

Experimental study of the role of heterogeneities in the rupture propagation

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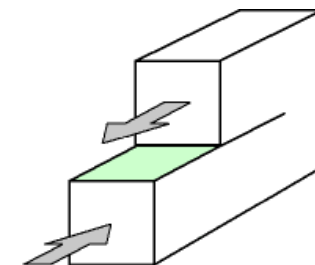
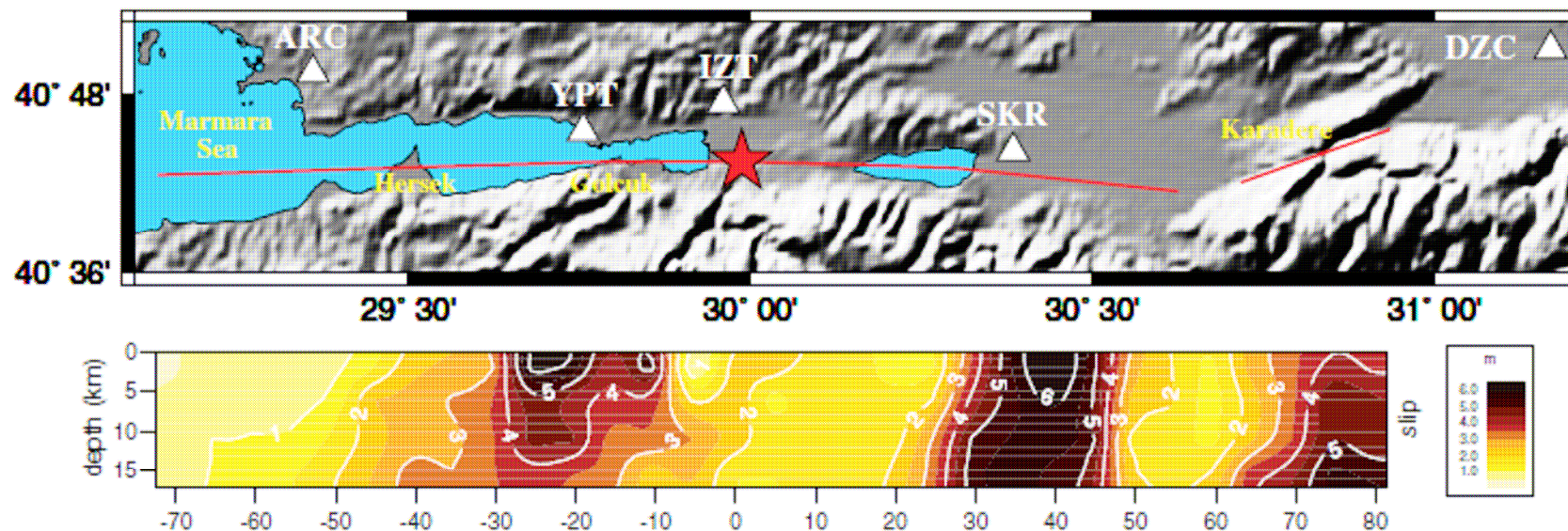
Olivier Lengliné (*IPG Strasbourg, 2009*)

Guillaume Daniel (*IPG Strasbourg, 2008*)

Technical support

Alain Steyer

Rupture observation

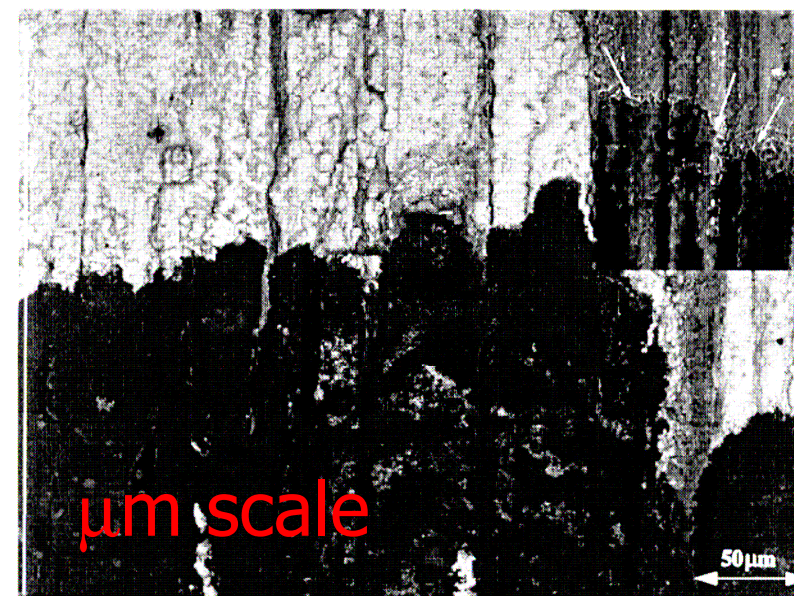
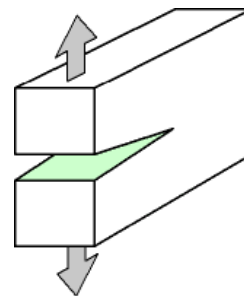


mode II
(shear)

Slip distribution of 1999 Izmit, Turkey, earthquake
Bouchon et al. (BSSA, 2002)

Fracture interface
Bouchaud (J. Phys, 1997)

mode I
(opening)

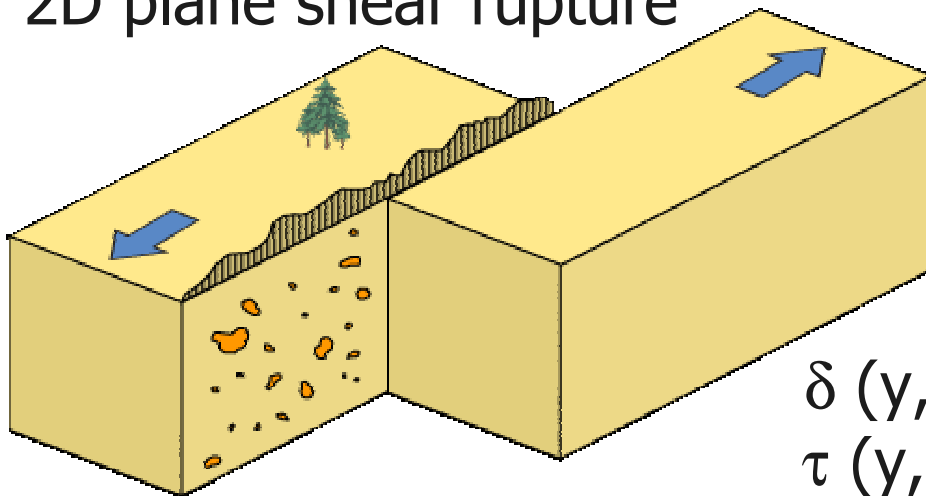


Rupture modelisation

In both cases:

- Fractures along favoured surfaces \Rightarrow weak planes
- Fluctuations of mechanical properties along plane
- Rough shape of coseismic slip and rupture front

2D plane shear rupture



τ = shear stress

$$\delta(y,t) \leftrightarrow a(x,t)$$

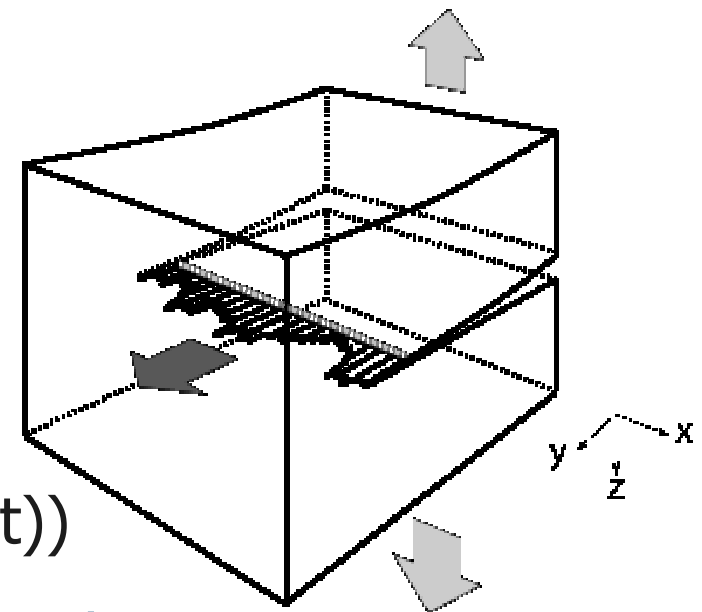
$$\tau(y,t) \leftrightarrow G(x,t)$$

$$\tau_c(y, \delta(y,t)) \leftrightarrow G_c(x, a(x,t))$$

Gao & Rice (J. Appl. Mech., 1989)

Schmittbuhl et al. (PAG, 2003)

Mode I interfacial crack



G = fracture energy

- Can fracture mechanics be inferred from analysis of crack front morphology ?
- What are the links between small and large scales ?
- Can small scale heterogeneities lead to large scale heterogeneities ?
- How do heterogeneities influence rupture propagation ?

- To try to answer these questions:
 - ⇒ Optical and acoustic monitoring of a crack propagation along a heterogeneous interface
 - ⇒ Analysis of fixed crack front morphology at high spatial resolution
 - ⇒ Analysis of crack front dynamics during its propagation

Outlines

- Issue
 - Morphology of fracture fronts
 - Dynamics of rupture propagation
- Experimental setup
- Results on morphology
 - scaling analysis \Rightarrow self-affinity of crack fronts
- Results on dynamics
 - scaling law distributions of velocities and acoustic emissions (AE)
- Comparison between experimental and large scale data
 - clustering of events in both cases
- Conclusions and perspectives

