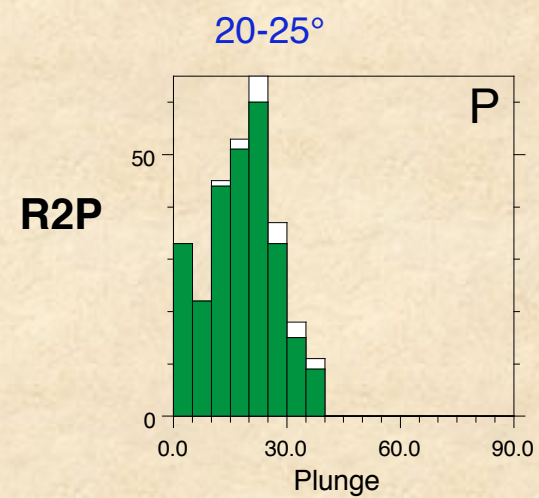
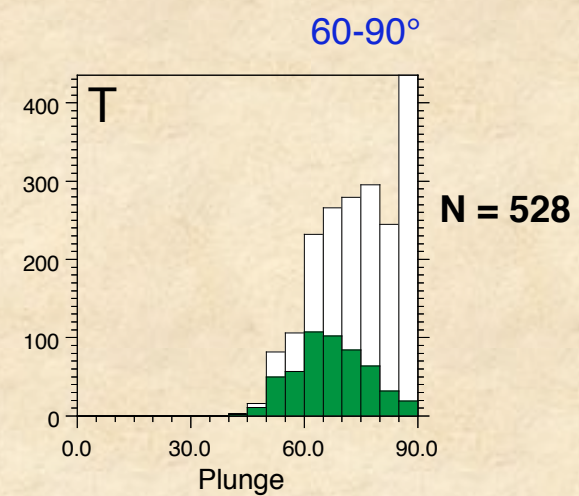
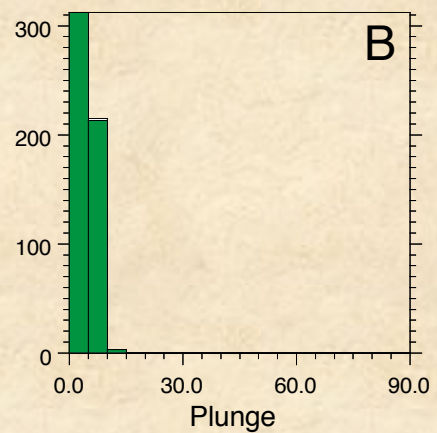
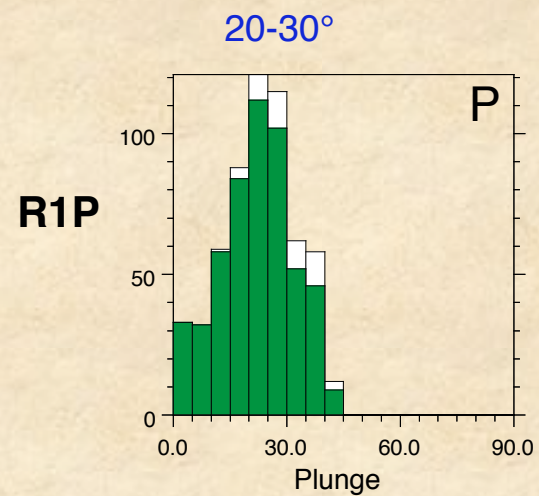


N2P N = 147



Results

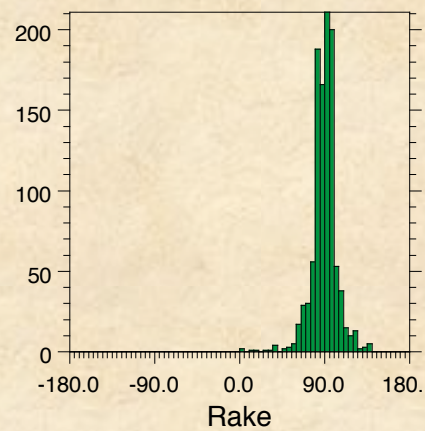
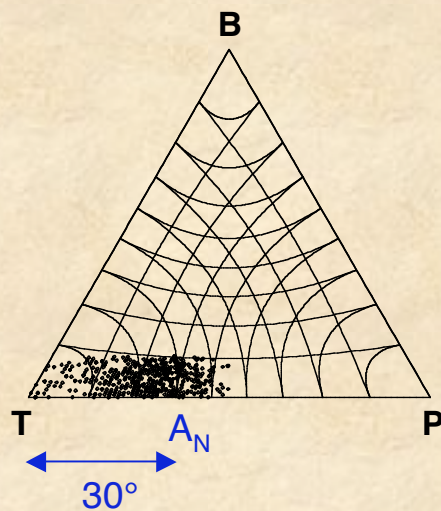
Reverse



Results

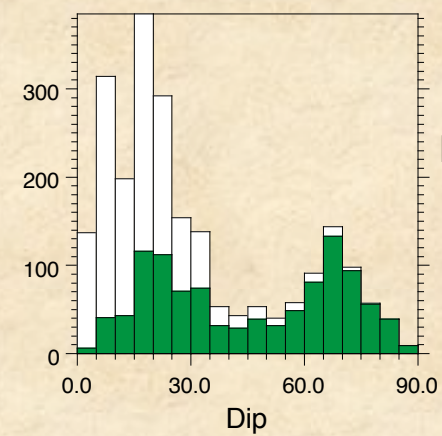
Reverse

R1P

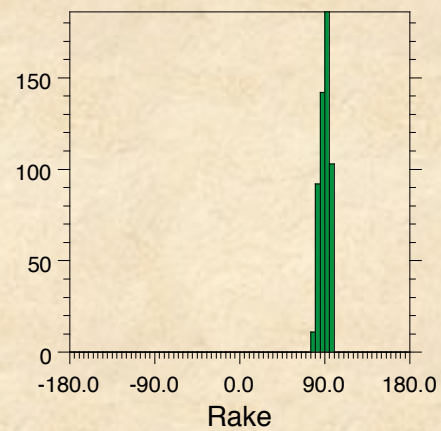
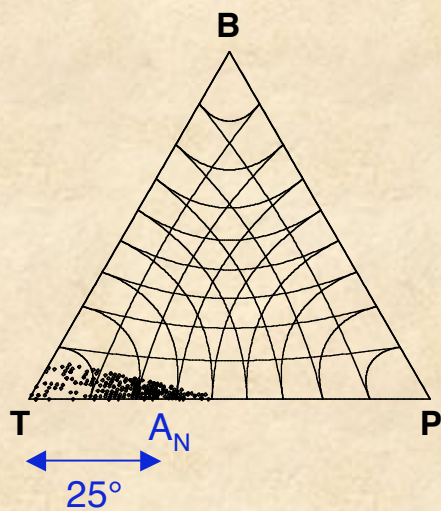


15-25°

65-70°

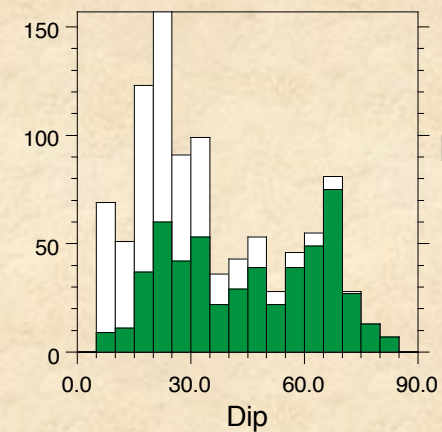


R2P



20-25°

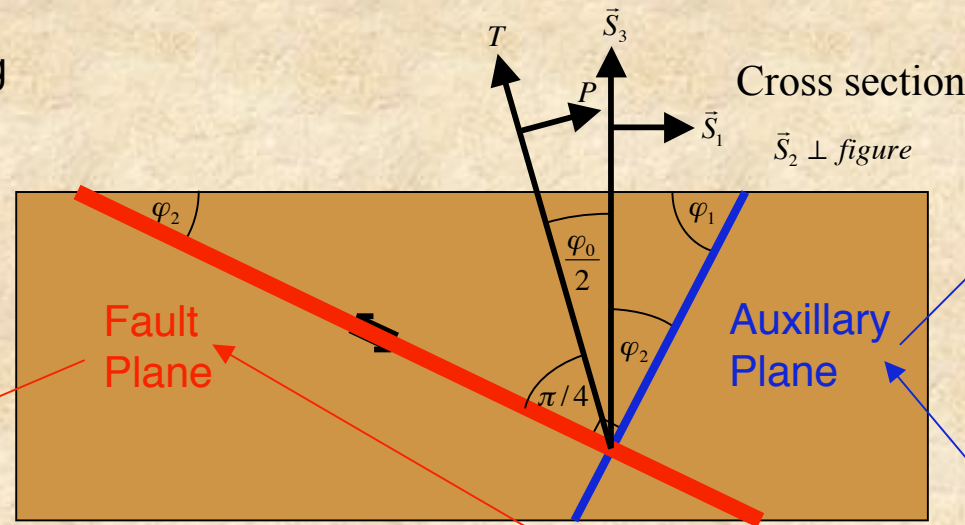
65-70°



Pure Reverse Faulting

N=528

R1P



$$\varphi_2 = 45^\circ - \varphi_0/2$$

$$\varphi_0 = 40-60^\circ$$

$$\varphi_1 = \varphi_0/2 + 45^\circ$$

$$\varphi_0 = 40-50^\circ$$

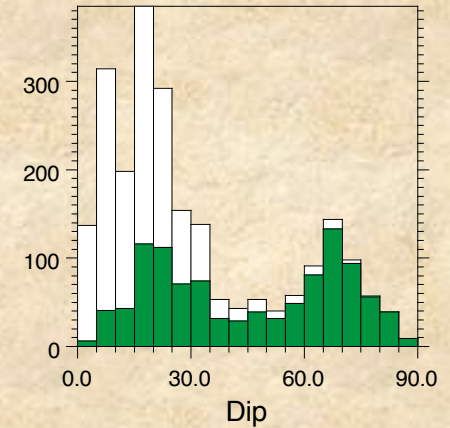
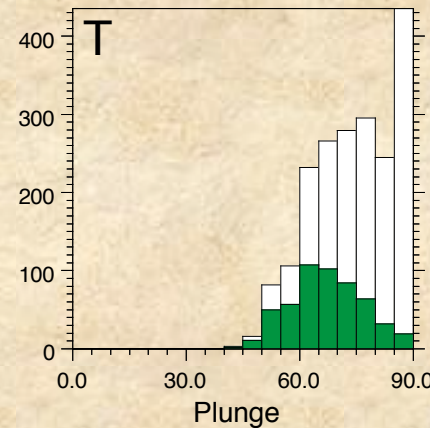
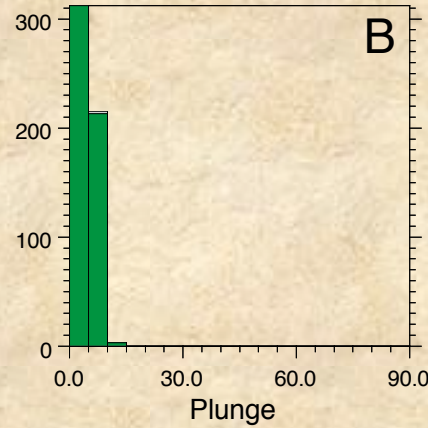
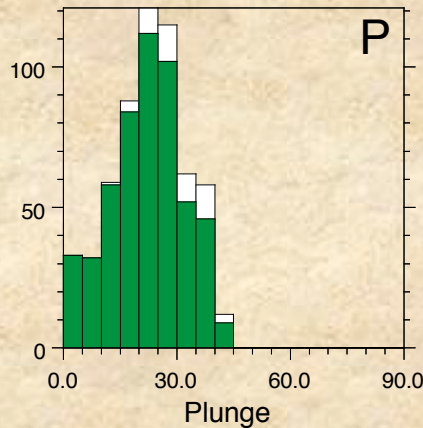
$$\varphi_0 = 40-60^\circ$$

$$\varphi_0 = 0-60^\circ$$

$$0-30^\circ$$

$$15-25^\circ$$

$$65-70^\circ$$

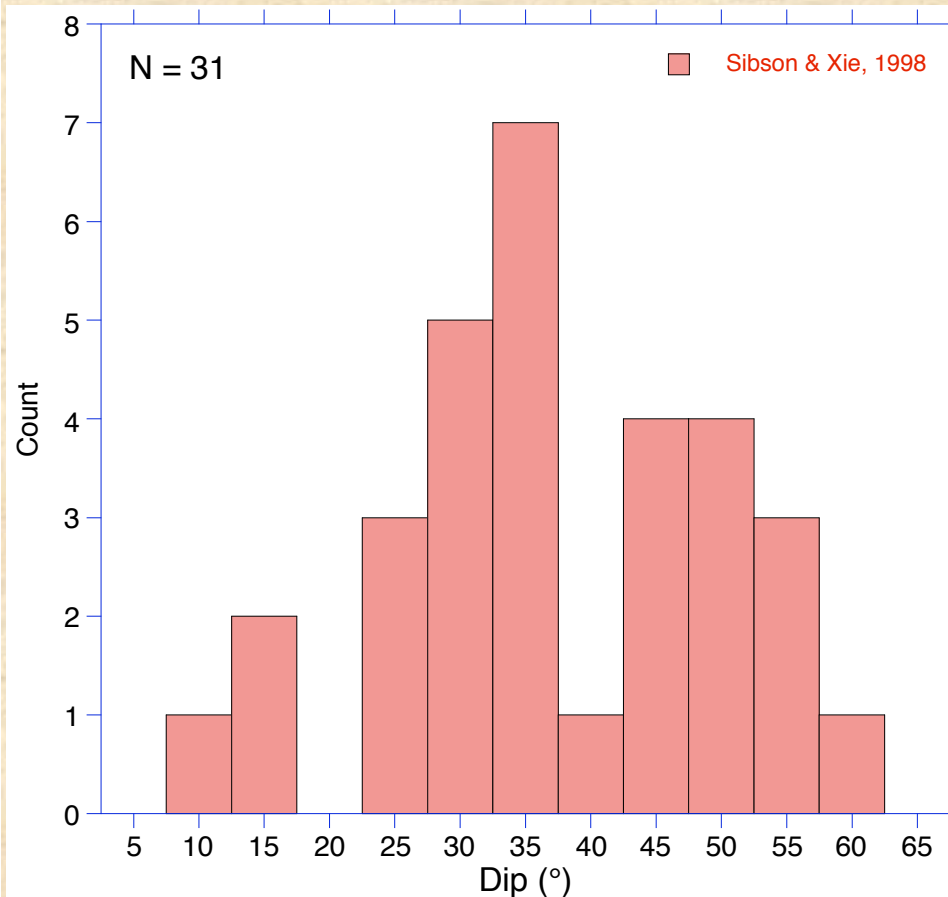


$M > 5.5$

Fault plane (known)

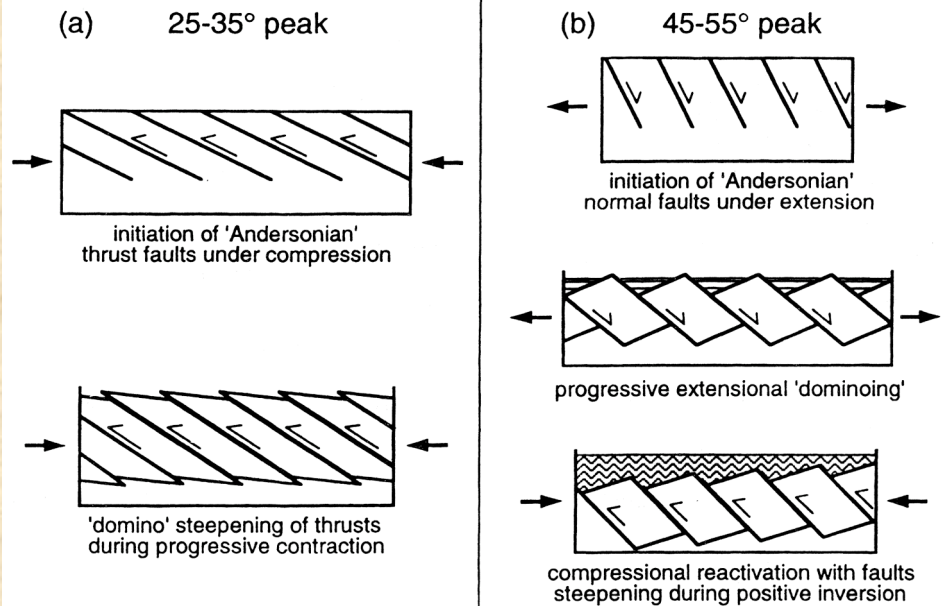
Rake = $+90 \pm 30^\circ$

Optimal & lock up angles
2D frictional sliding



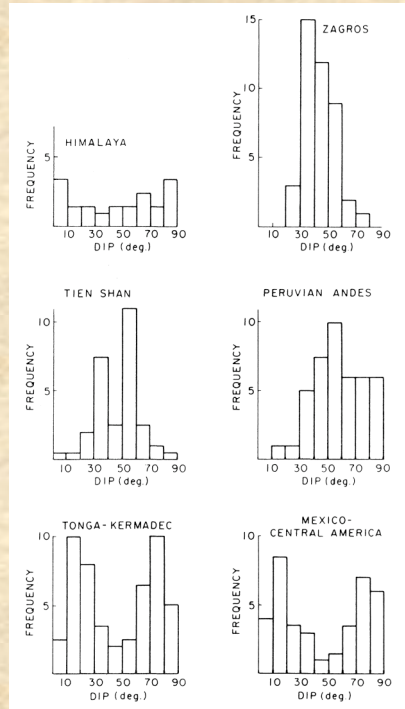
Conclusions:

- Bimodal 25-35°, 45-55°
- 25-35° $\rightarrow \varphi_0 = 20-40^\circ$
- Paucity of $\delta < 20^\circ$
- Lock up angle $\delta = 60^\circ$
consistent with $\mu = 0.6$
- Domino rotation to high dip (45-55°)?
- Reactivation of normal faults (45-55°)?