Experimental setup

micro-
scope

force
sensor

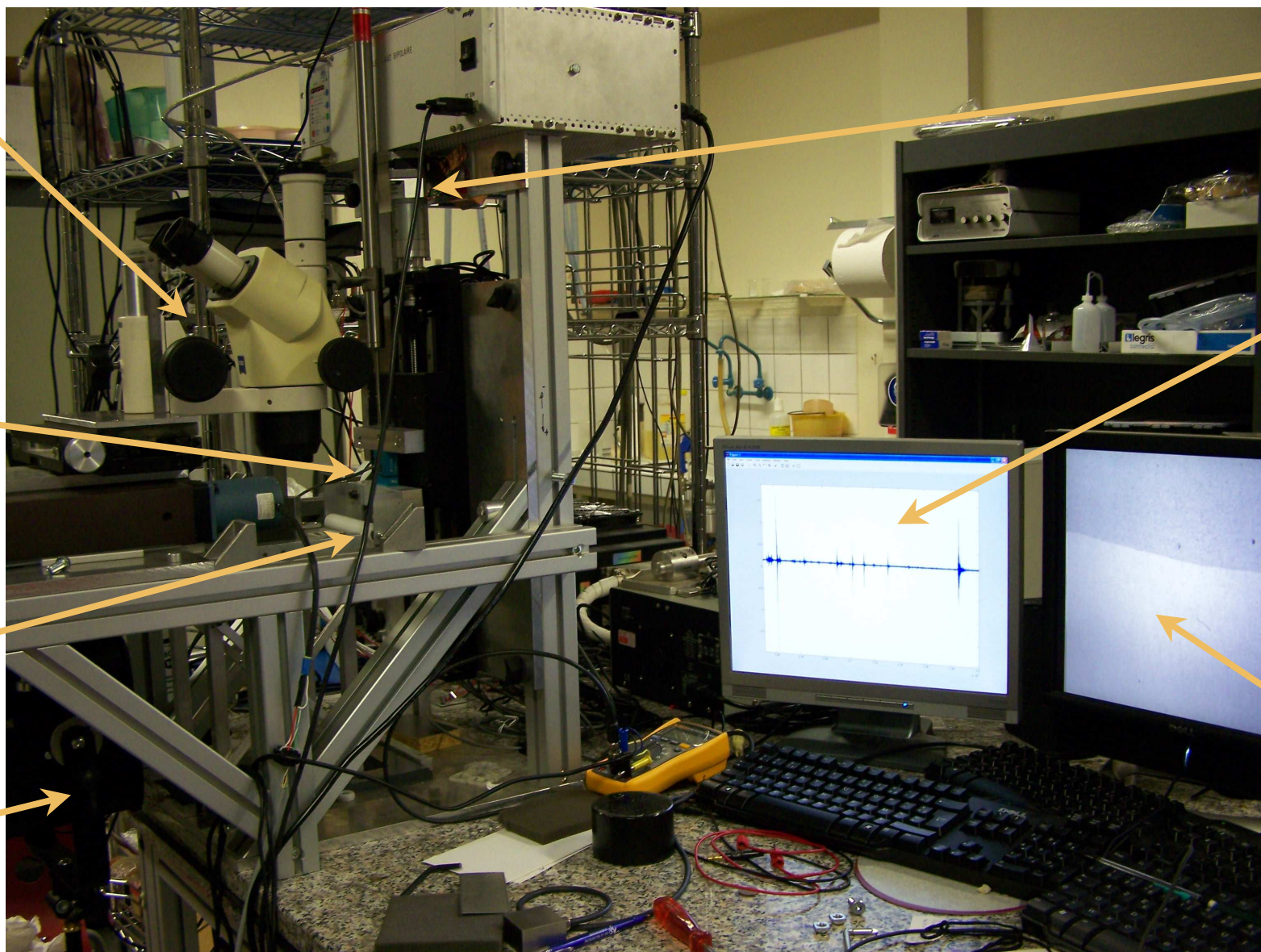
press

lighting

motor

AE
signal

front
images



Experimental setup

microscope

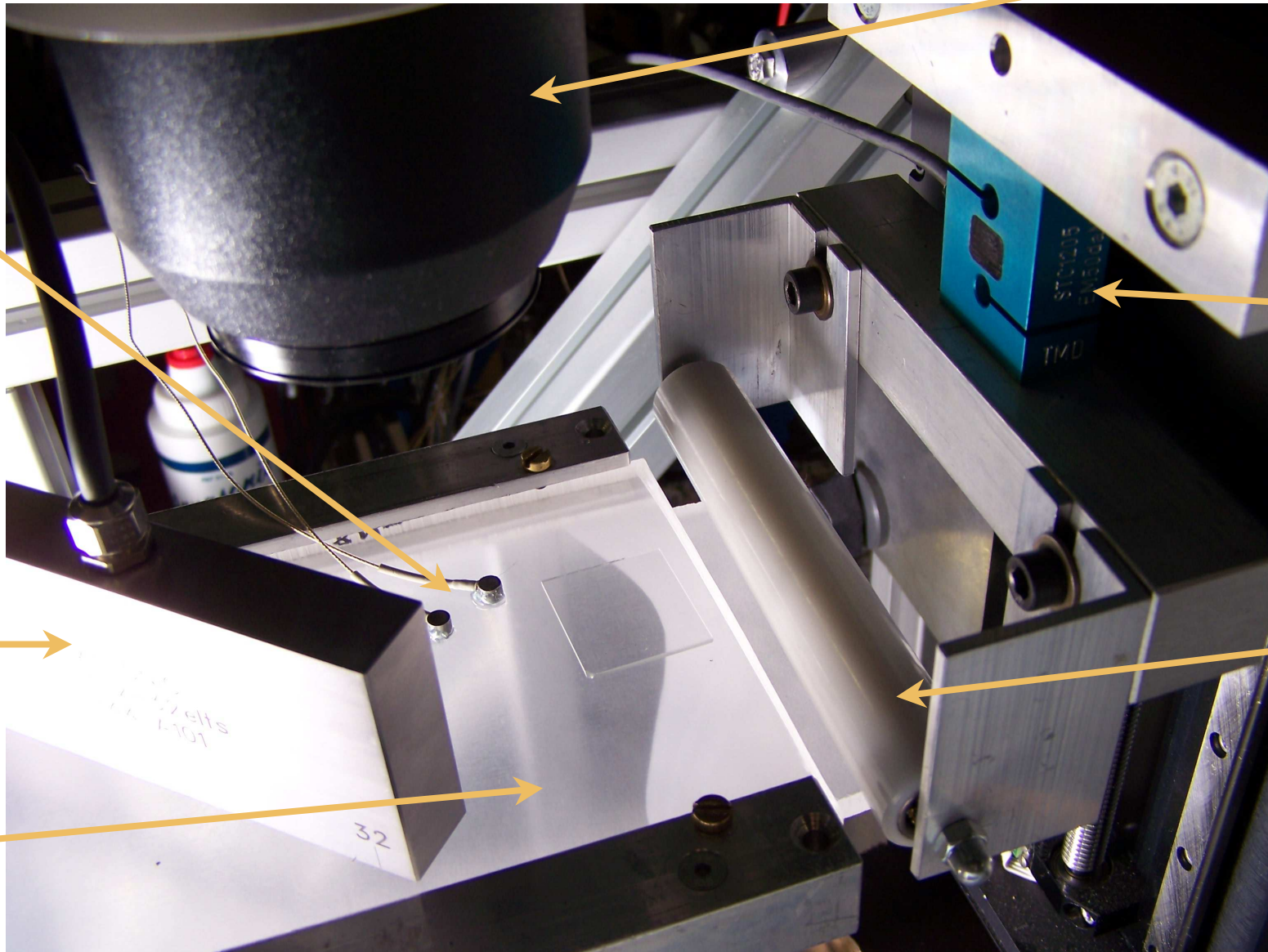
acoustic
sensors

force
sensor

linear
array of
acoustic
sensors

press

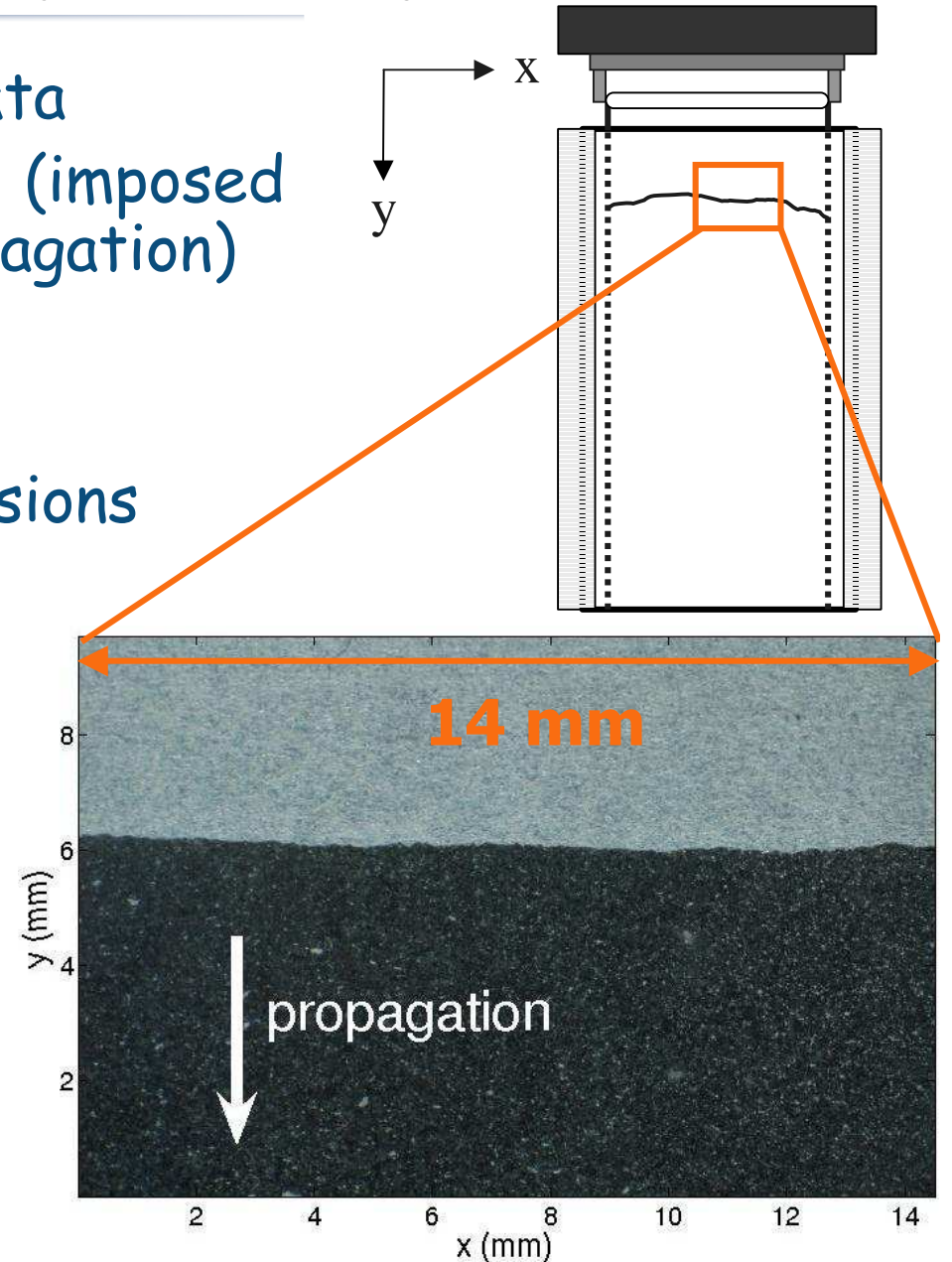
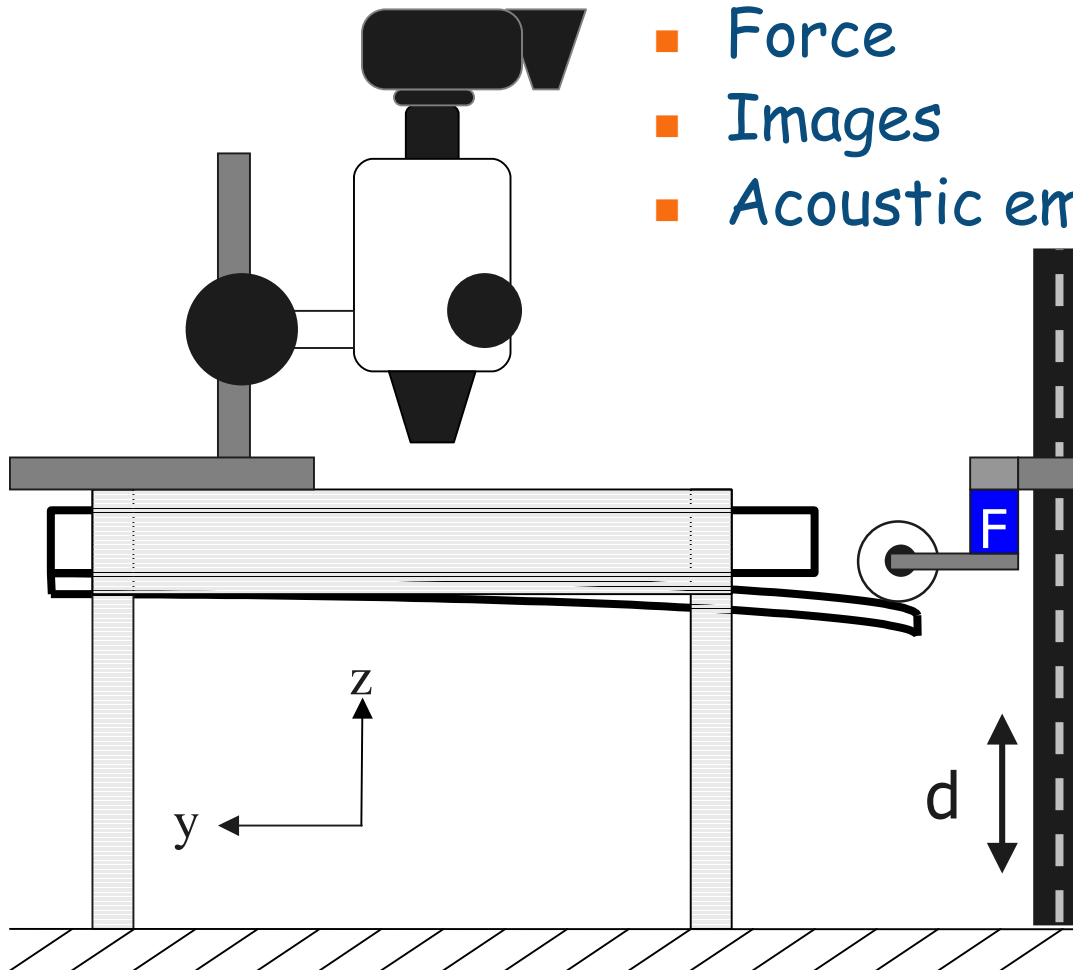
sample



Experimental setup

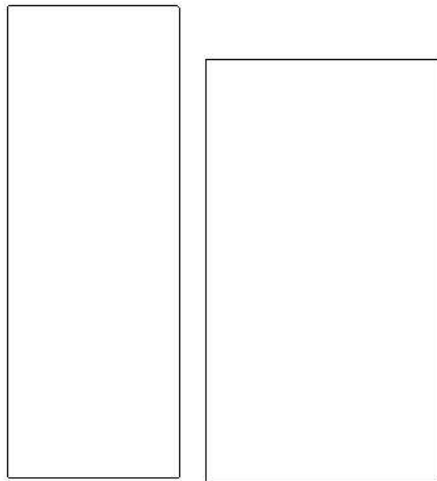
4 observation data

- Displacement (imposed \Rightarrow stable propagation)
- Force
- Images
- Acoustic emissions

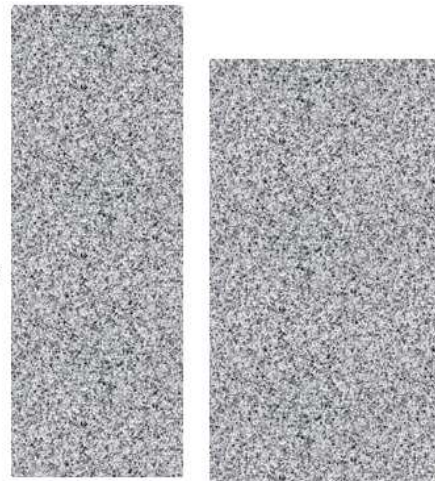


Sample preparation

Plexiglas plates



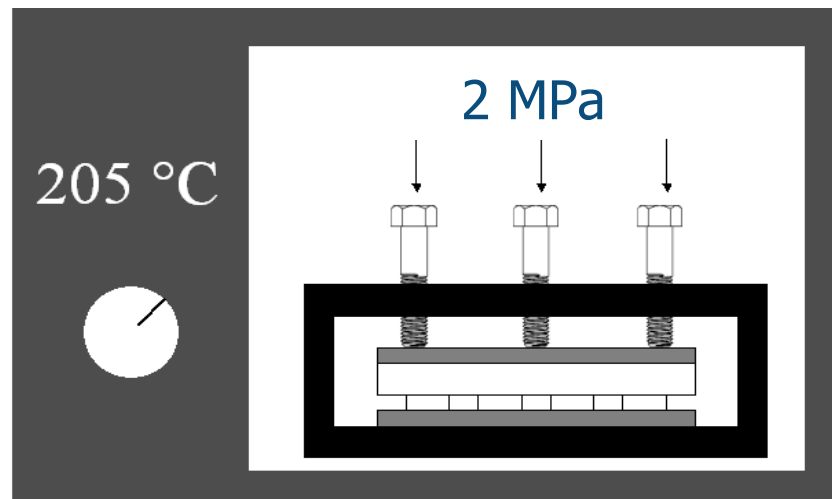
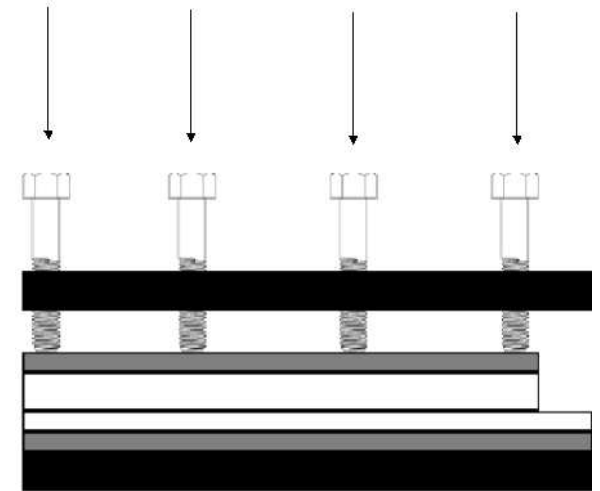
disorder introduction



superposition



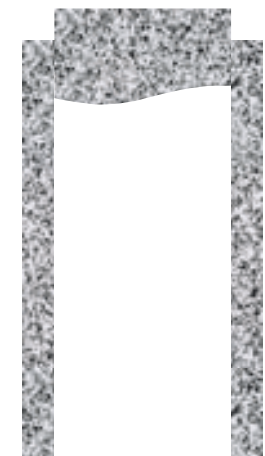
$\sigma_N = 2 \text{ MPa}$



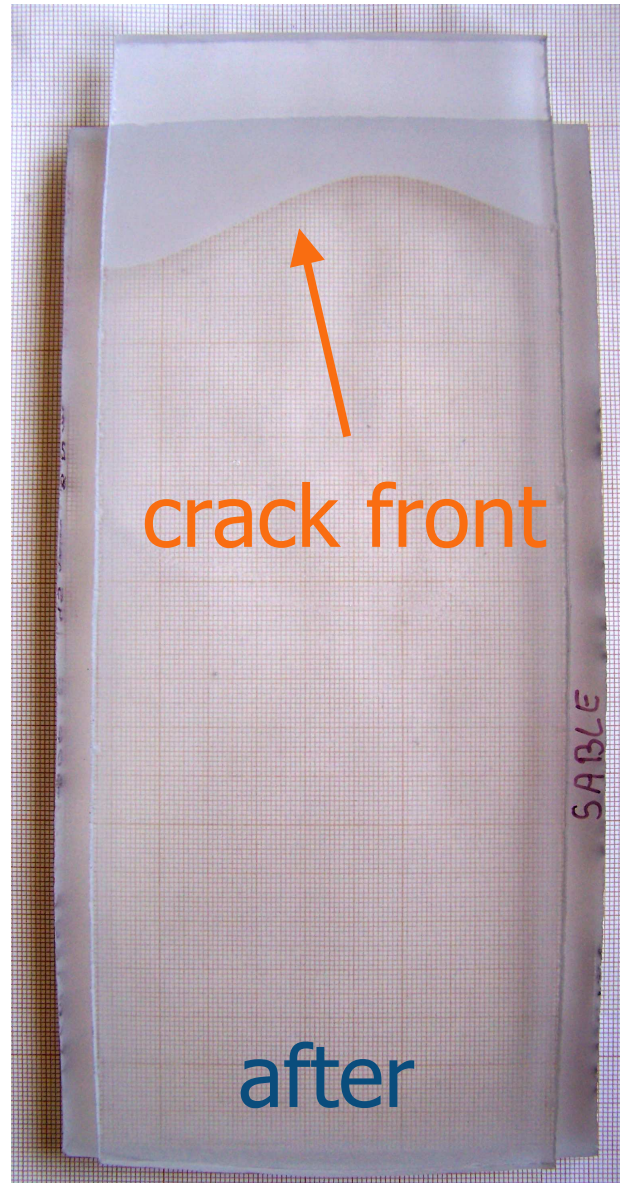
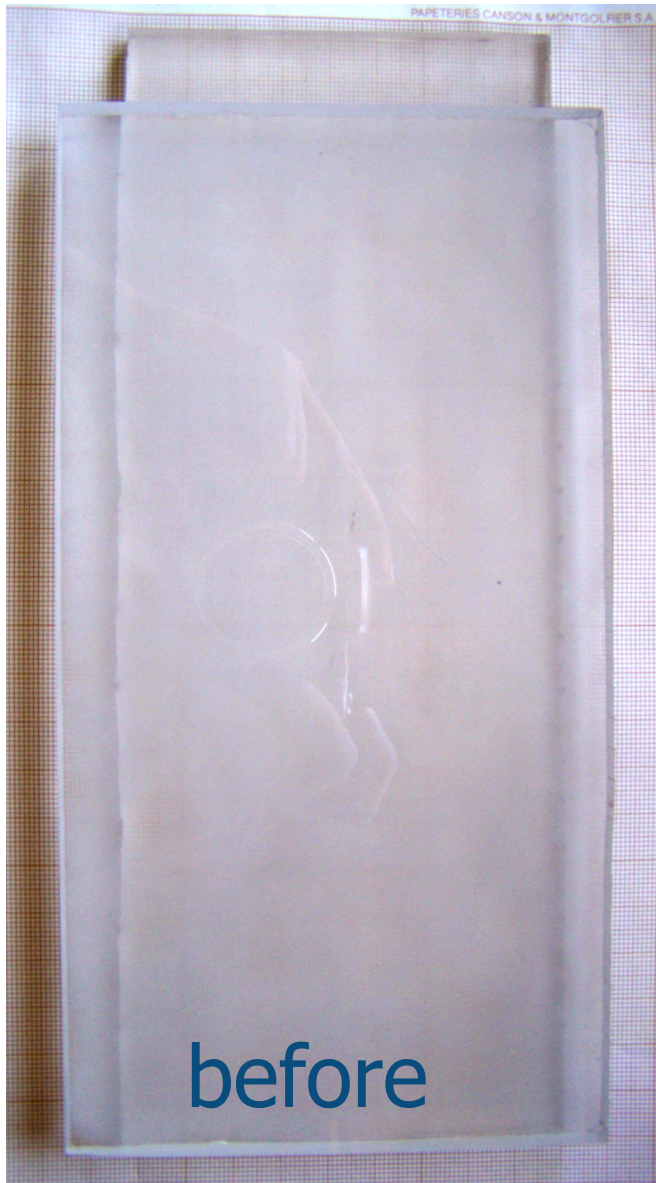
annealing



opening

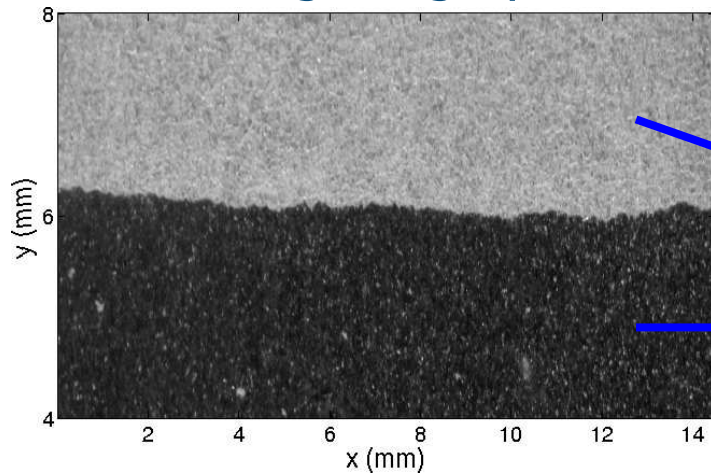


Sample preparation

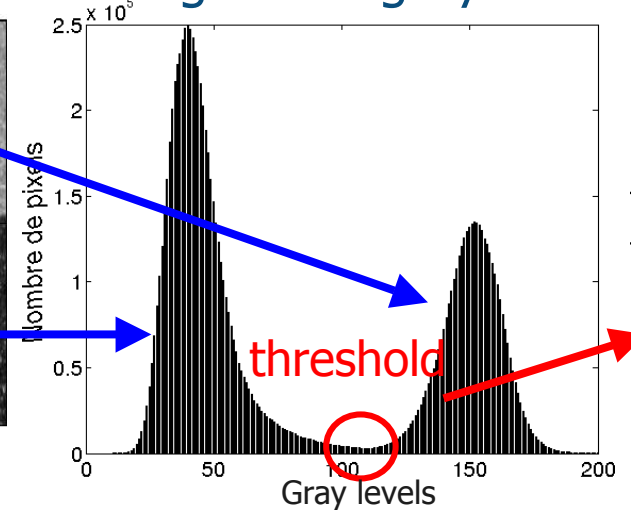


Front extraction

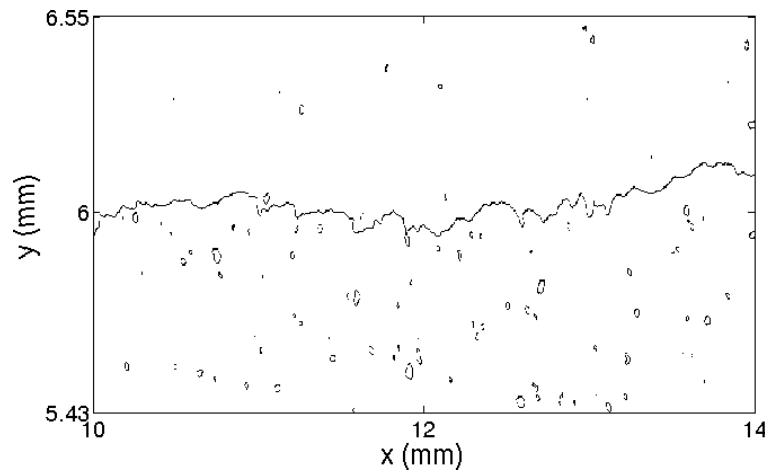
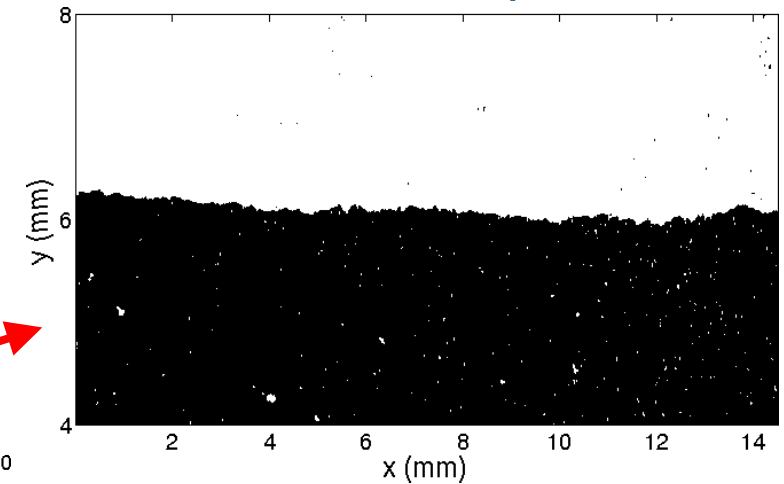
image in gray