Molnar & Chen,
1982

Both
nodal
planes



Triep et al, JGR, 1995

CMT 1977-1992

0-40 km

Plunge P < plunge T

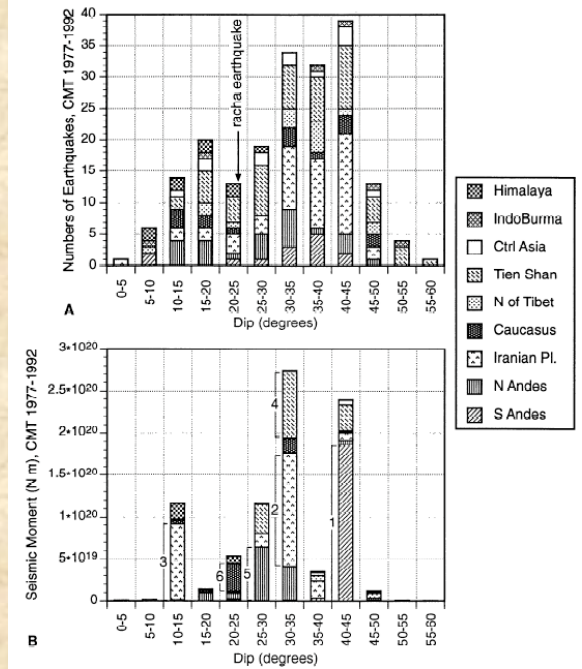
$$\sqrt{(plunge\ P)^2 + (plunge\ T)^2} > 45^\circ$$

Assume

Shallower dip = Fault

⇒ maximum estimate
of shallow dip

TRIEP ET AL.: ACTIVE THRUST FRONT OF THE GREATER CAUCASUS

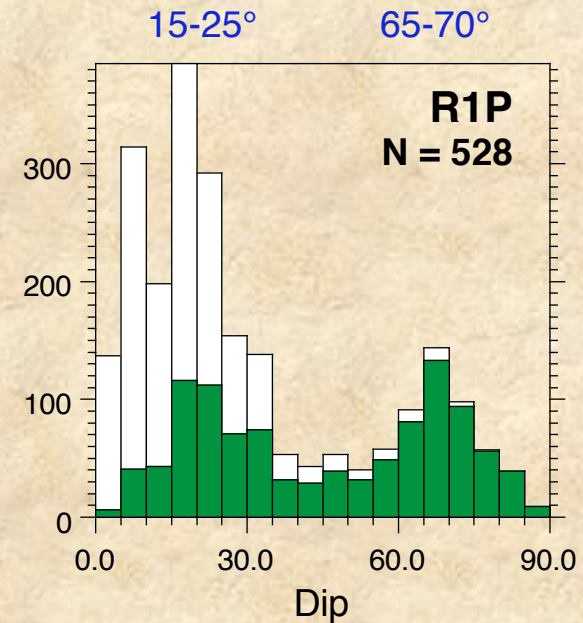
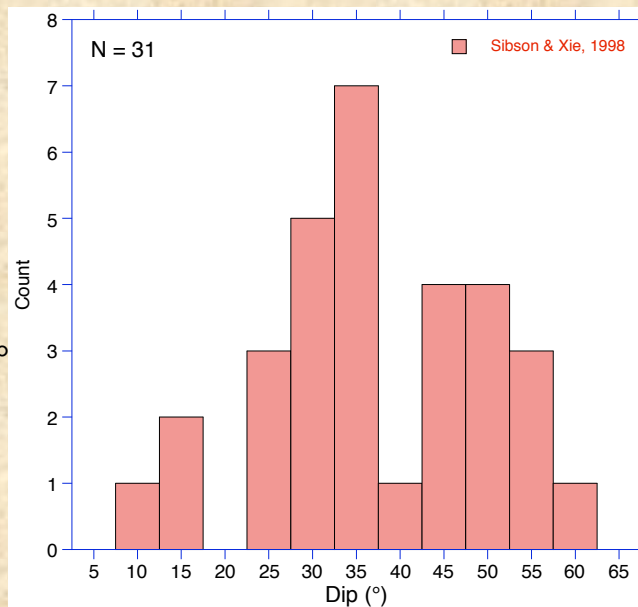


Sibson & Xie,
1998

M > 5.5

Fault plane
(known)

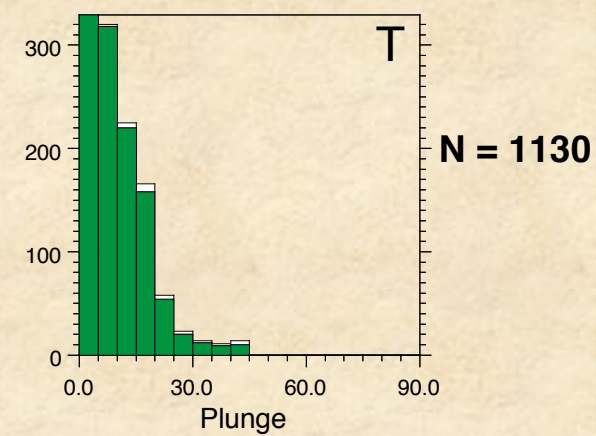
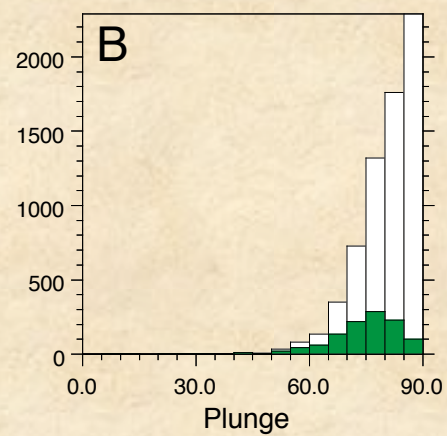
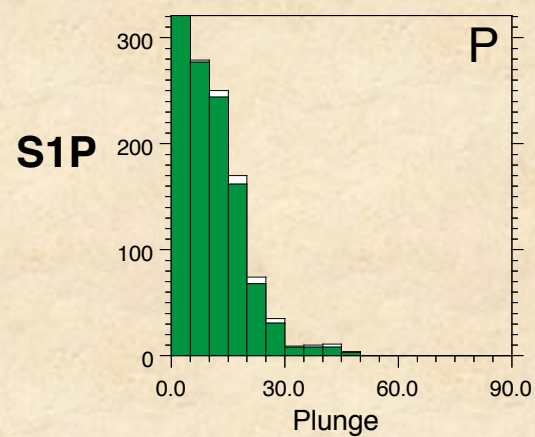
Rake = +90±30°



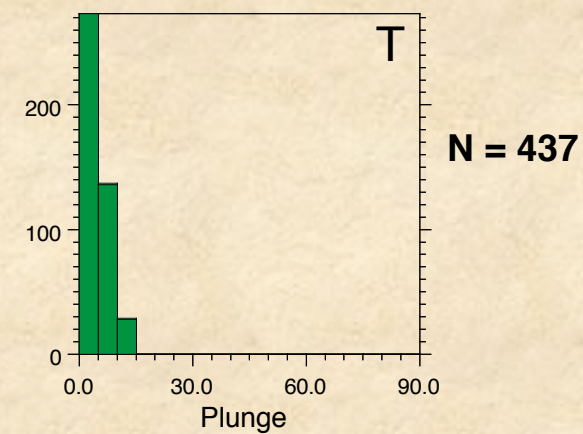
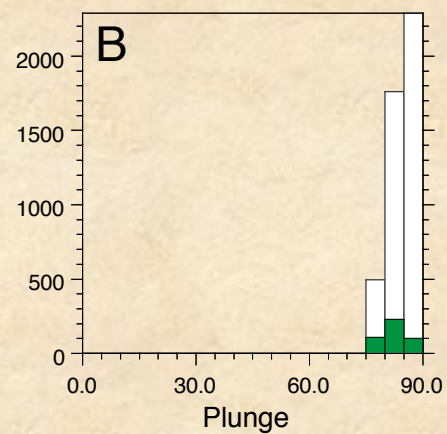
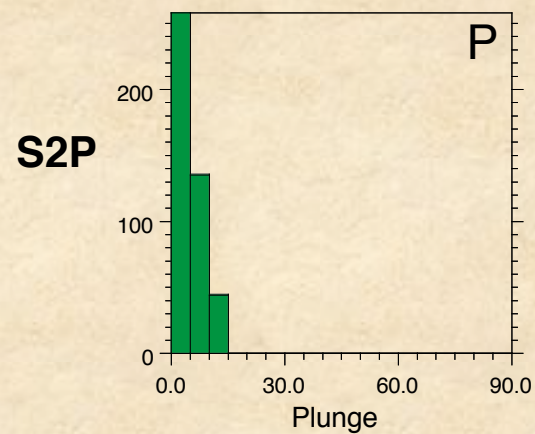
Results

Strike-slip

75-90°



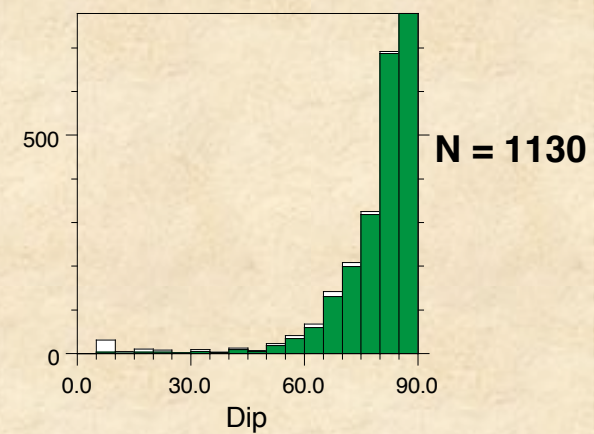
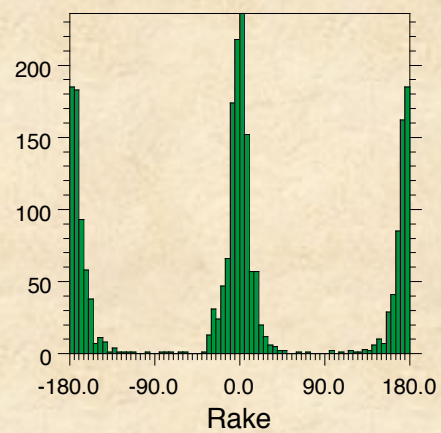
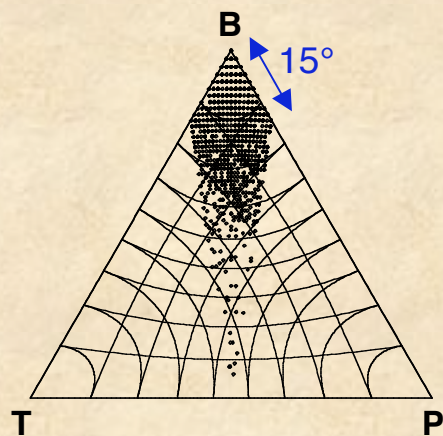
80-90°