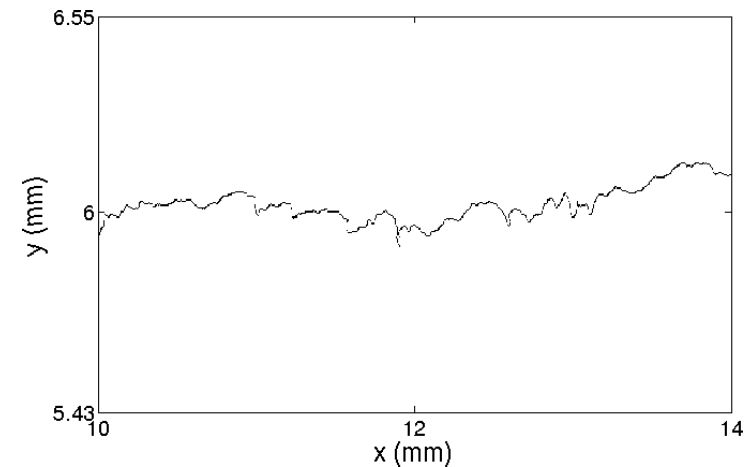
histogram of gray levels



thresholded picture

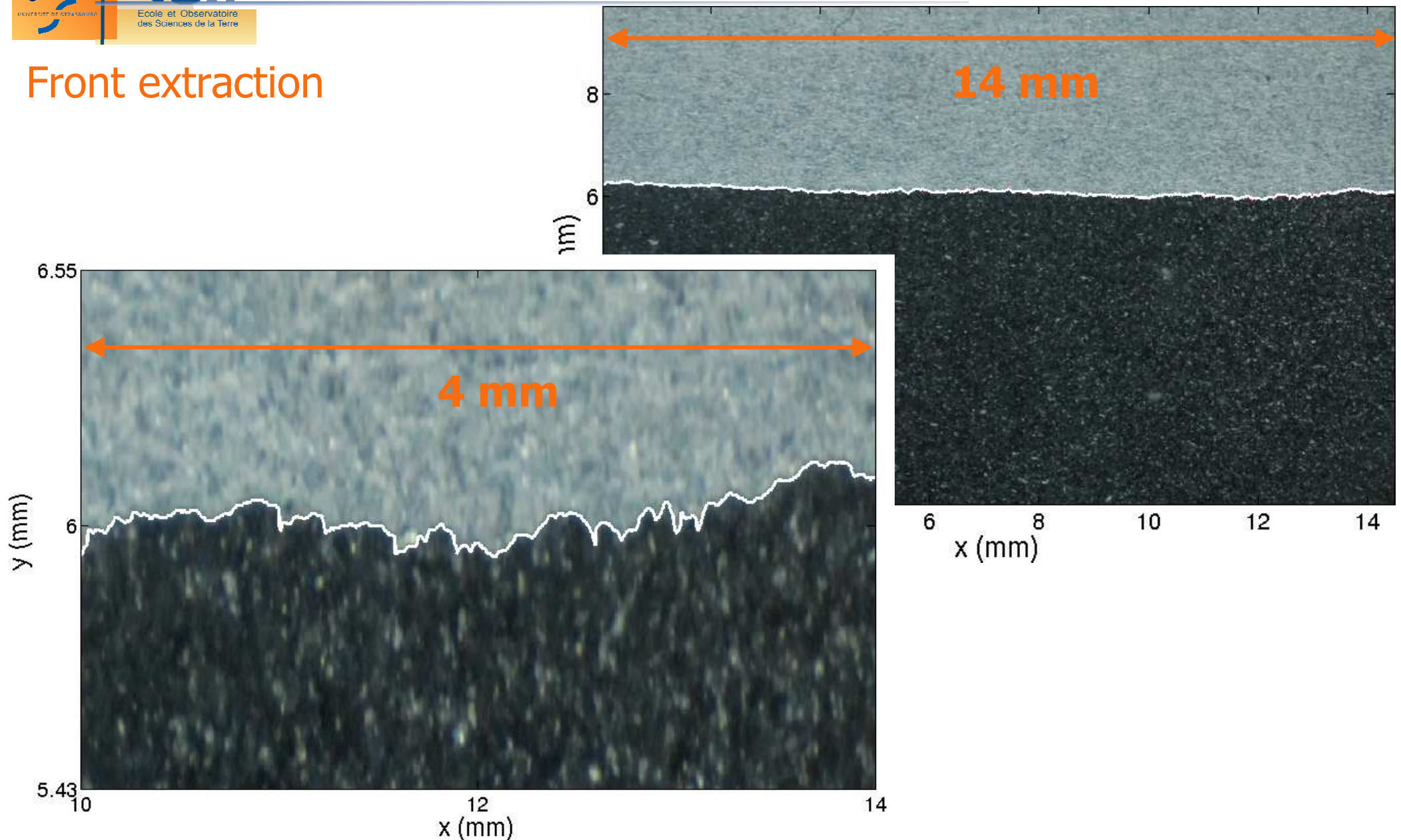


norm of gradient



front extracted

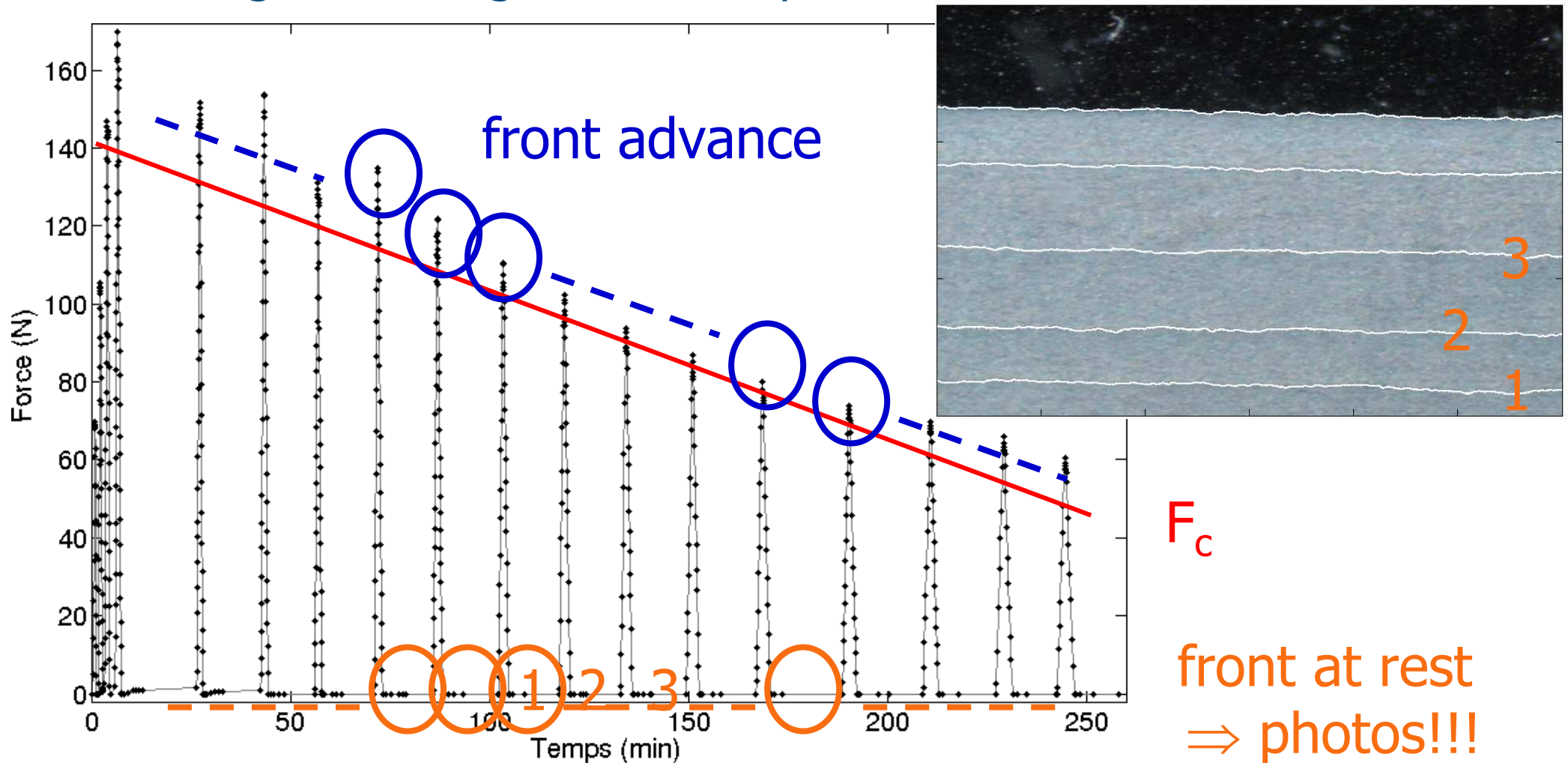
Front extraction



Static experiments

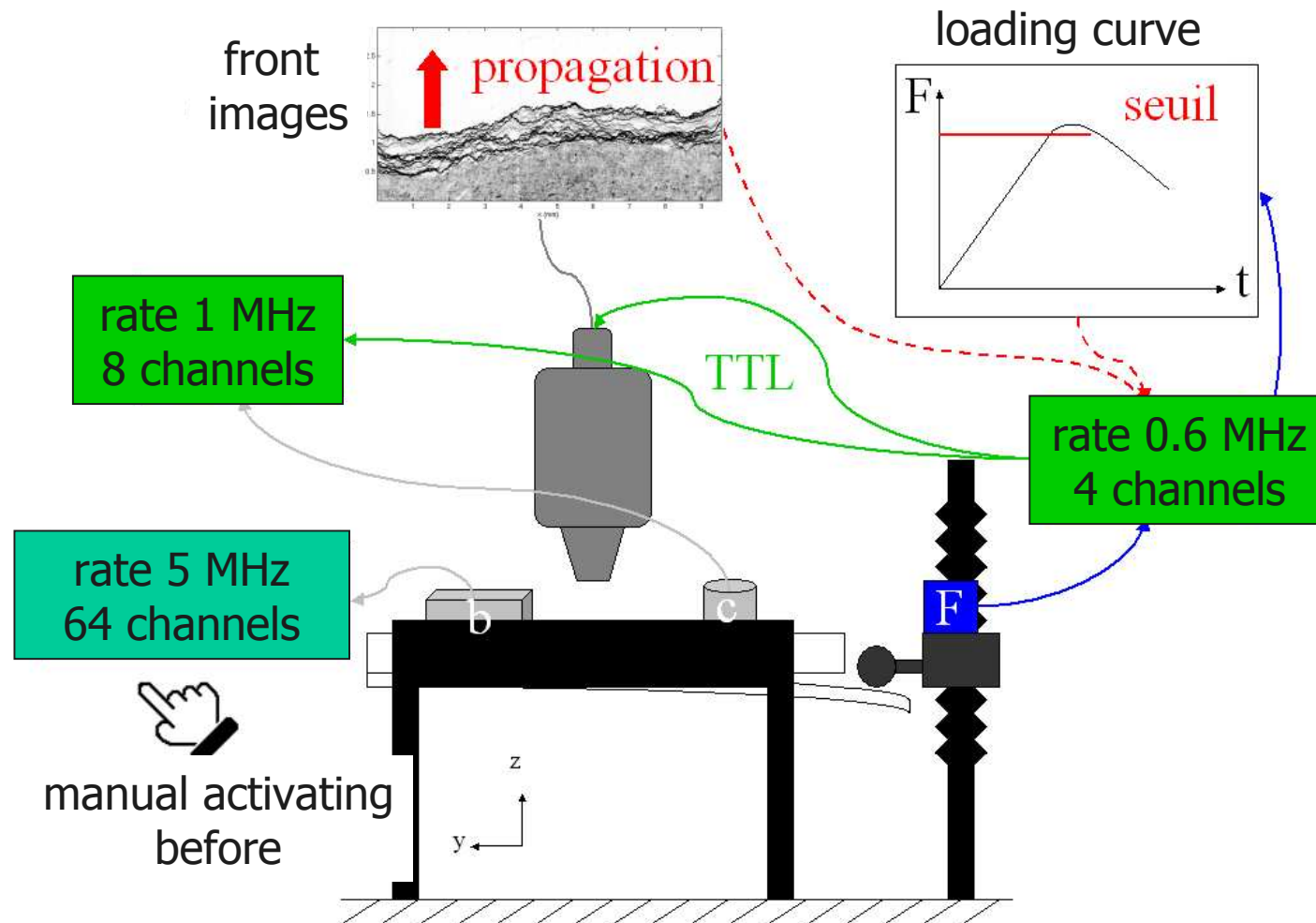
Loading to make front advance

Unloading to take high resolution pictures of front at rest

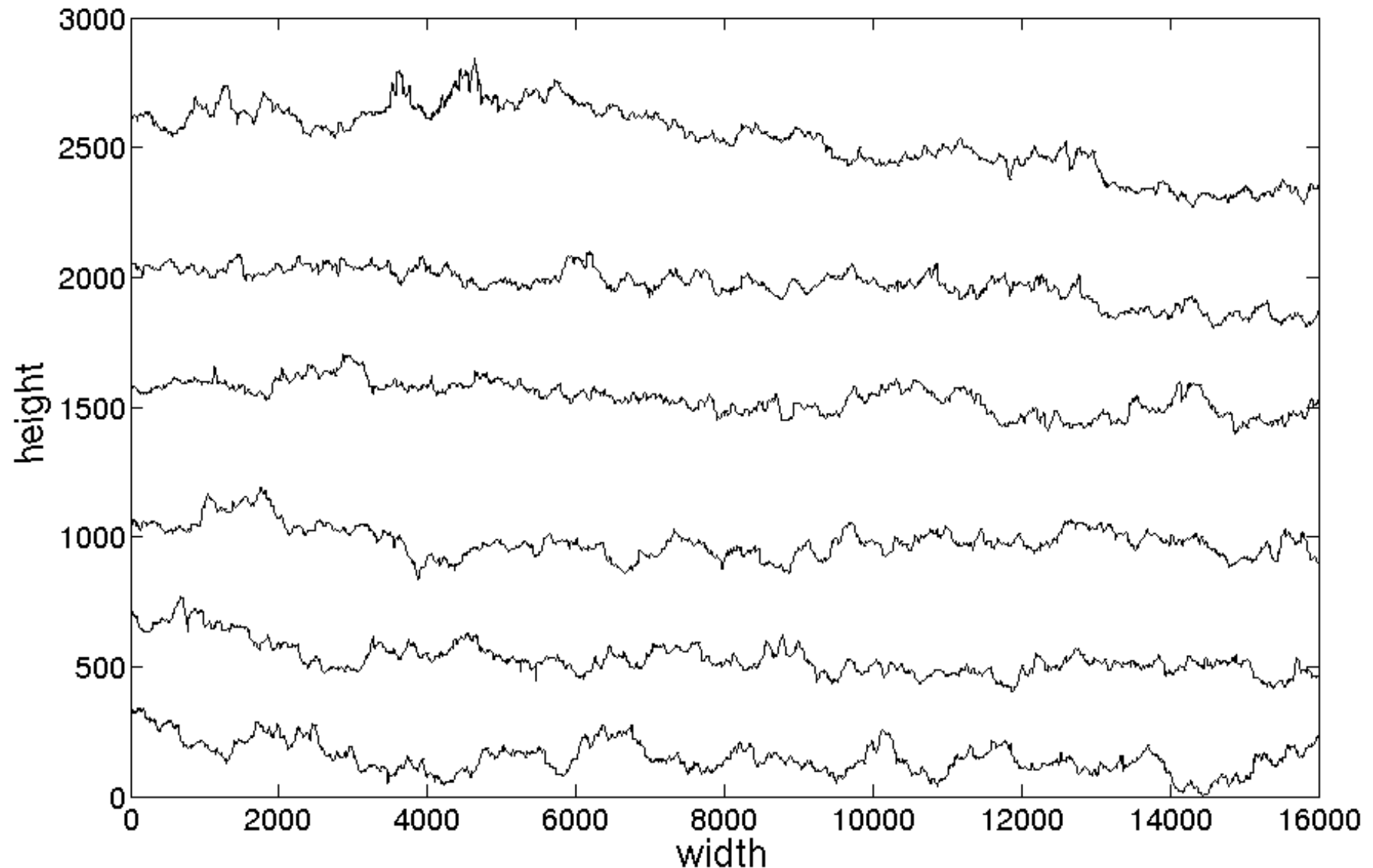


Dynamic experiments

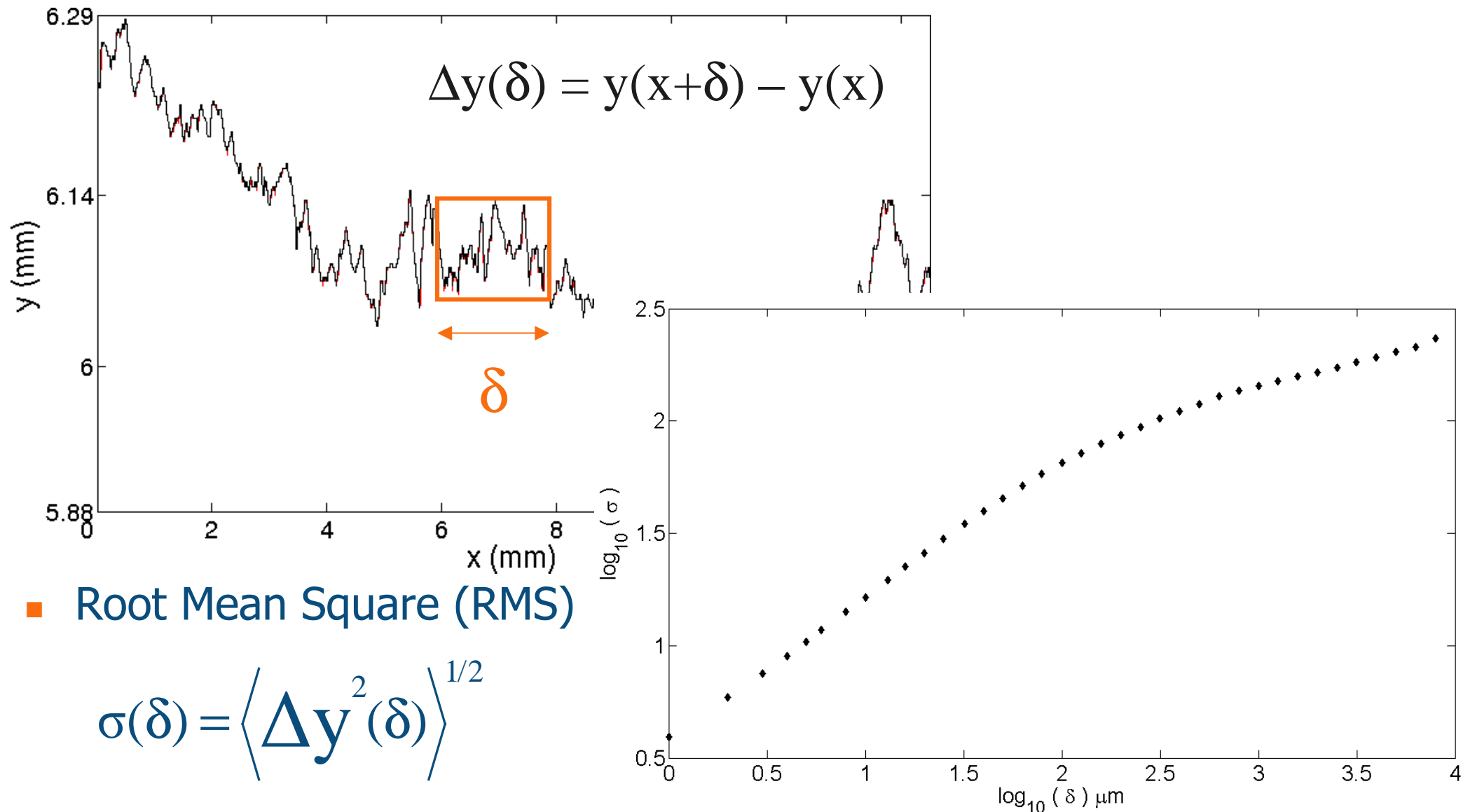
Loading for the duration of experiment at constant speed
 Lots of images taken at high acquisition rate (≈ 1000 frames / s)



Front morphology analysis



Roughness measurement

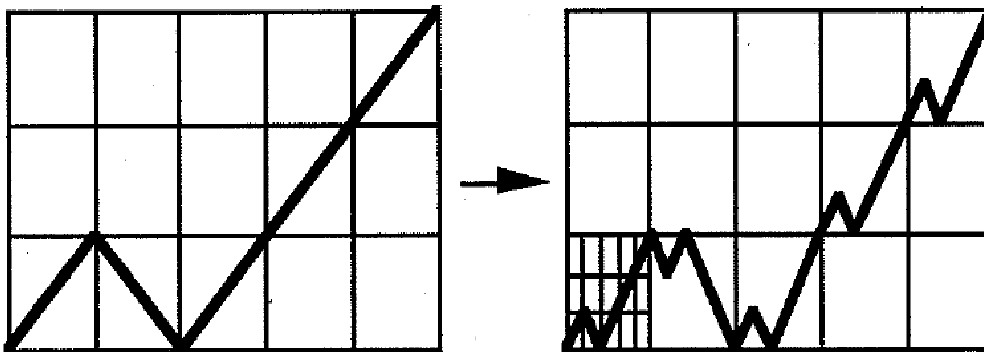


Roughness measurement

Scaling law

⇒ Self-affine structure = front shape statistically invariant under an affine transformation

$$d_x \rightarrow \lambda_x d_x, d_y \rightarrow \lambda_y d_y$$



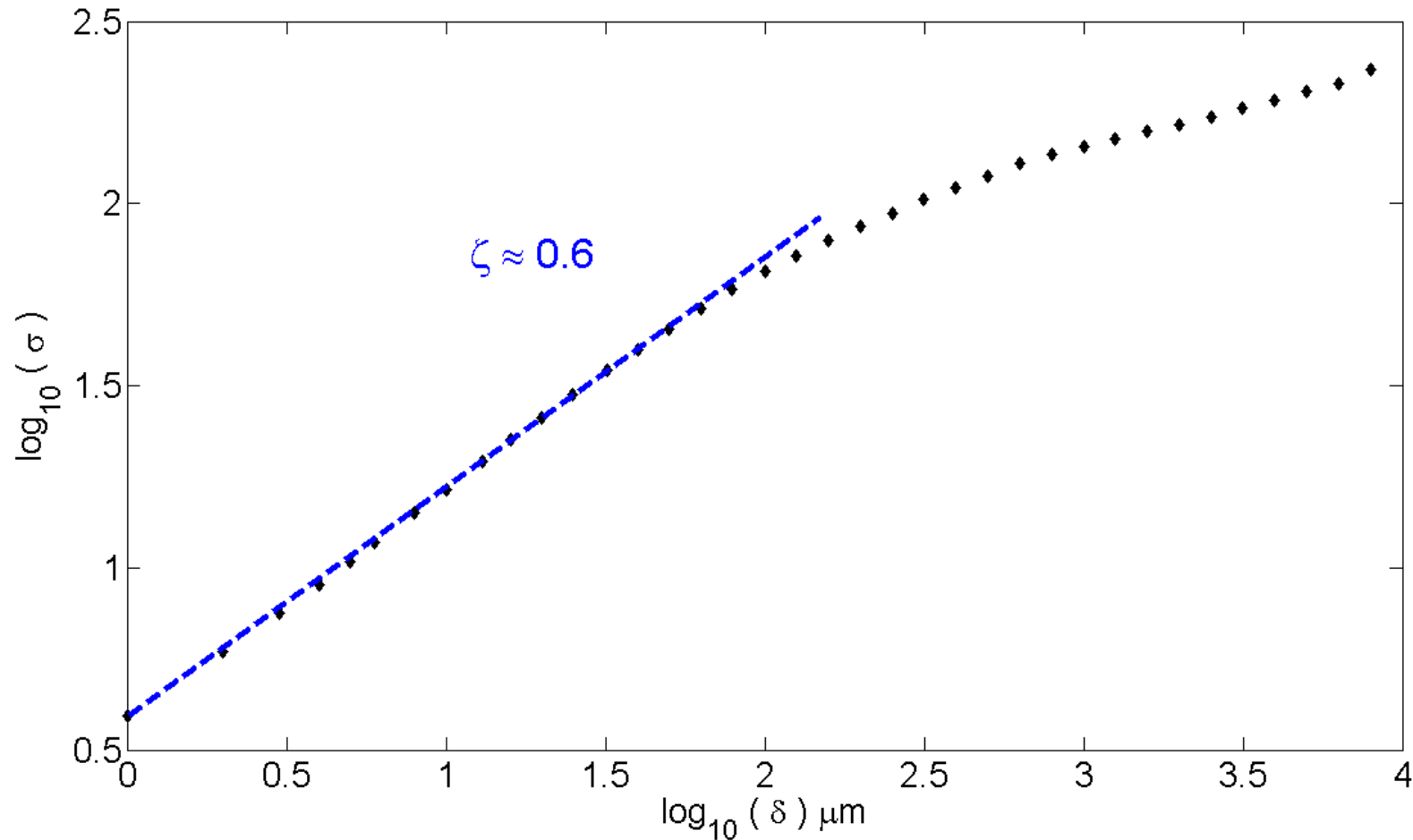
$$\lambda_y = \lambda_x^\zeta$$

roughness
exponent

⇒ Determination of a roughness exponent ζ

$$\langle \sigma(\delta) \rangle_{x_0} \propto \delta^\zeta$$

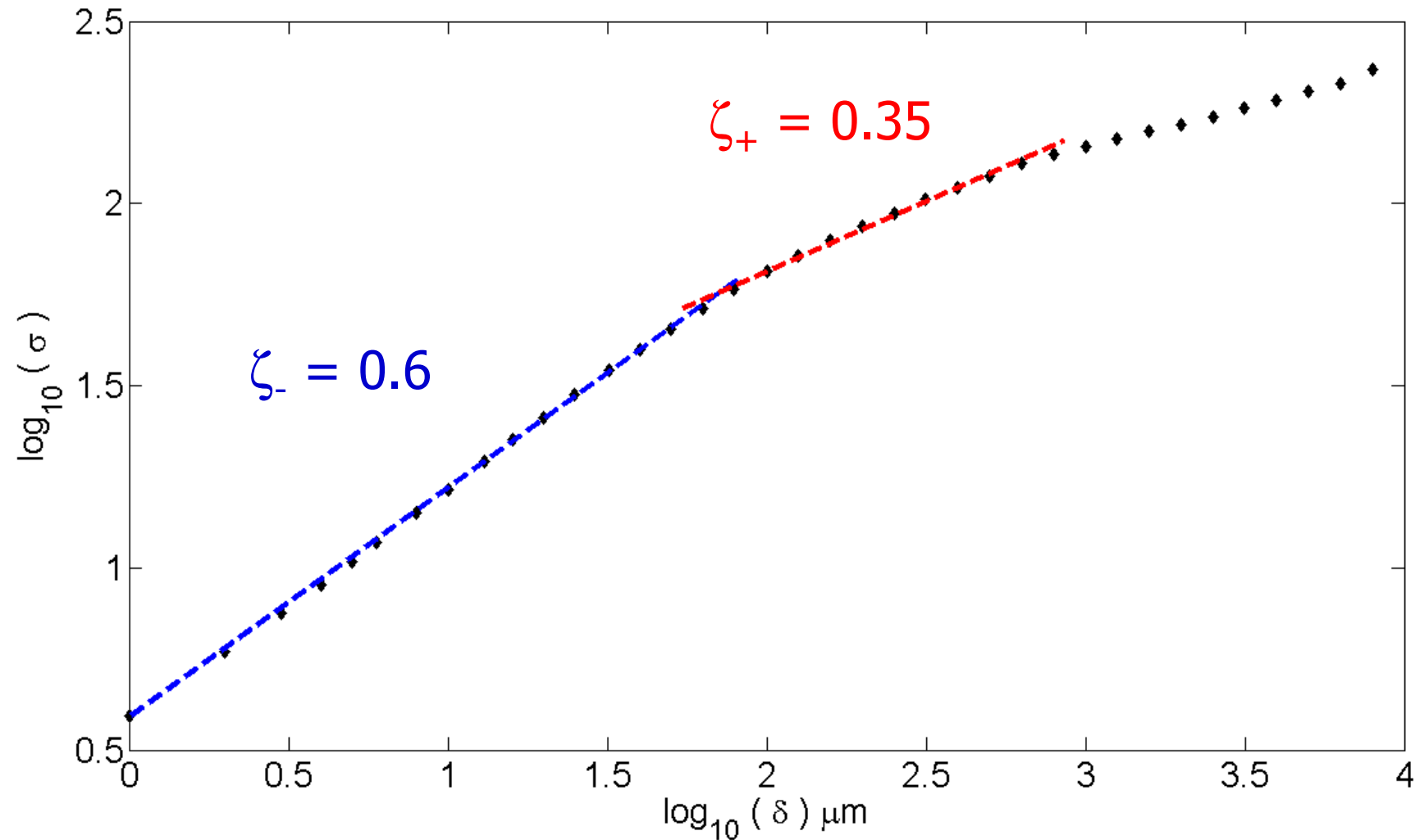
Roughness measurement



Måløy & Schmittbuhl (PRL, 1997)

Delaplace et al. (1999)

Roughness measurement



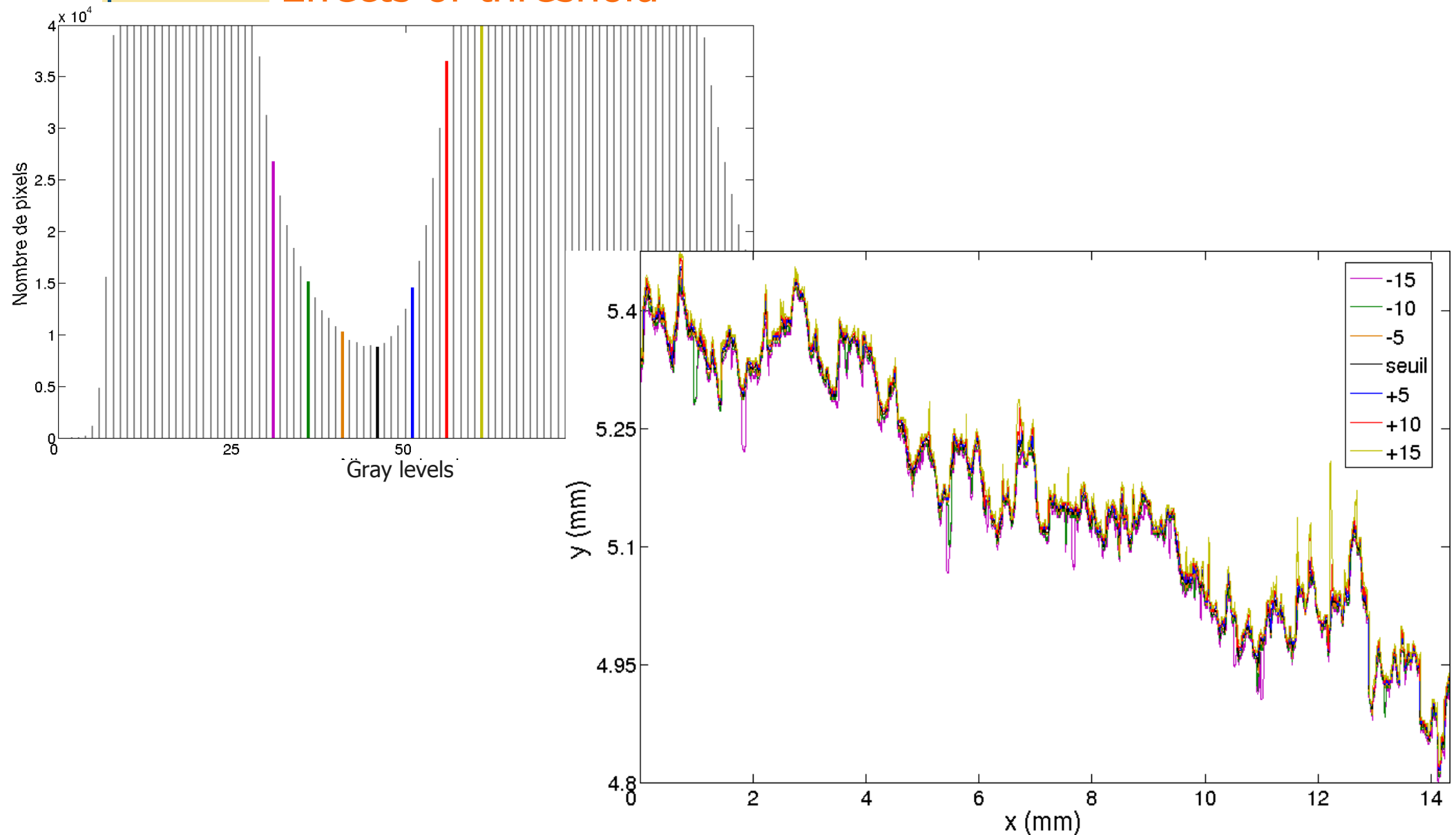
\Rightarrow 2 roughness exponents

Roughness measurement

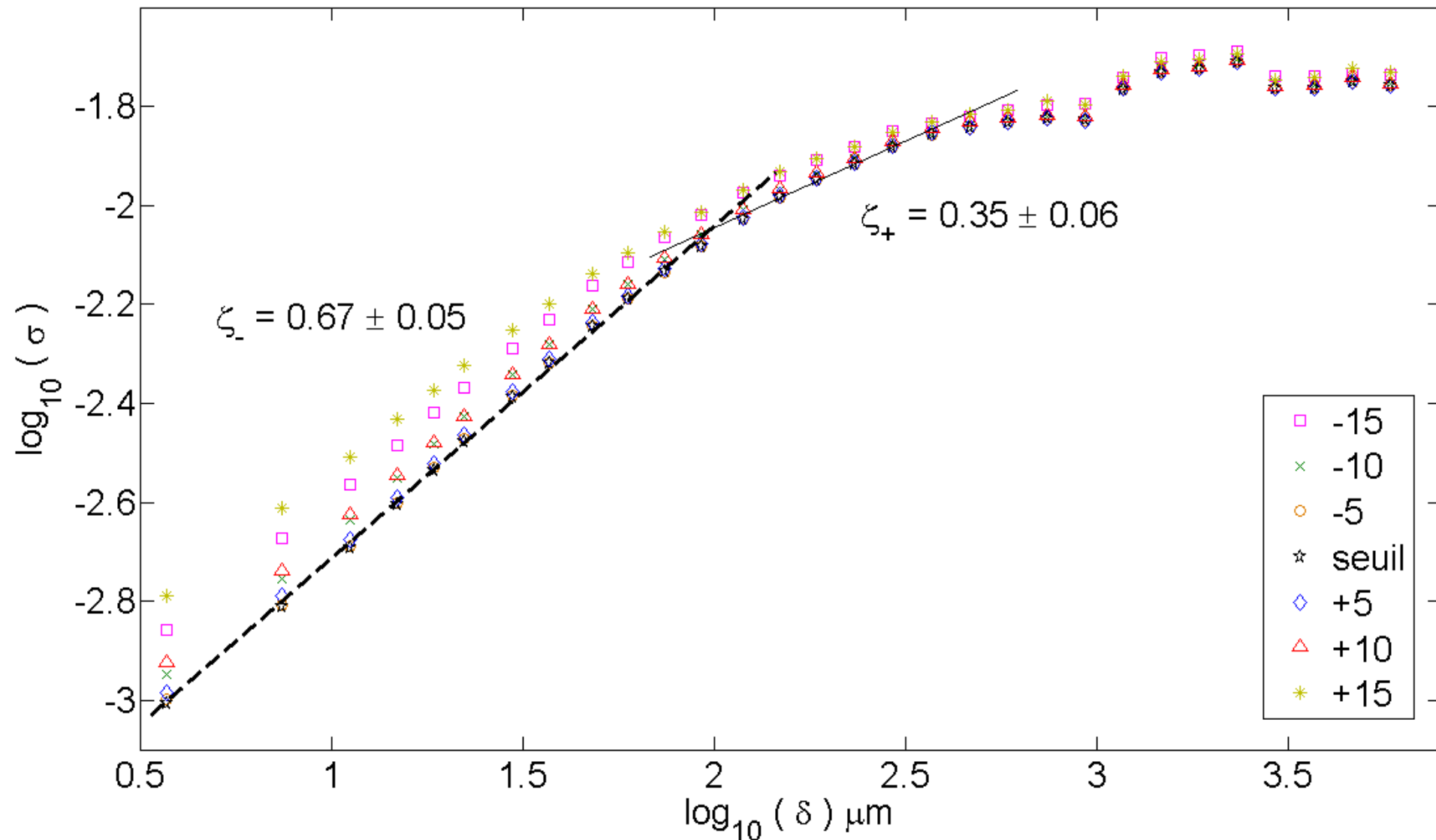
Result independent of parameters from:

- Image processing (threshold value for front extraction...)
- Optical acquisition (resolution = images taken with different magnifications of the microscope...)
- Disorder introduction procedure (sand-blasting with various beads, chemical...)
- Statistical method used to analyse the front morphology