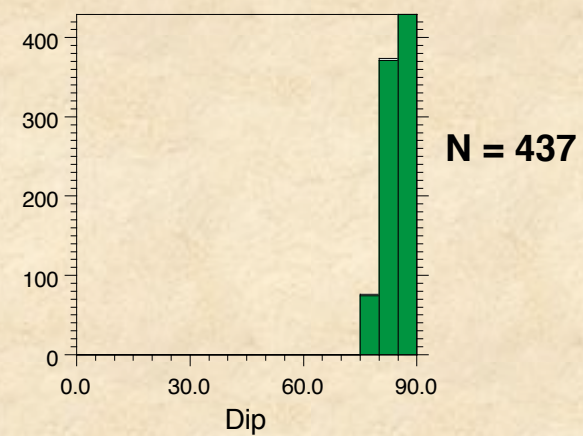
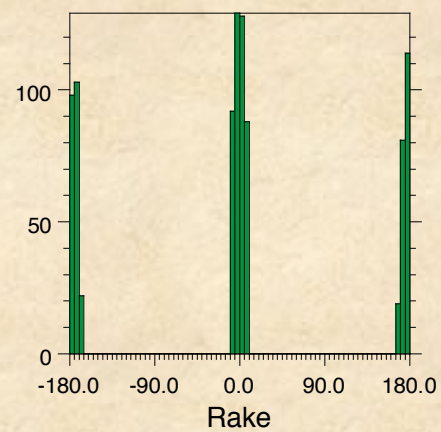
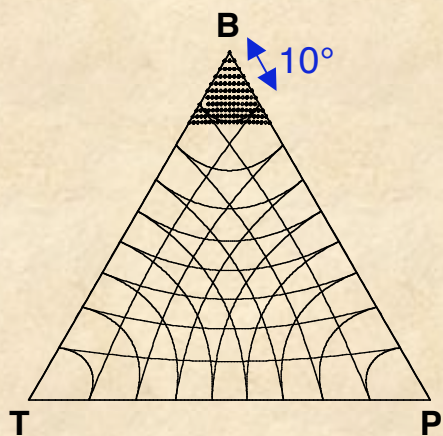
Results

Strike-slip

S1P



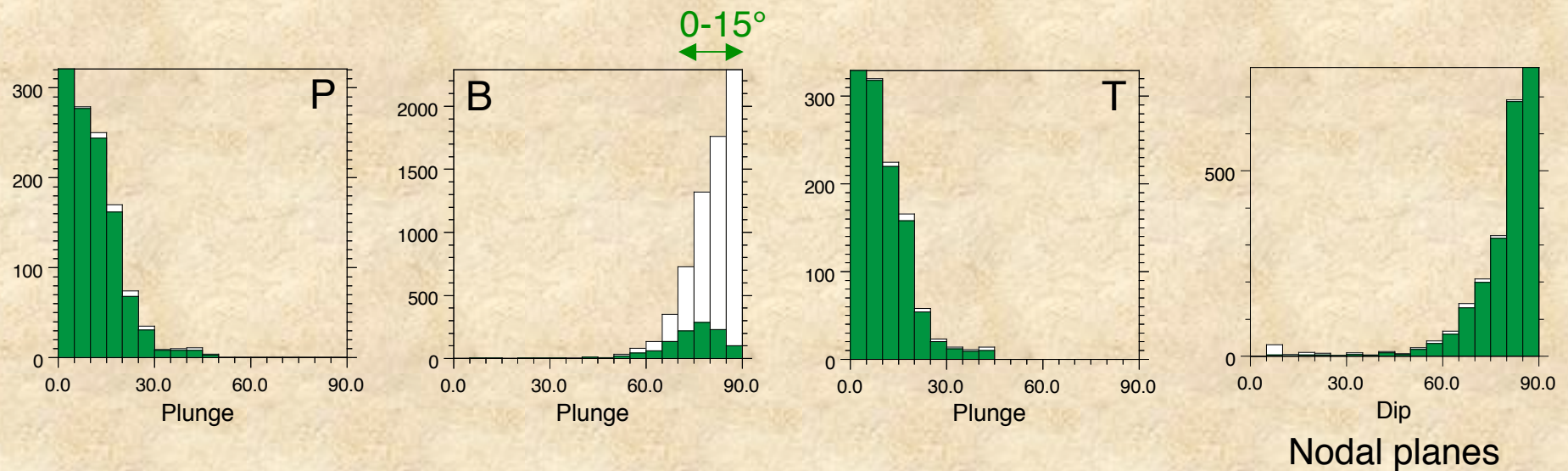
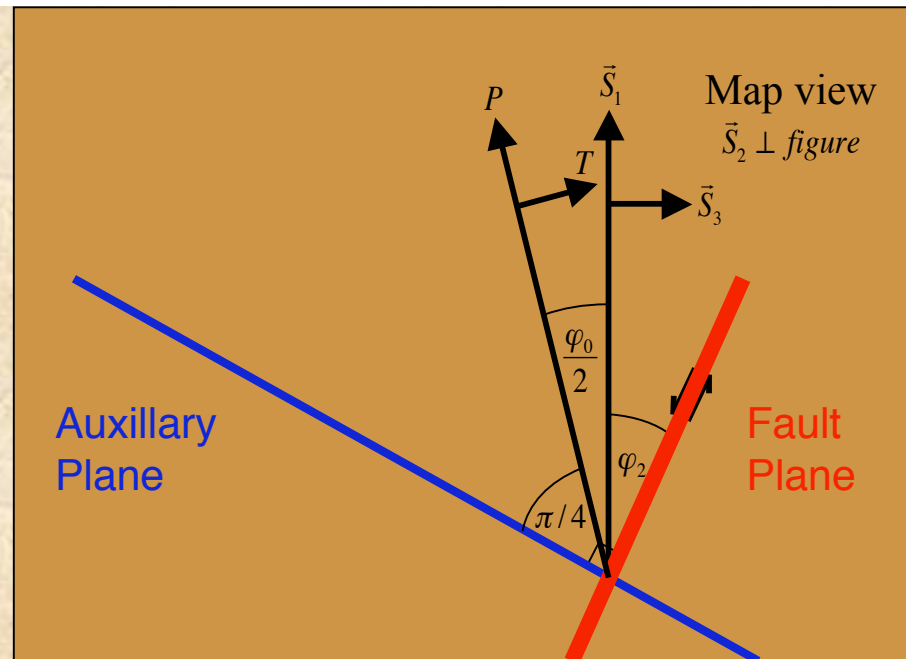
S2P



Pure Strike Slip Faulting

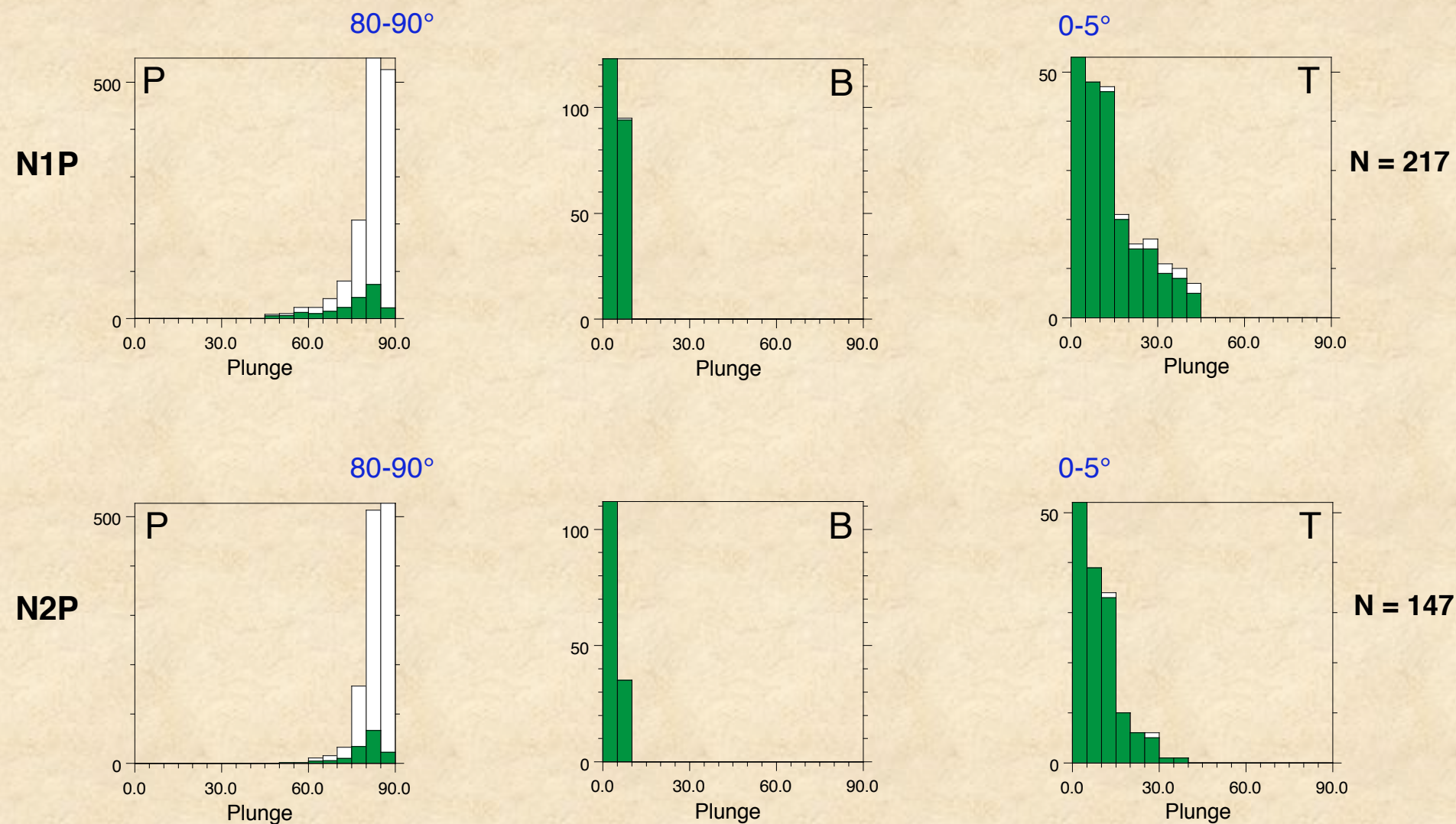
N=1130

S1P



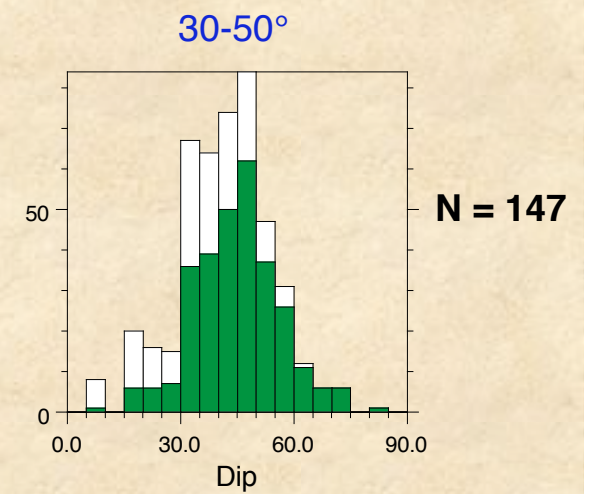
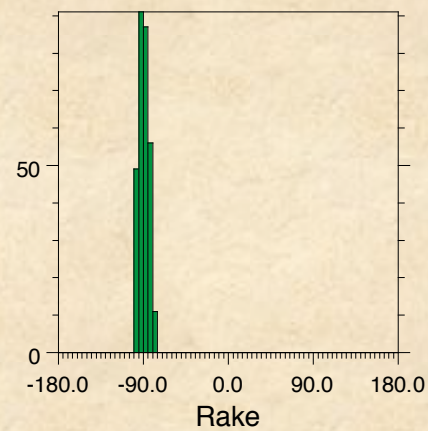
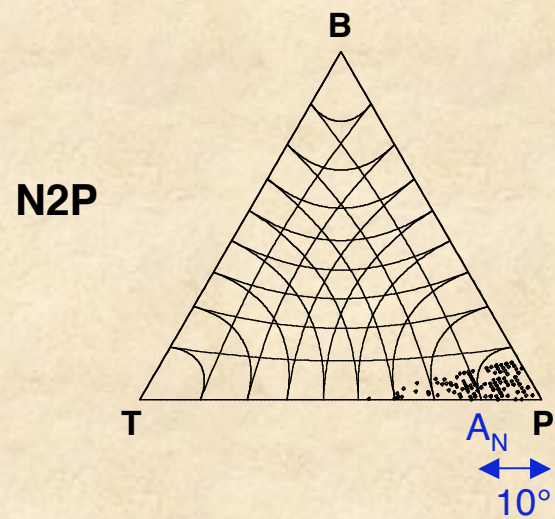
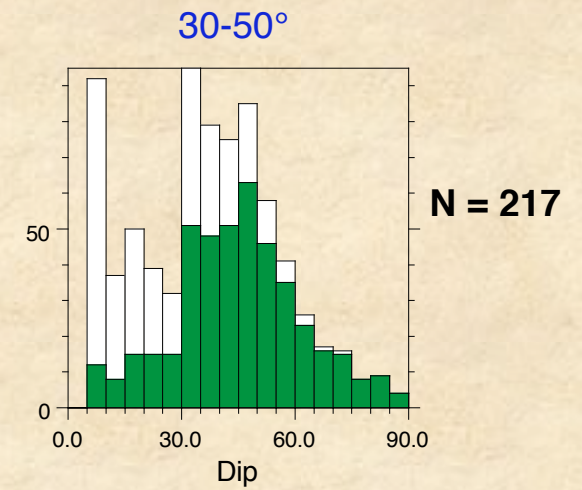
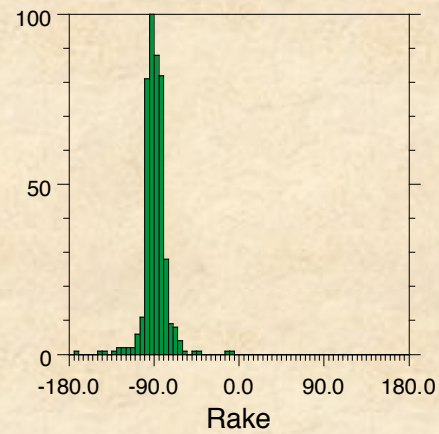
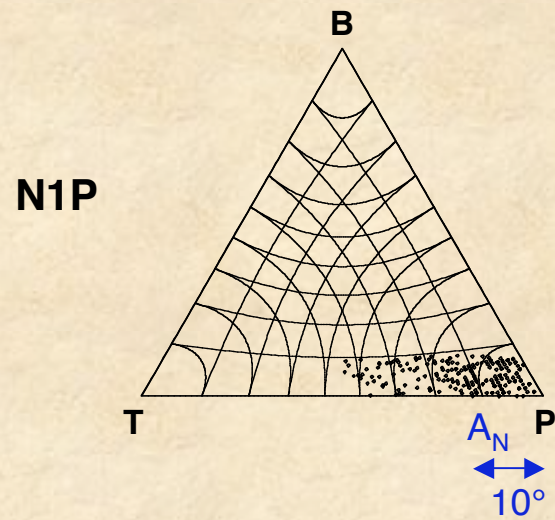
Results

Normal



Results

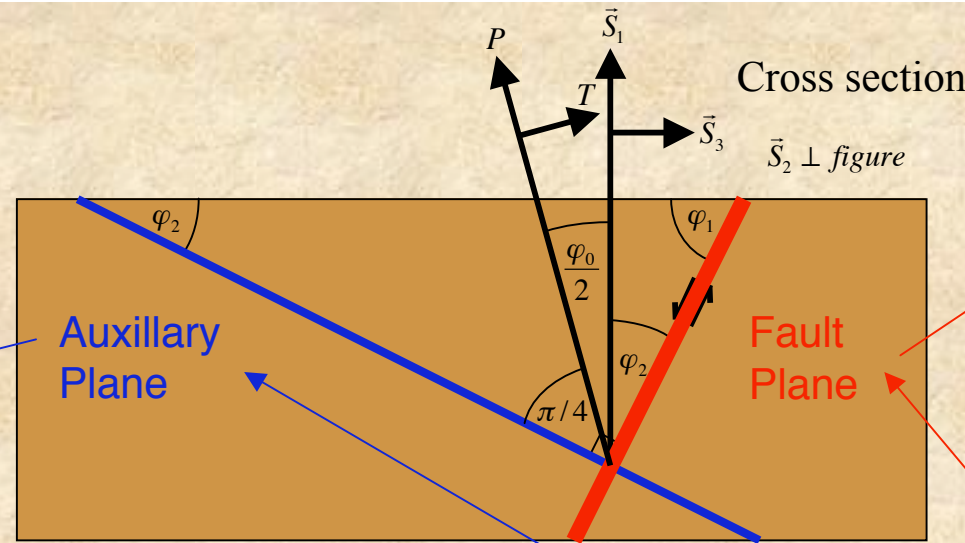
Normal



Pure Normal Faulting

N=217

N1P



$$\varphi_2 = 45^\circ - \varphi_0/2$$

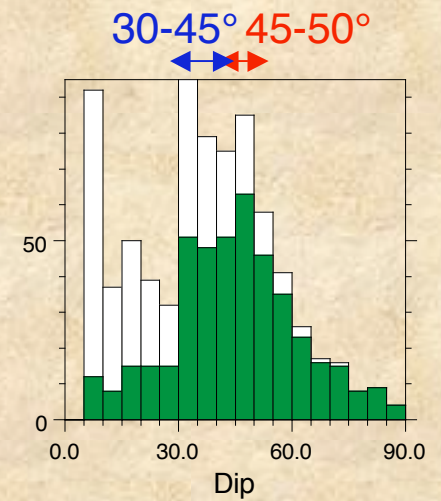
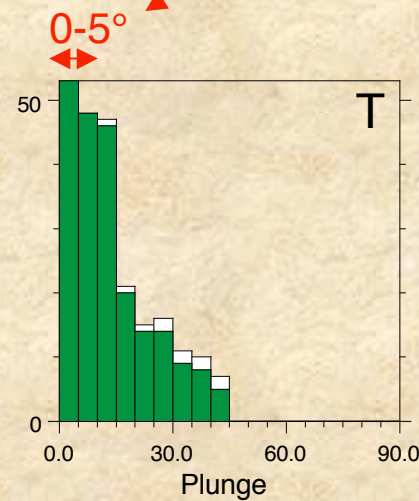
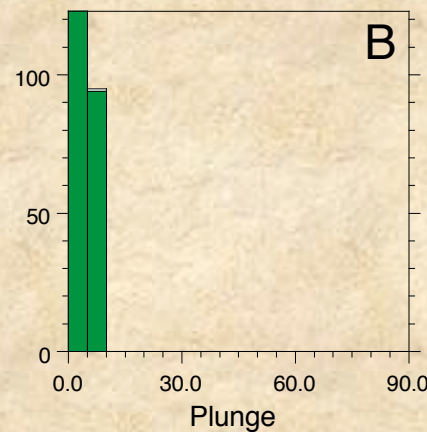
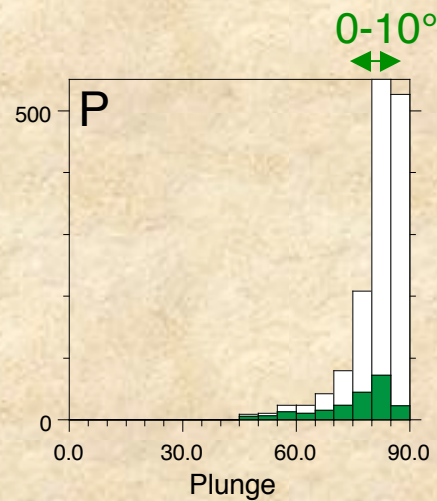
$$\varphi_0 = 0-30^\circ$$