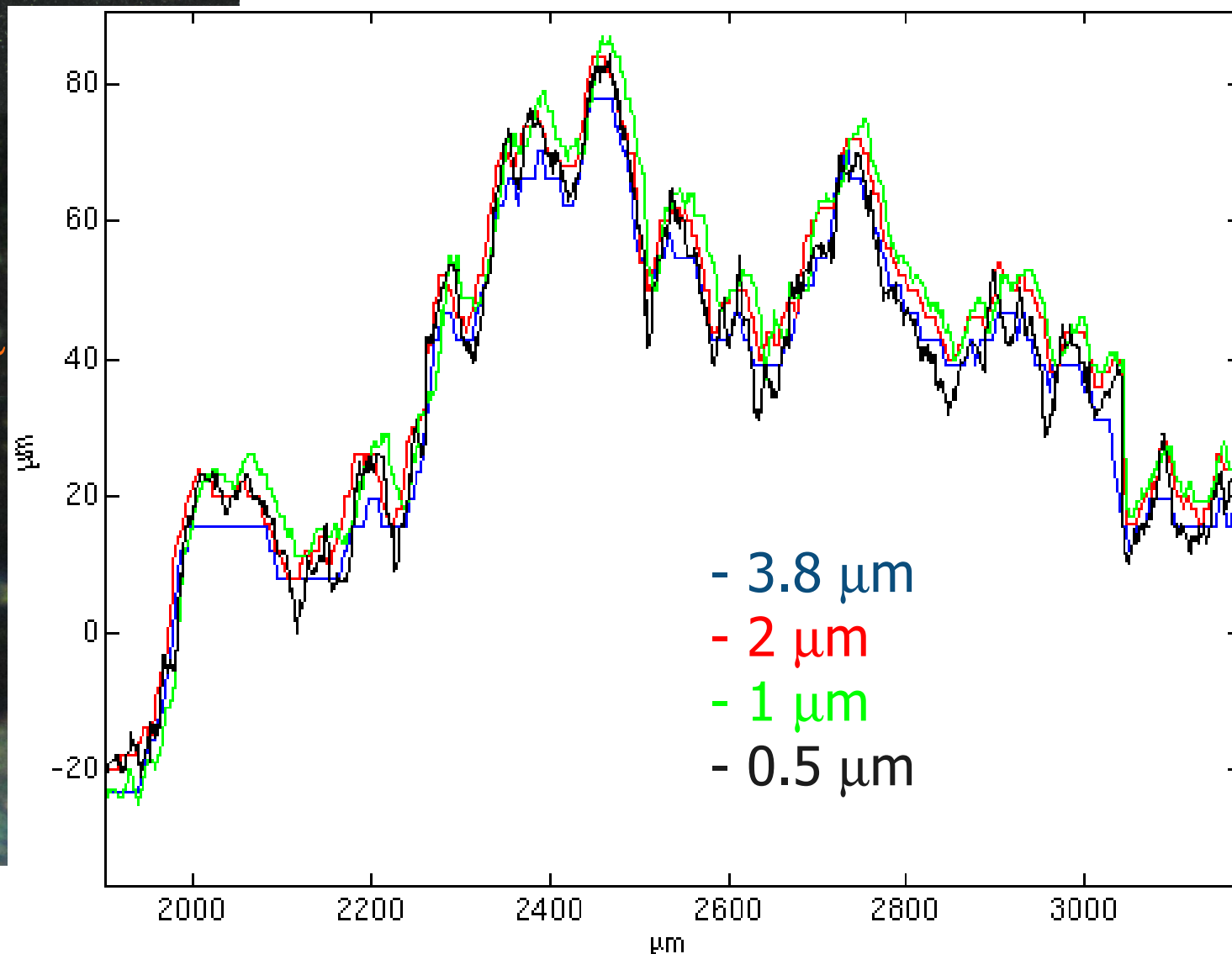
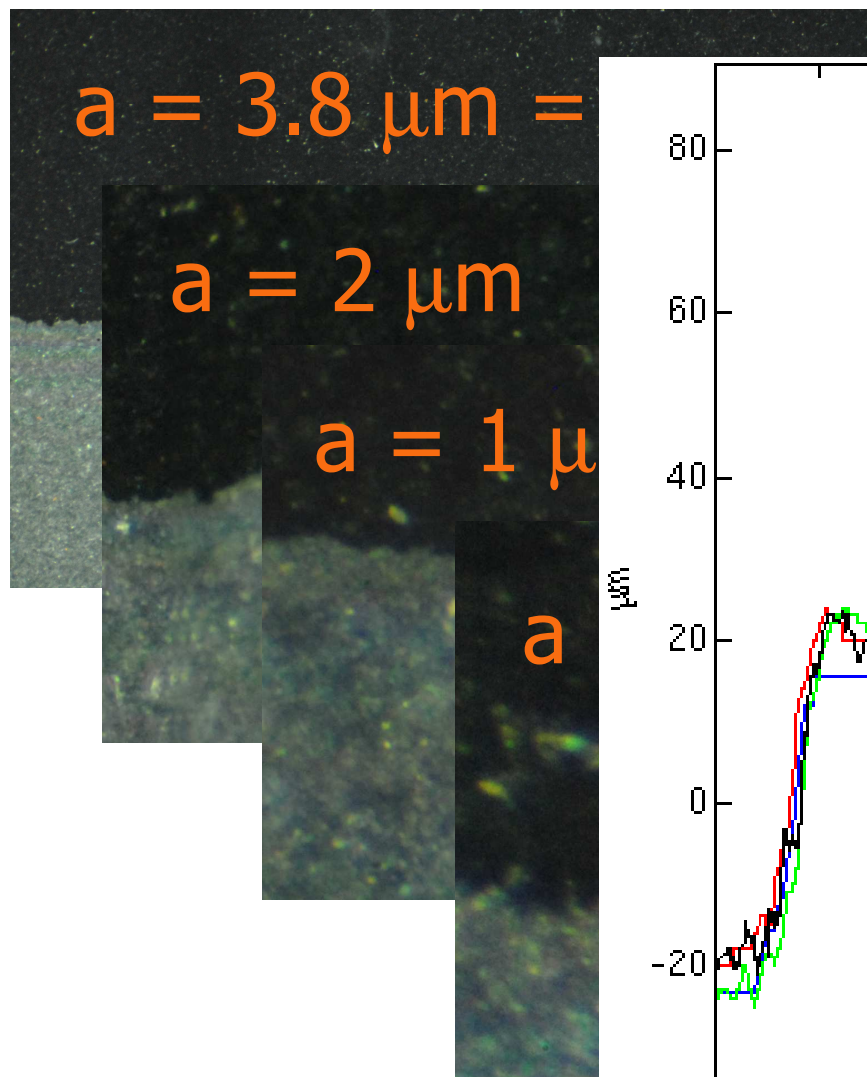
Effects of threshold



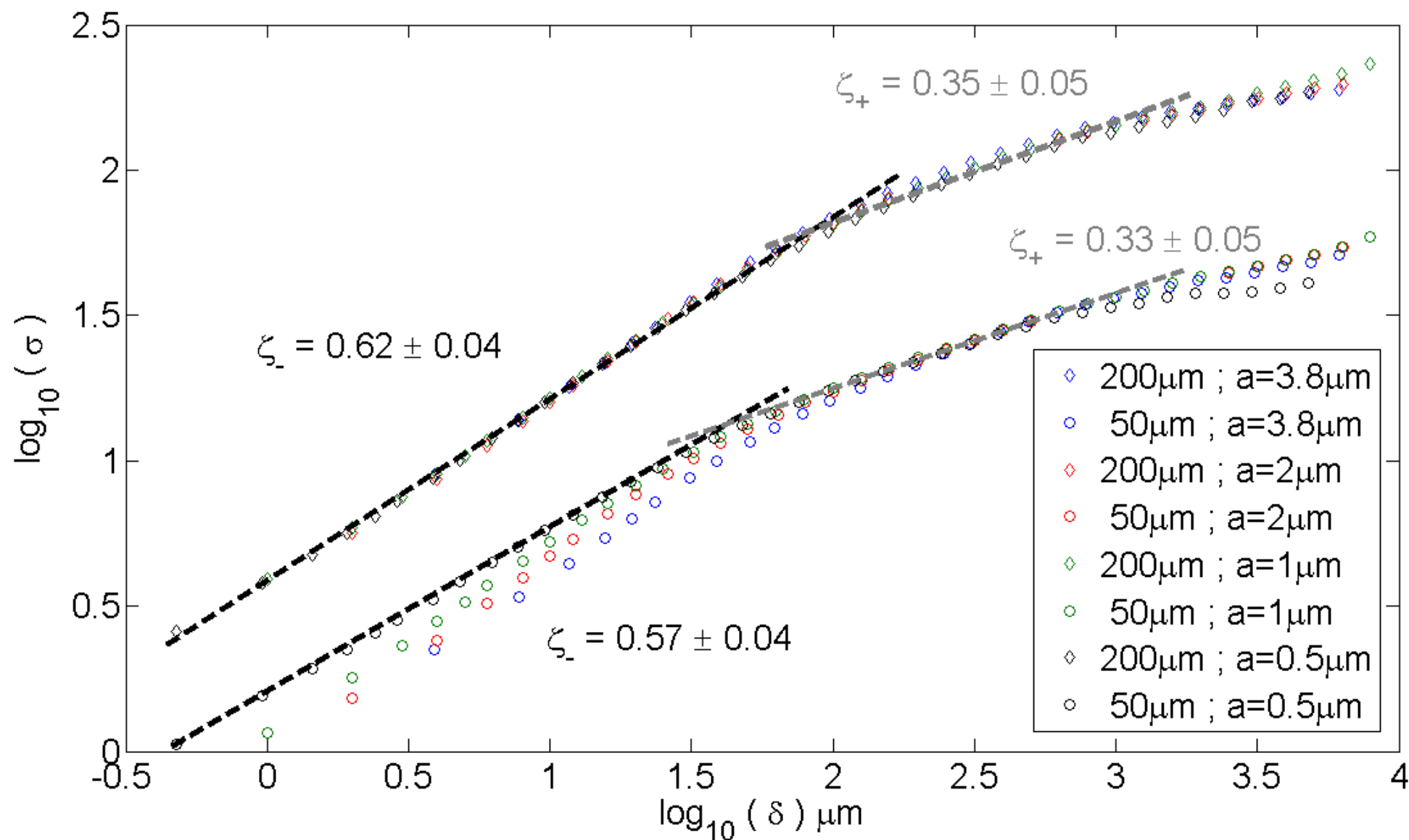
Effects of threshold



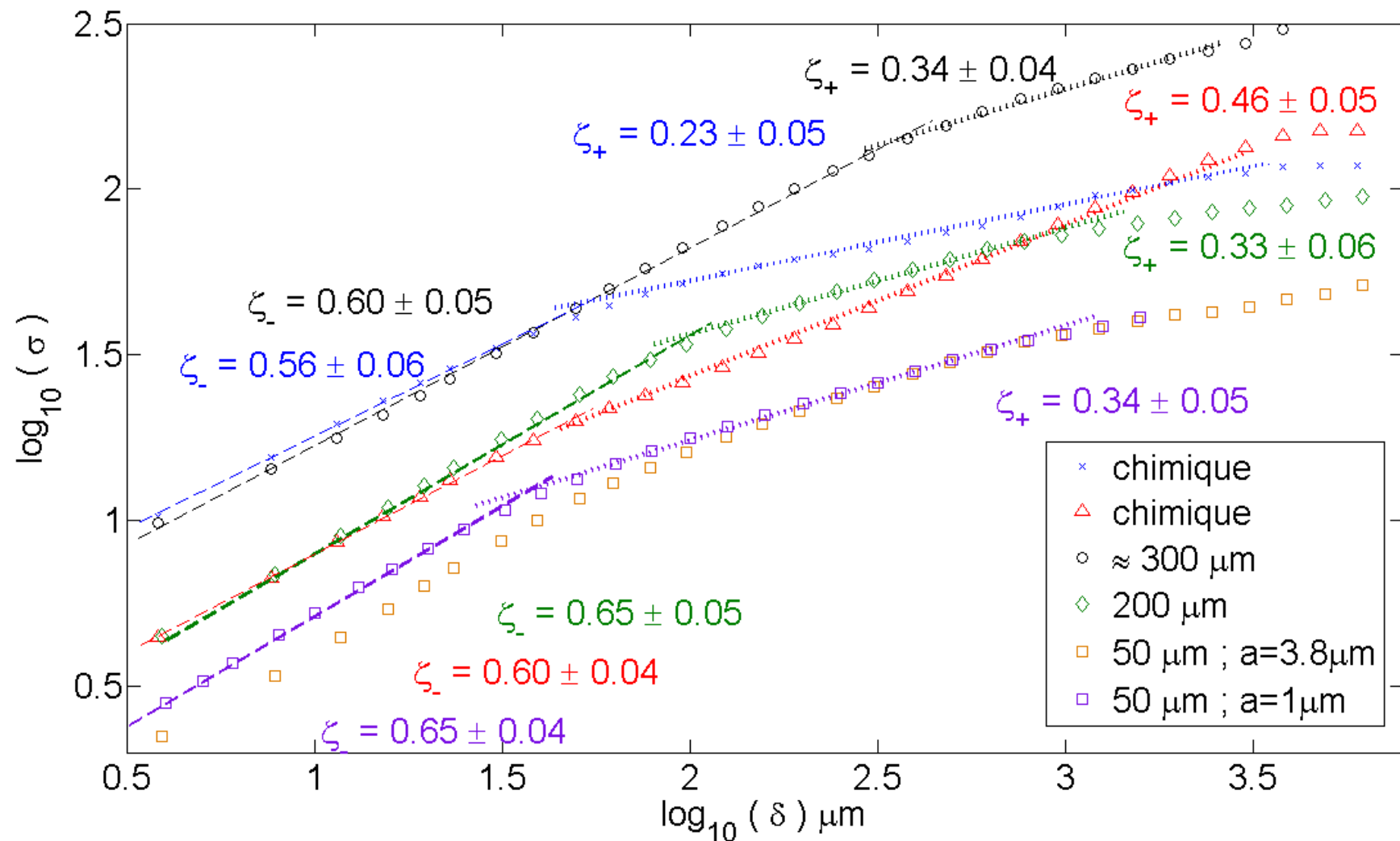
Effects of resolution



Effects of resolution



Effects of disorder



Coherence of roughness measurement methods

■ Maximum-Minimum (MM)

$$\Delta(x_0, \delta) = \max_{x \in [x_0, x_0 + \delta]} (y(x)) - \min_{x \in [x_0, x_0 + \delta]} (y(x))$$

$$\langle \Delta(\delta) \rangle_{x_0} \propto \delta^\zeta$$

Schmittbuhl et al. (PR E, 1995)

■ Structure functions (SF)

$$C_k(\delta) = \left\langle |y(x+\delta) - y(x)|^k \right\rangle^{\frac{1}{k}}$$

$$C_k(\delta) = \delta^{\zeta_k}$$

Halpin-Healy (PR A, 1991)

■ Power spectrum (PS)

$$P(k) = \text{TF of } w(\Delta x) = \langle y(x+\Delta x)y(x) \rangle - \langle y(x+\Delta x) \rangle \langle y(x) \rangle$$

$$P(k) \propto k^{-1-2\zeta}$$

Schmittbuhl et al. (1995)

■ Average Wavelet Coefficient (AWC)

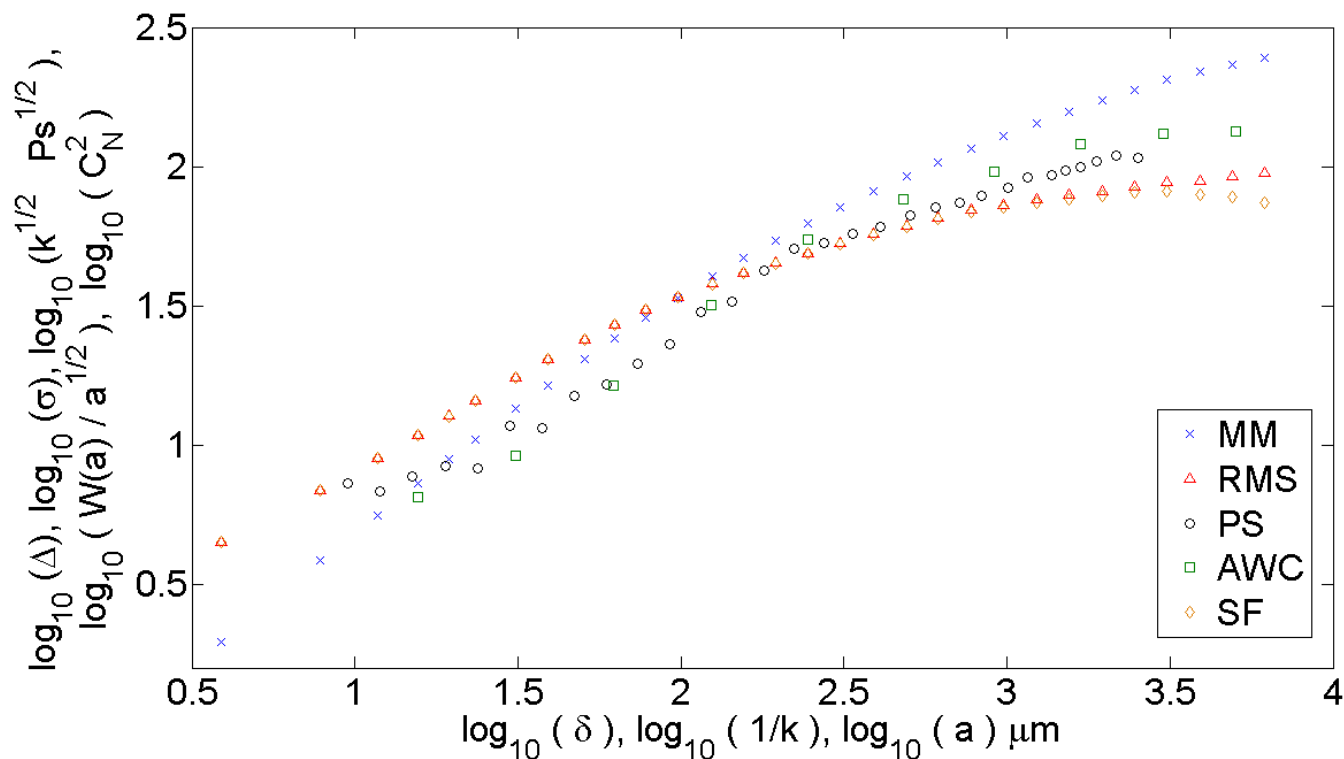
$$W[y](a) = \left\langle |W[y](a, b)| \right\rangle_b$$