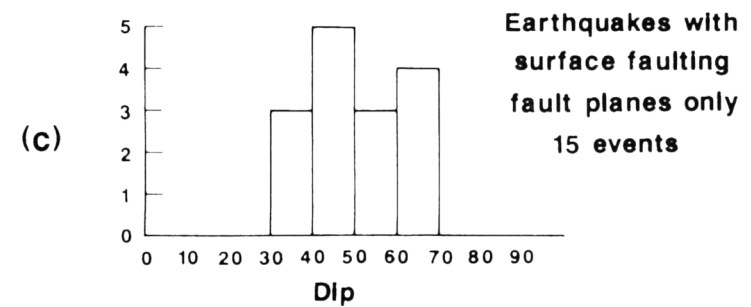
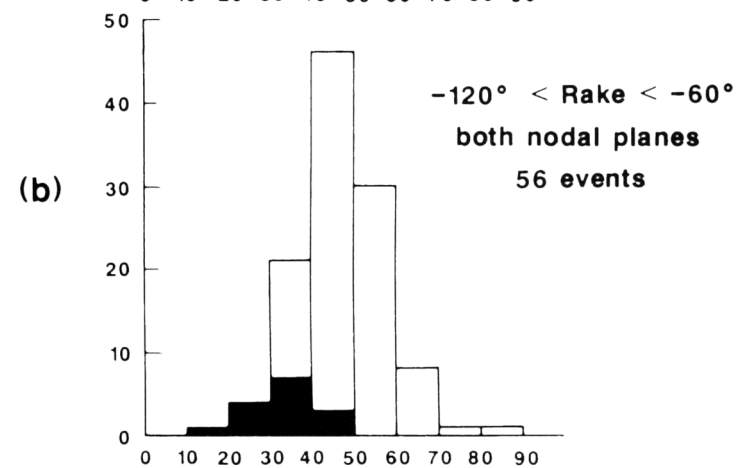
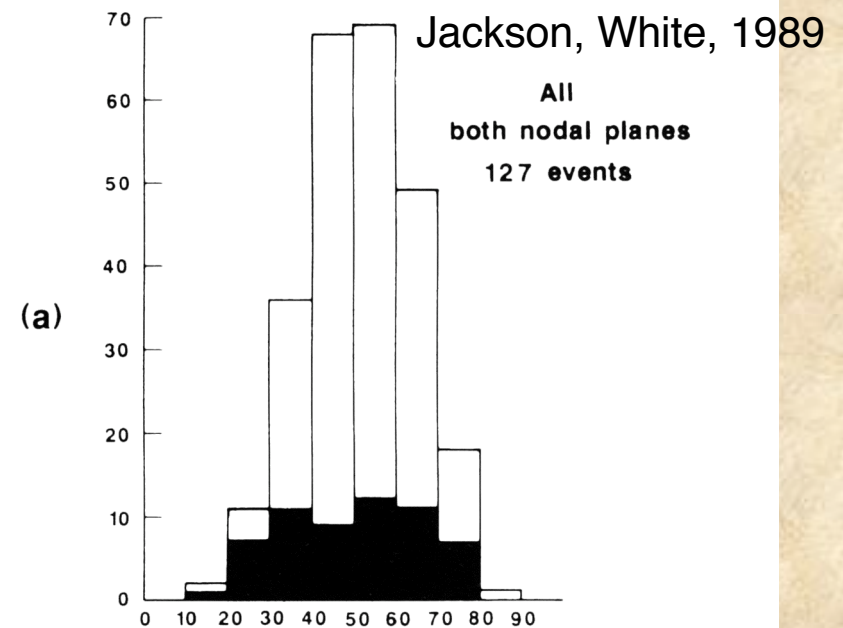
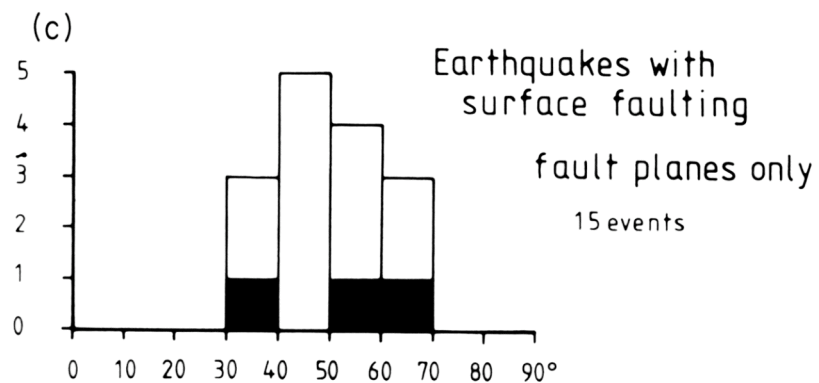
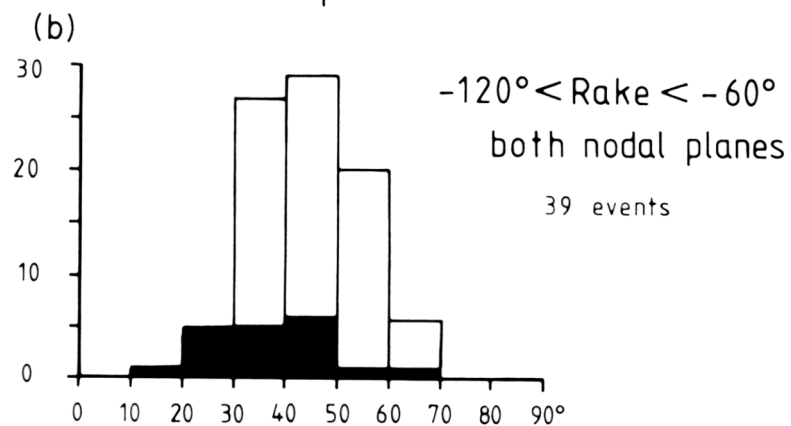
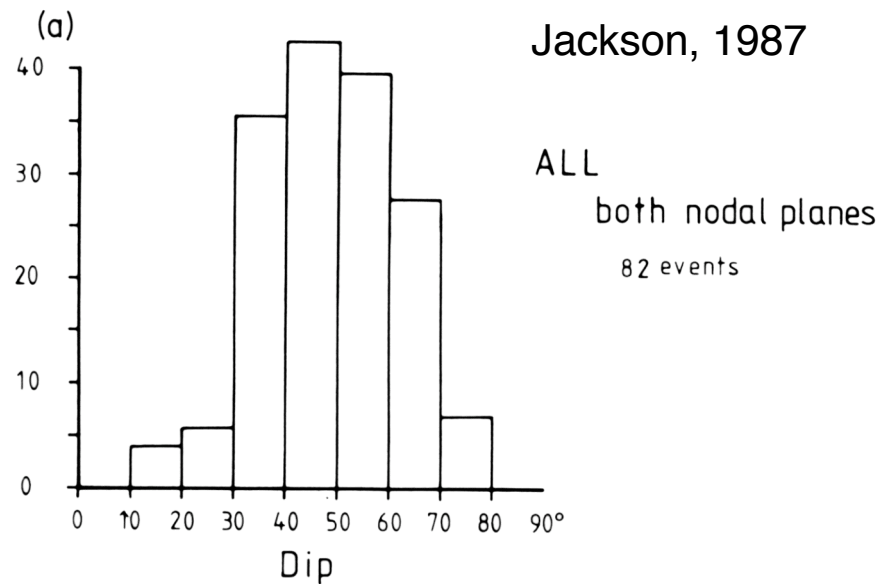
$$\varphi_0 = 0-20^\circ$$

Other interpretation:
 $\Rightarrow \varphi_0 < 0$

$$\varphi_1 = \varphi_0/2 + 45^\circ$$

$$\varphi_0 = 0-10^\circ$$





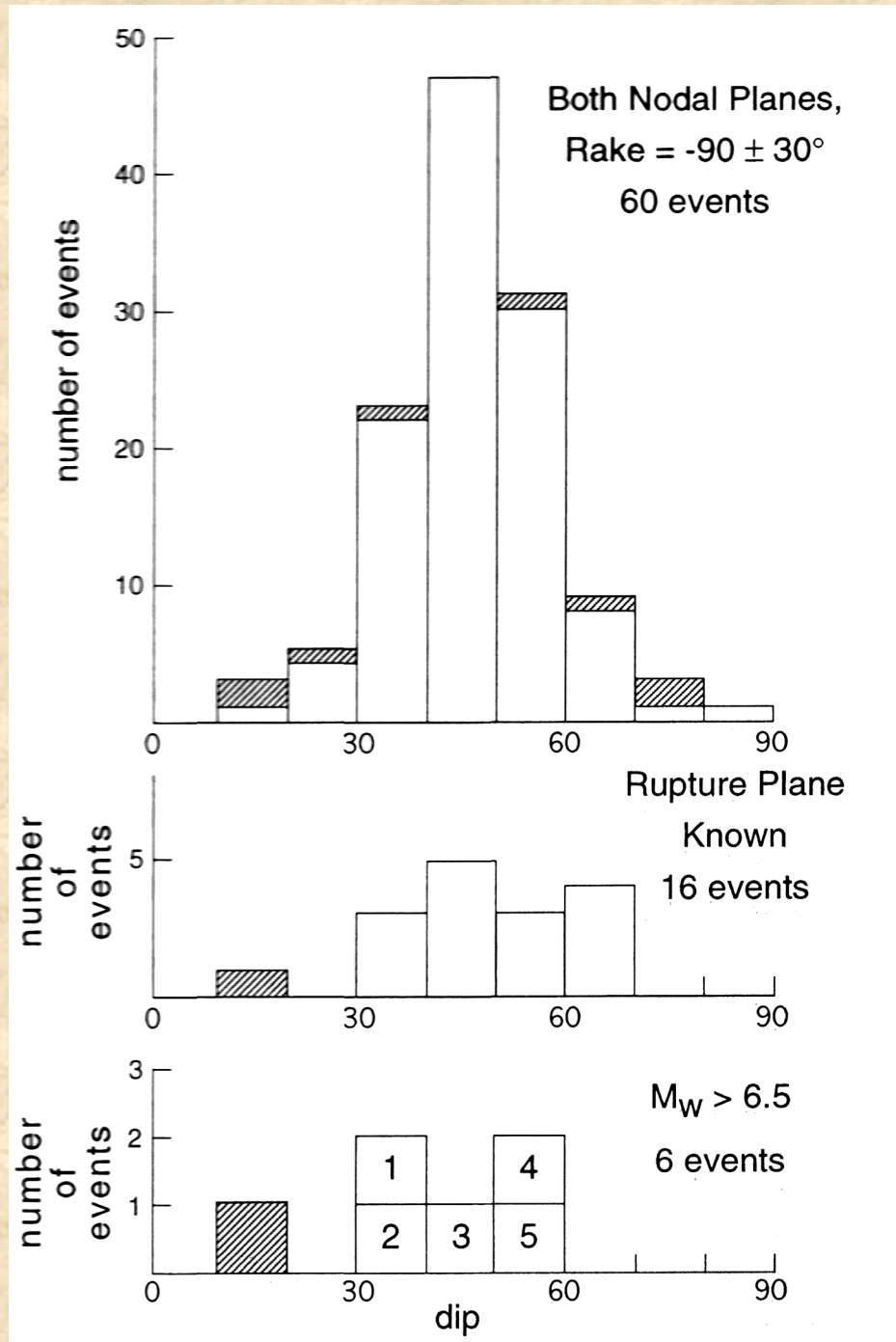
Wernicke, 1995, JGR

Jackson & White, 1989
Abers, 1991 (hatched)

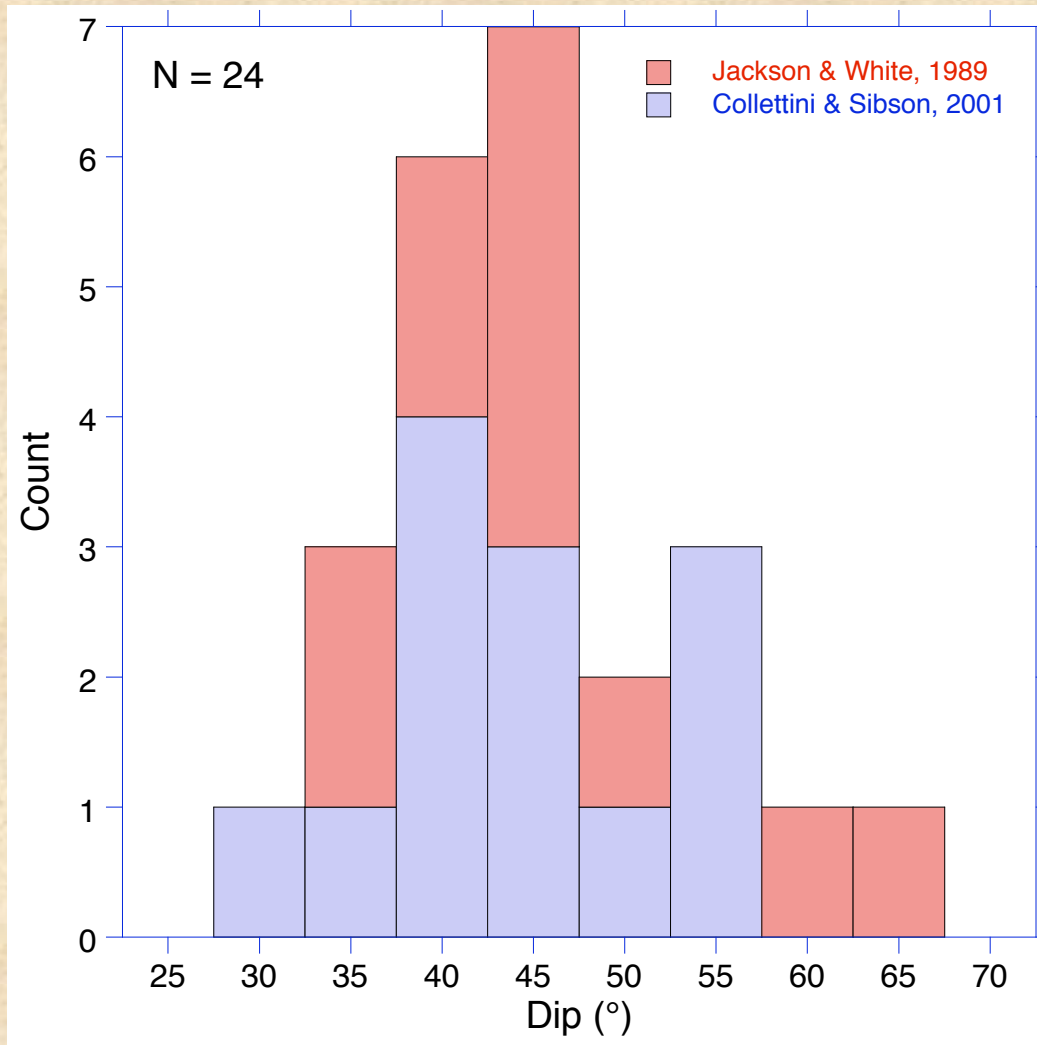
Jackson & White, 1989
Abers, 1991 (hatched = Woodlark basin)

Doser & Smith, 1989
Jackson & White, 1989
Abers, 1991 (hatched)

1 Aegean Sea 1970
2 Aegean Sea 1969
3 Hebgen Lake, 1959
4 Borah Peak, 1983
5 Italy, 1980



Colletini & Sibson, 2001

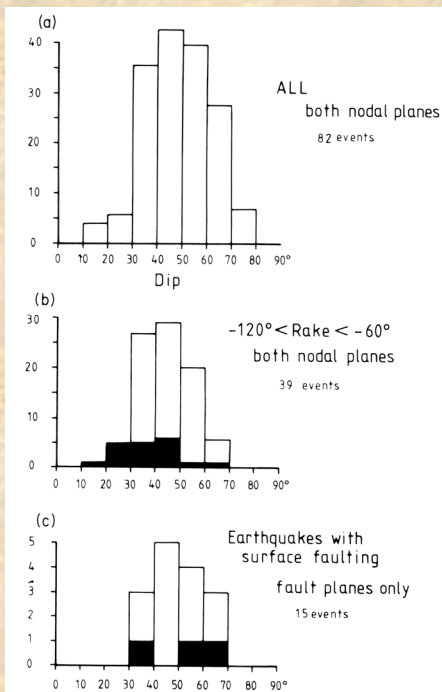


M > 5.5
Fault plane (known)
Rake = $-90 \pm 30^\circ$

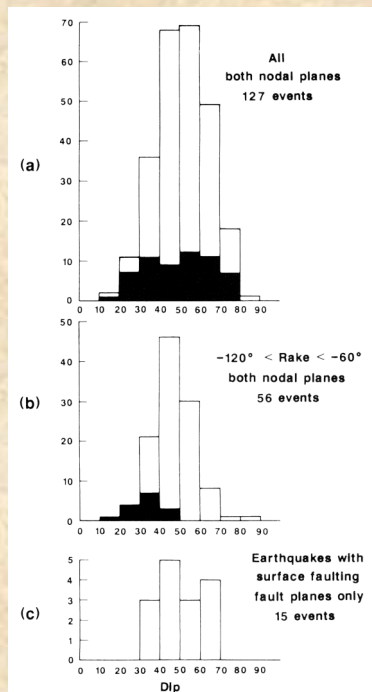
Conclusions:

- Lock up angle $\delta = 30^\circ$
consistent with $\mu = 0.6$
- Peak at 45° unexplained
- Domino rotation to low dip ?
- Reactivation of reverse faults ?