$$W[h](a) \propto a^{\zeta + \frac{1}{2}}$$

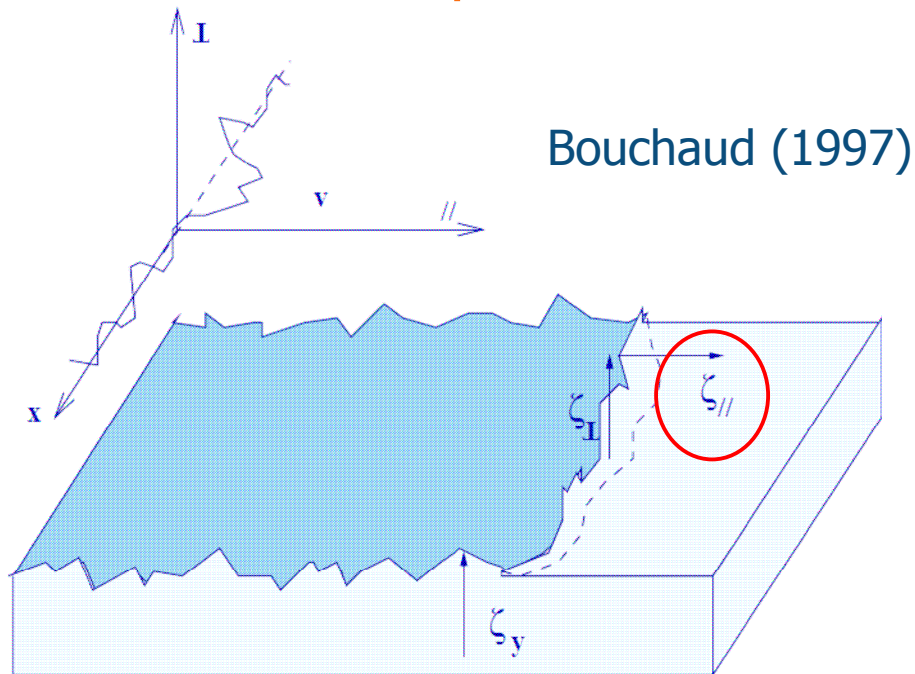
Simonsen et al. (1998)

Coherence of roughness measurement methods

	RMS	SF	MM	PS	AWC
ζ	0.33 ± 0.06	0.35 ± 0.05	0.44 ± 0.05	0.35 ± 0.07	0.37 ± 0.05
	0.65 ± 0.05	0.62 ± 0.04	0.80 ± 0.06	0.69 ± 0.04	0.73 ± 0.07

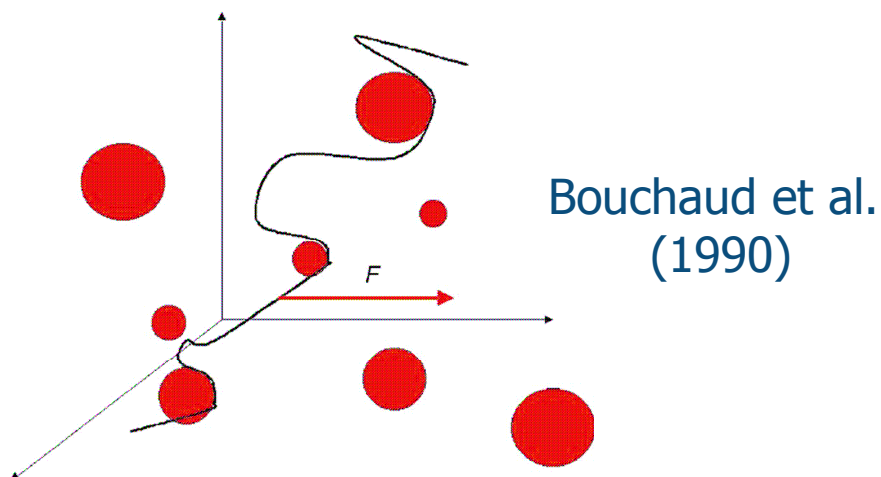


Comparison with former roughness measurements

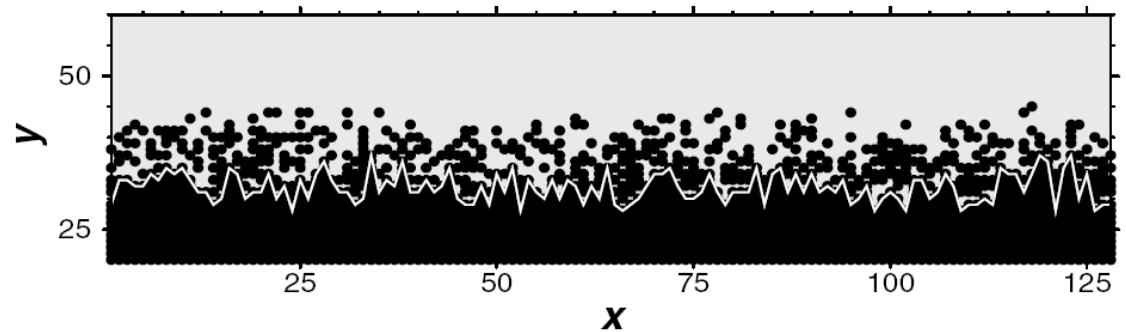


Bouchaud (1997)

	ζ_{II}
modélisation	0.35 Schmittbuhl et al. (1995)
	0.6 Hansen et al. (2003)
experiments	0.6 Daguier et al. (1995) Delaplace et al. (1999)



Bouchaud et al.
(1990)



Hansen et al. (2003)

Comparison with former roughness measurements

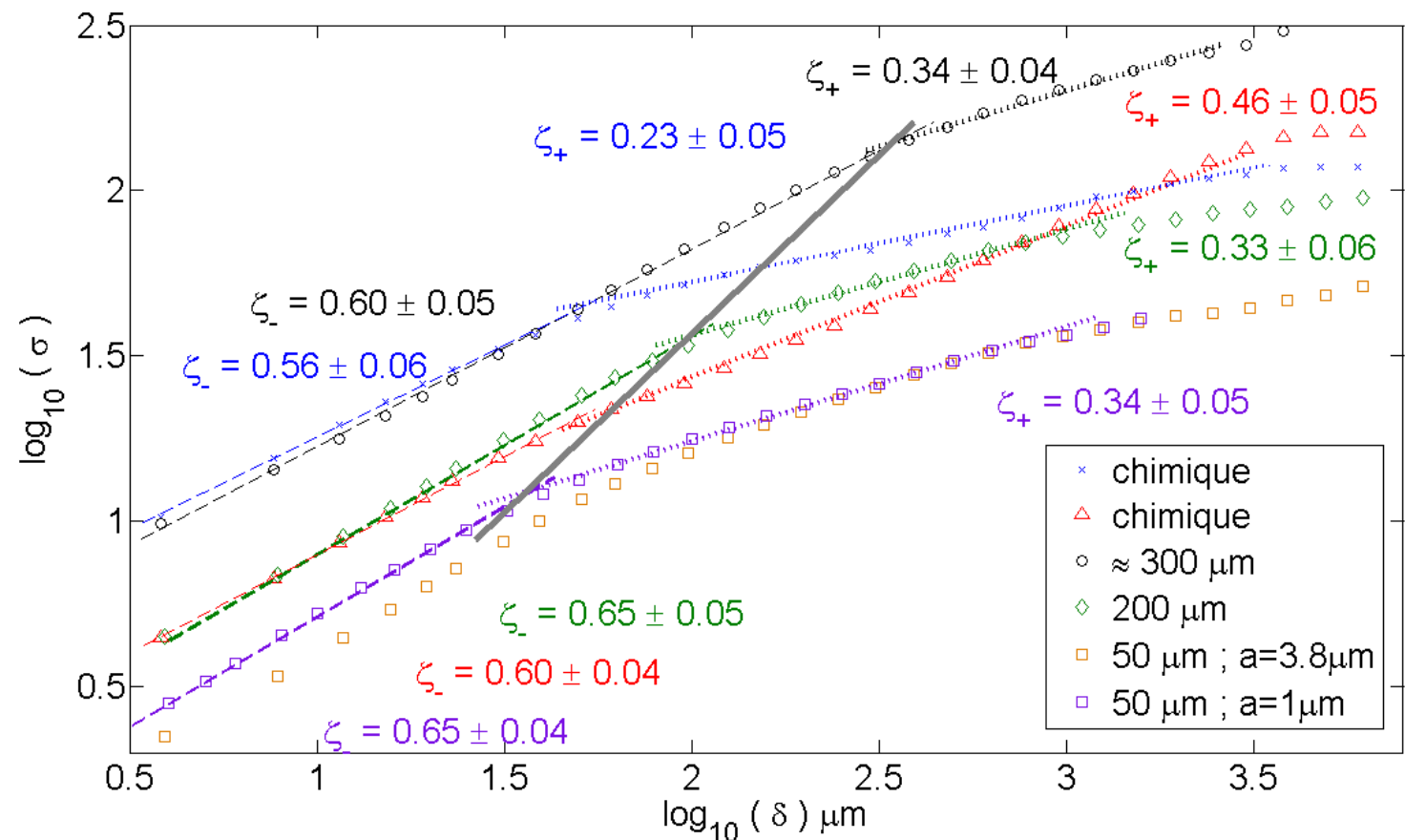
Hypothesis:

- Coalescence processes at small scales
- Fluctuating elastic line at large scales

gray line

$$\sigma = 0.35 \delta^*$$

with δ^* =
separating
length scale



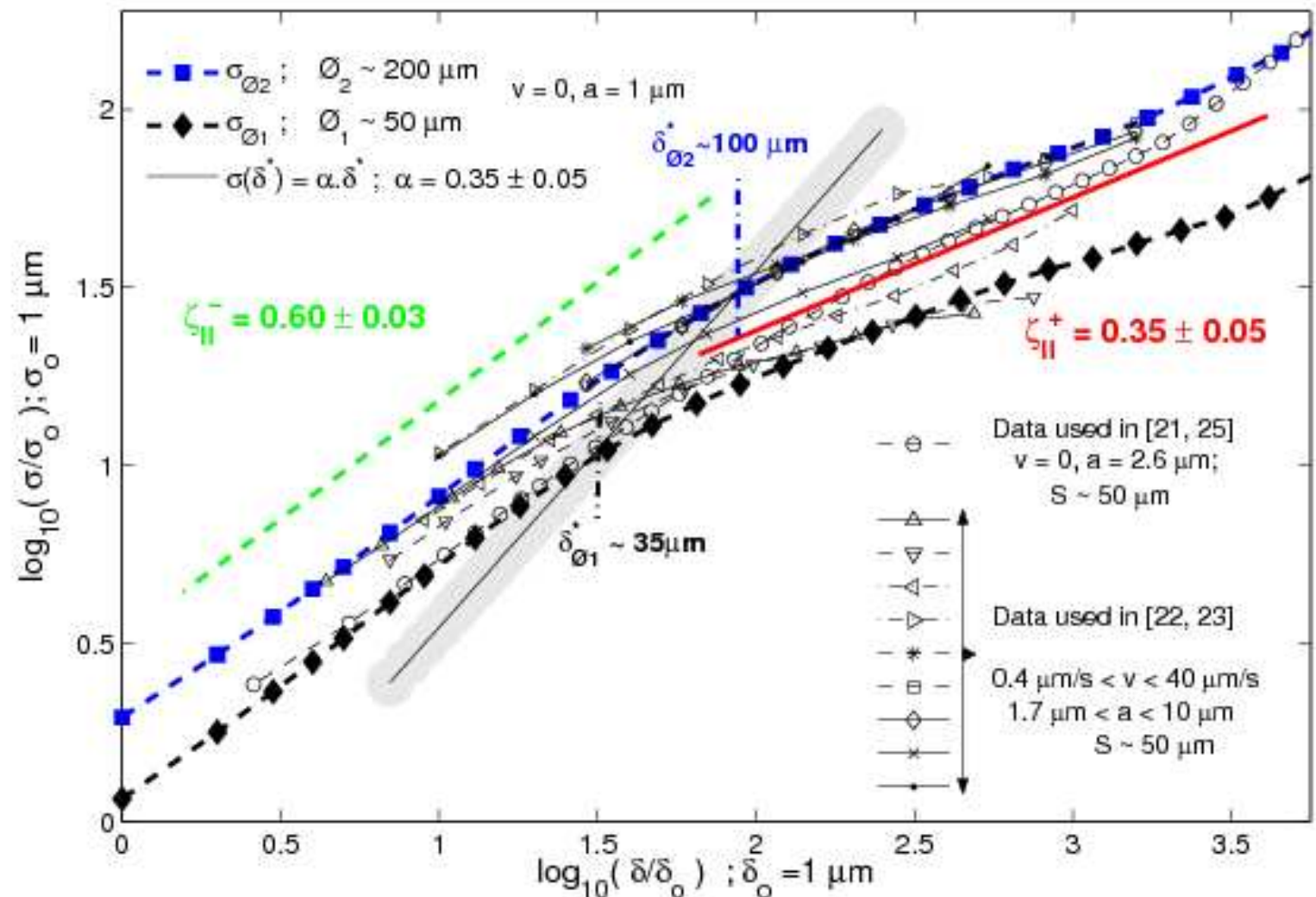
Comparison with former roughness measurements

Robust because found for former experiments too

gray line

$$\sigma = 0.35 \delta^*$$

with δ^* =
separating
length scale



Conclusions on morphology

- Two roughness regimes: $\zeta \approx 0.6$ at small length scales and $\zeta \approx 0.35$ at large length scales
 - Robust for different parameter changes (disorder preparation, resolution...)
 - Threshold length scale around disorder typical length
-
- ⇒ Regime at small length scales due to coalescence processes
 - ⇒ Regime at large length scales due to long-range elastic interaction processes
 - ⇒ These roughness regimes seem universal