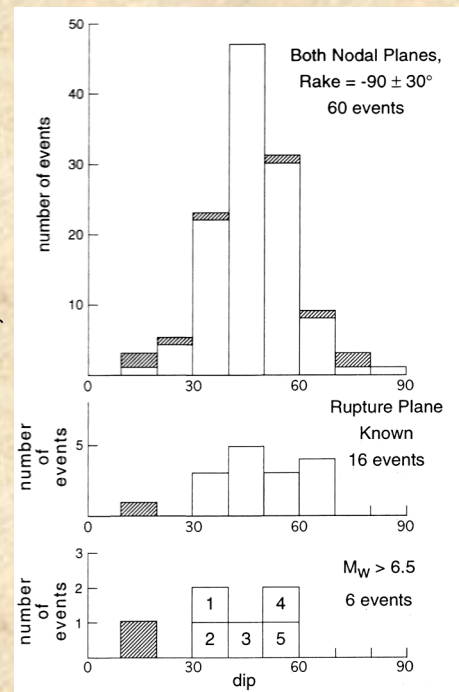
Jackson, 1987



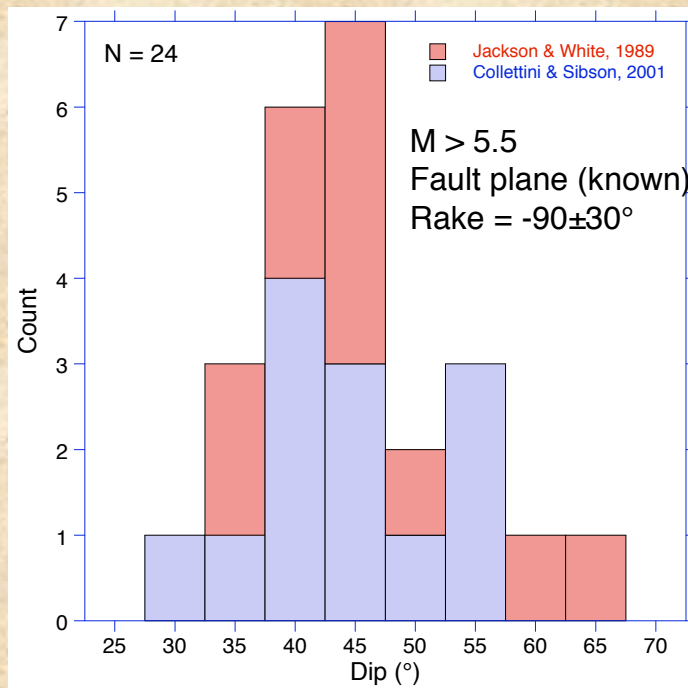
Jackson, White, 1989



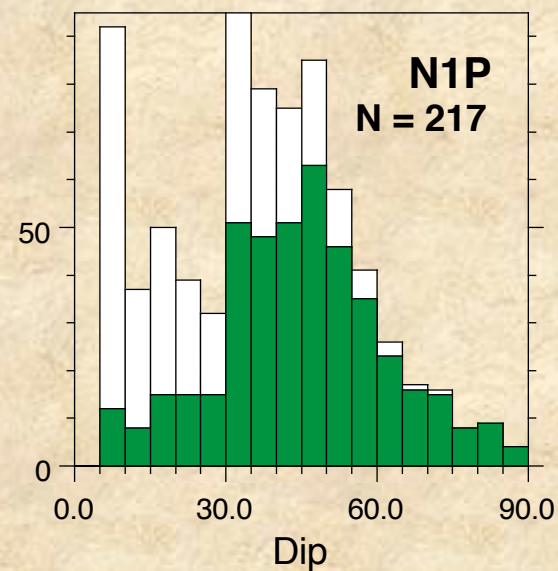
Wernicke, 1995



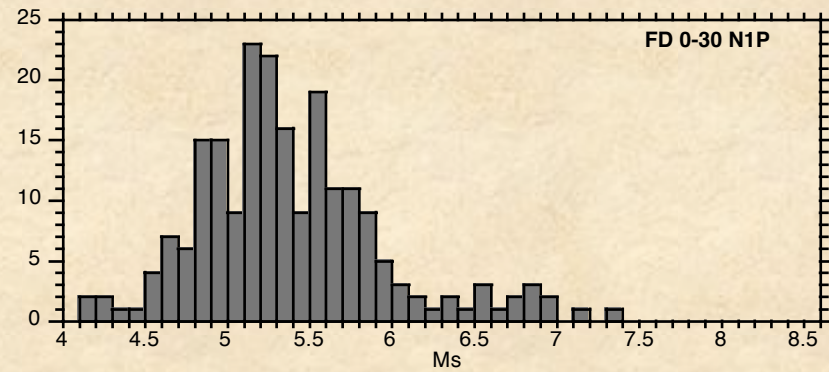
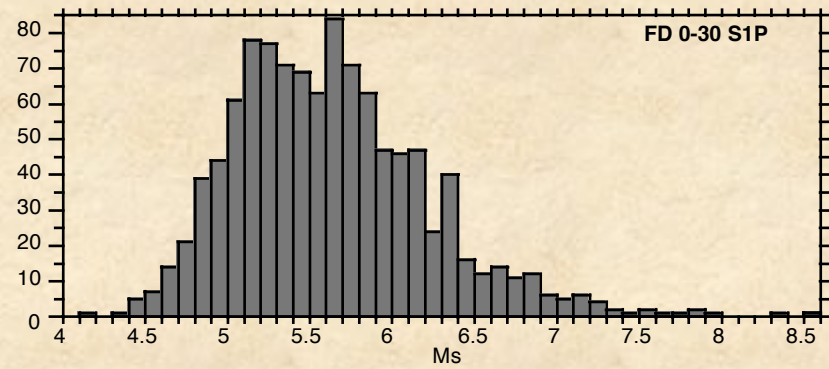
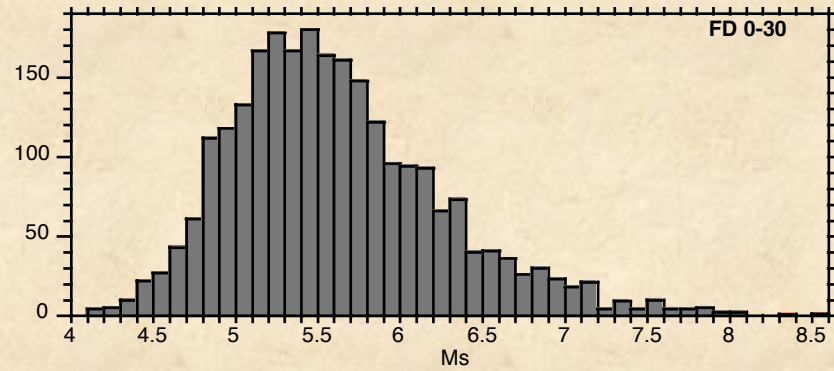
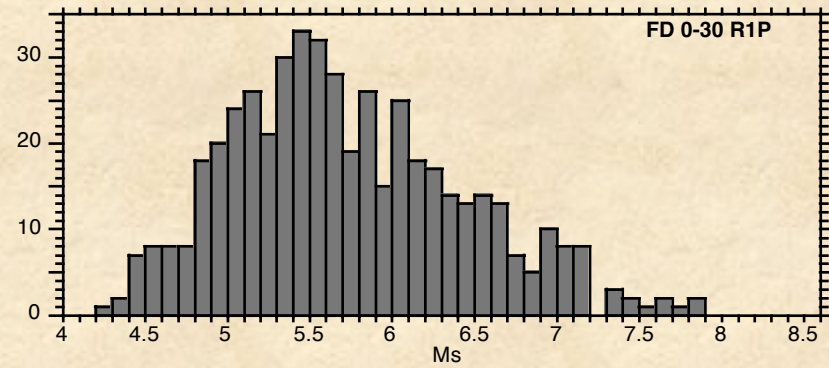
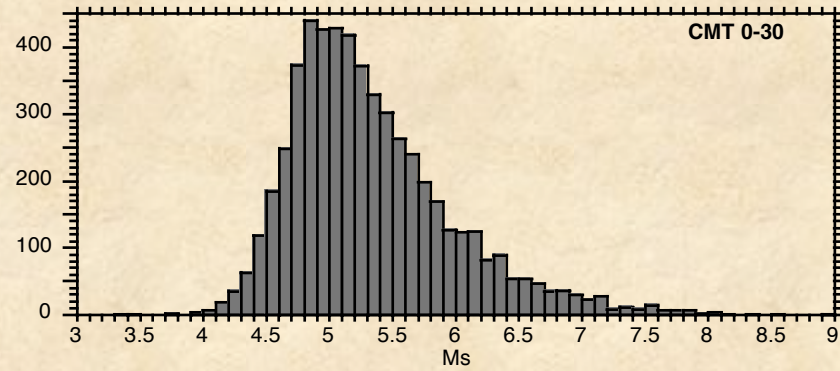
Colletini & Sibson, 2001



30-50°



Catalog completeness / Magnitudes



Conclusions

- Shallow earthquakes dominated by pure dip or strike slip events.
- Simplest interpretation: dominant 'near Anderson' faulting.
 - supports crustal strength hypothesis of Brace & Kohlstedt (1980) to crustal depths
- Dissymetry between normal and thrust events
- Thrust events compatible with Andersonian conditions but with $\varphi_0 = 40-60^\circ$.
- Normal events nodal planes dipping around 45° , suggesting $\varphi_0 \rightarrow 0^\circ$, $\varphi_0 = 0-30^\circ$.
- Highlights how much complete global catalogs can reveal
- How much more could be learnt from catalog complete to lower magnitude ($x10/M$), more precise depth determinations and fault plane identification.