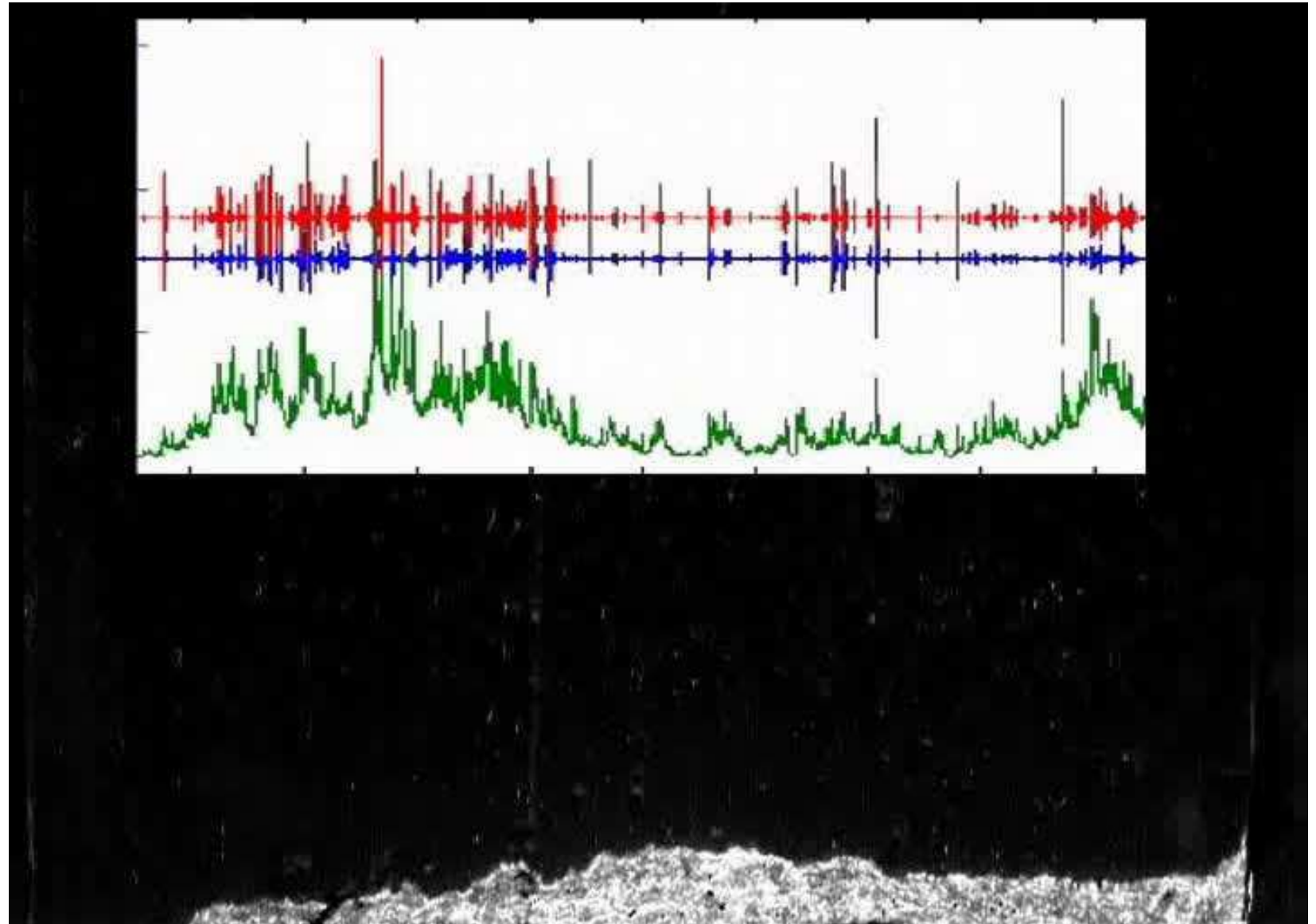
Front dynamics analysis

AE signal

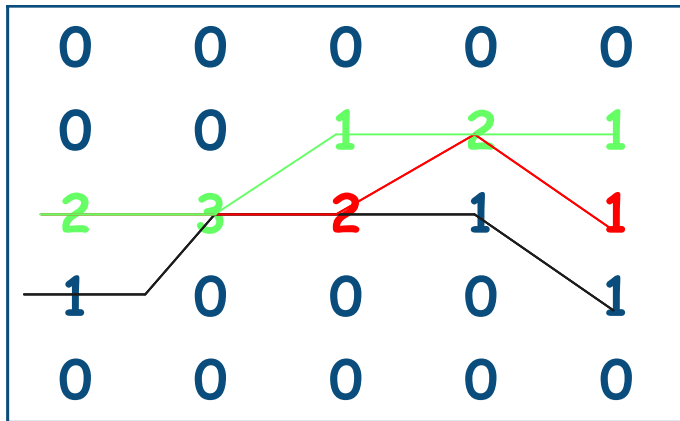
sensor 1

sensor 2

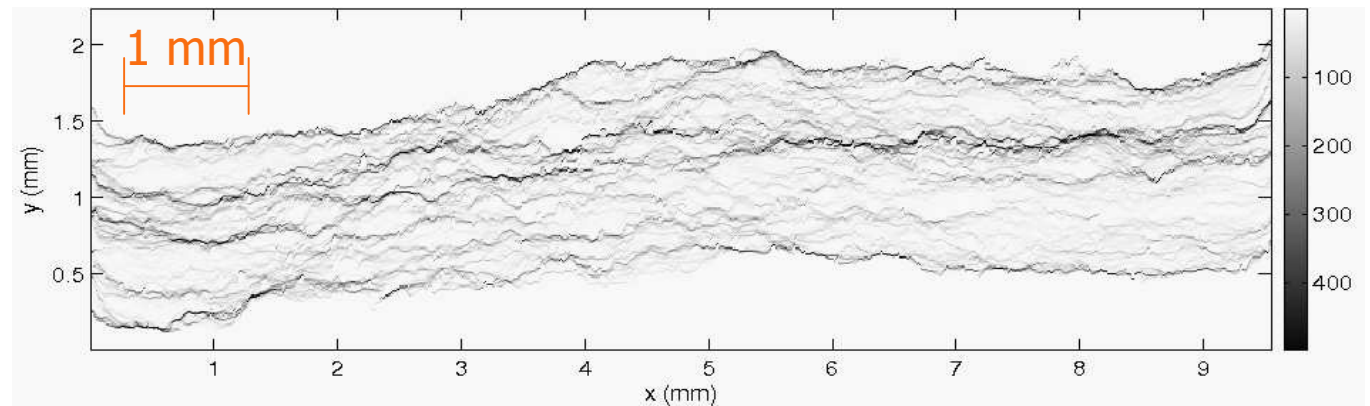
Mean front
velocity $\langle V \rangle$



Local velocities



Waiting time matrix $W(x,y)$



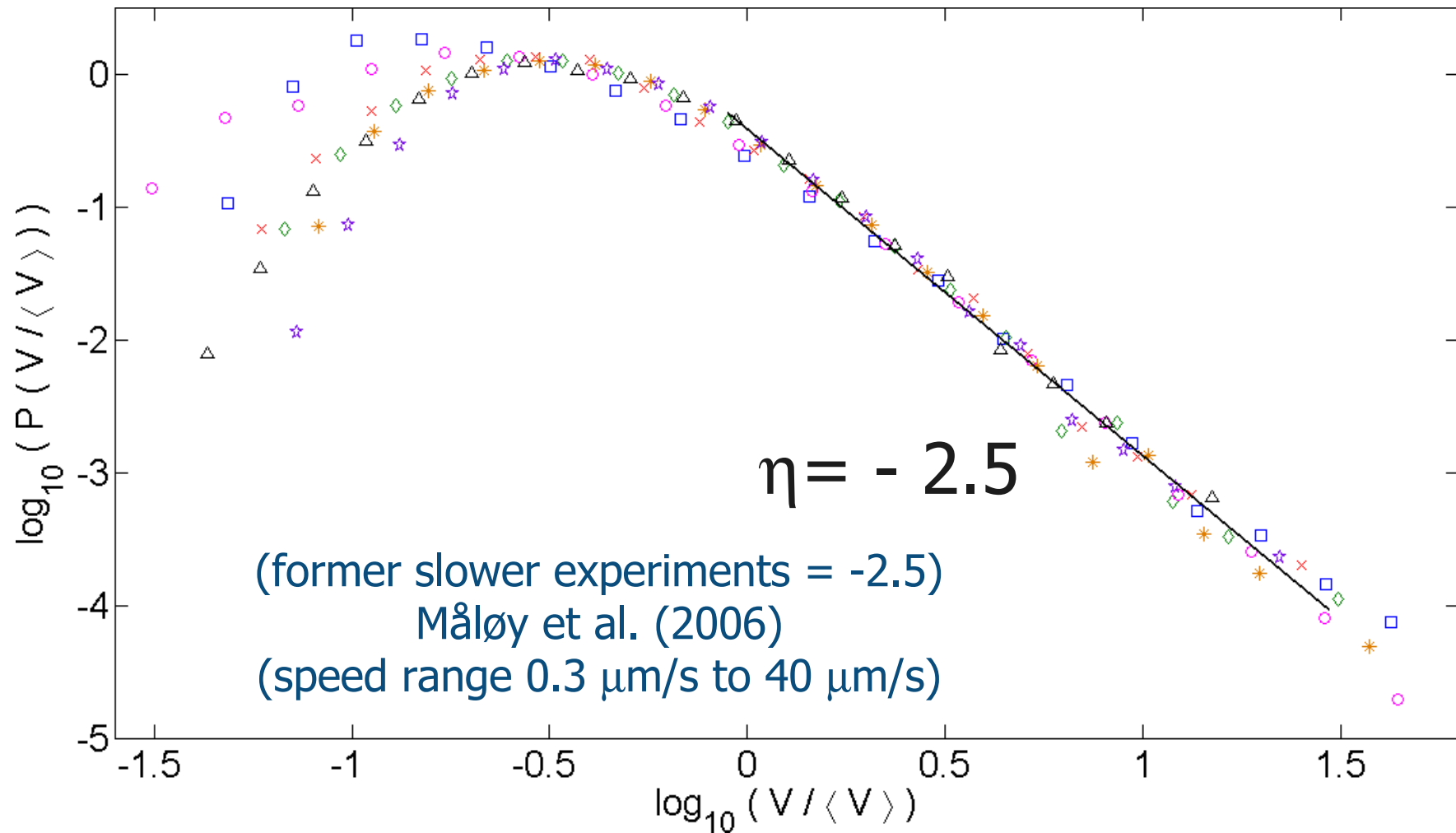
Velocity matrix:
$$V(x,y) = \frac{\alpha}{\delta t} \frac{1}{W(x,y)}$$

$\left\{ \begin{array}{l} \alpha = 10 \text{ } \mu\text{m} \\ \delta t = 1 \text{ ms} \end{array} \right.$

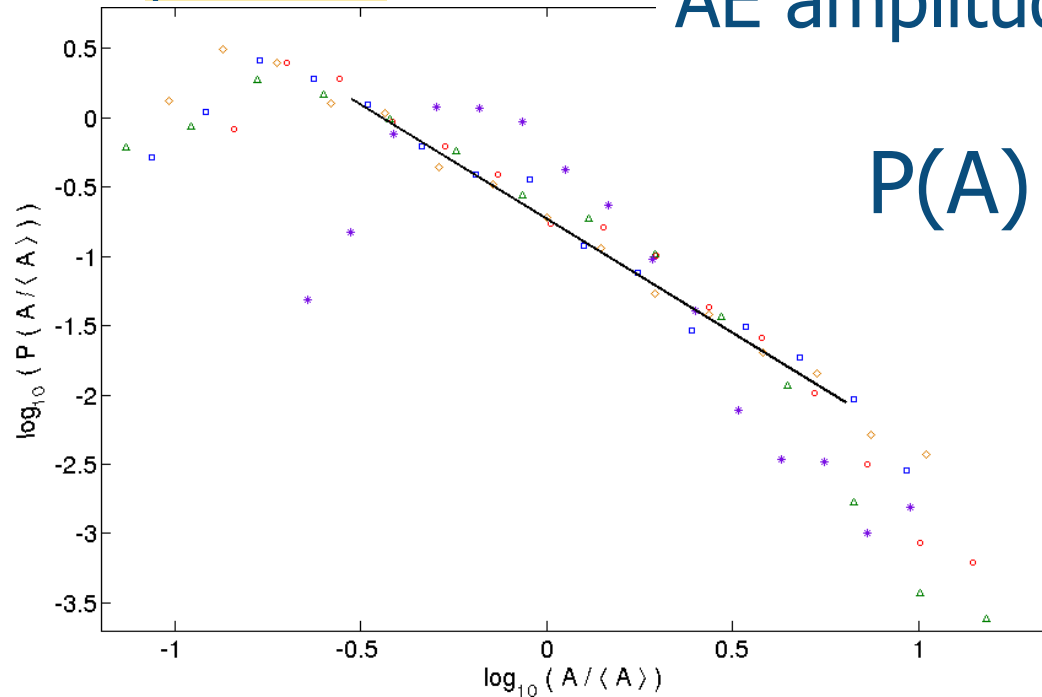
$$150 \text{ } \mu\text{m/s} < \langle v \rangle < 1000 \text{ } \mu\text{m/s}$$

Local velocities

\neq colors and signs $\Rightarrow \neq$ disorders
 \neq mean front velocities

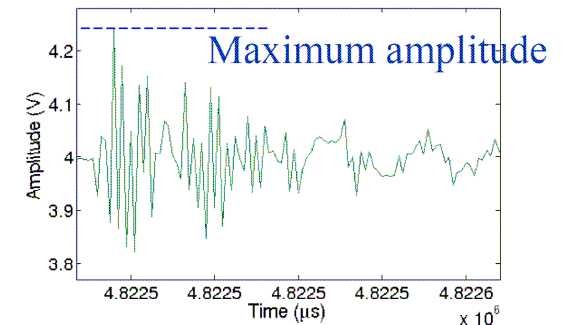


AE amplitude distribution



$$P(A) \propto A^{-1.65}$$

≠ colors and signs
 ⇒ ≠ disorders
 ≠ mean front velocities

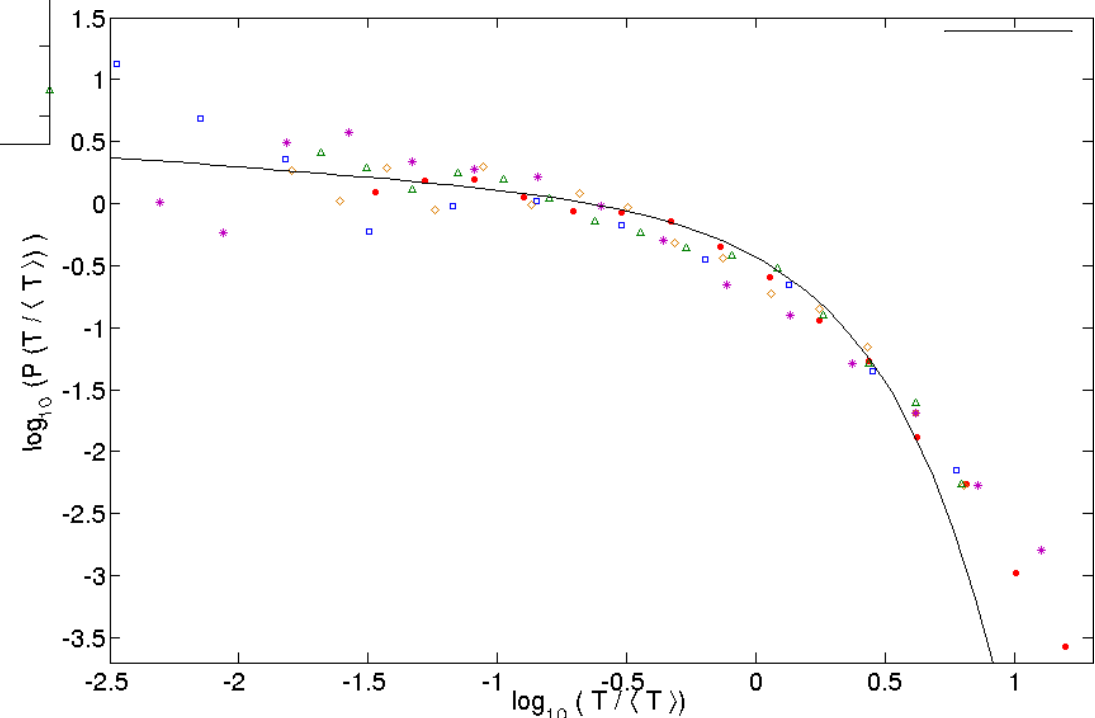


AE waiting time distribution

$$P(T) \propto T^{-(1-\gamma)} \exp(-T/B)$$

$$\gamma = 0.85 ; B = 1$$

(idem Davidsen et al., PRL, 2007)

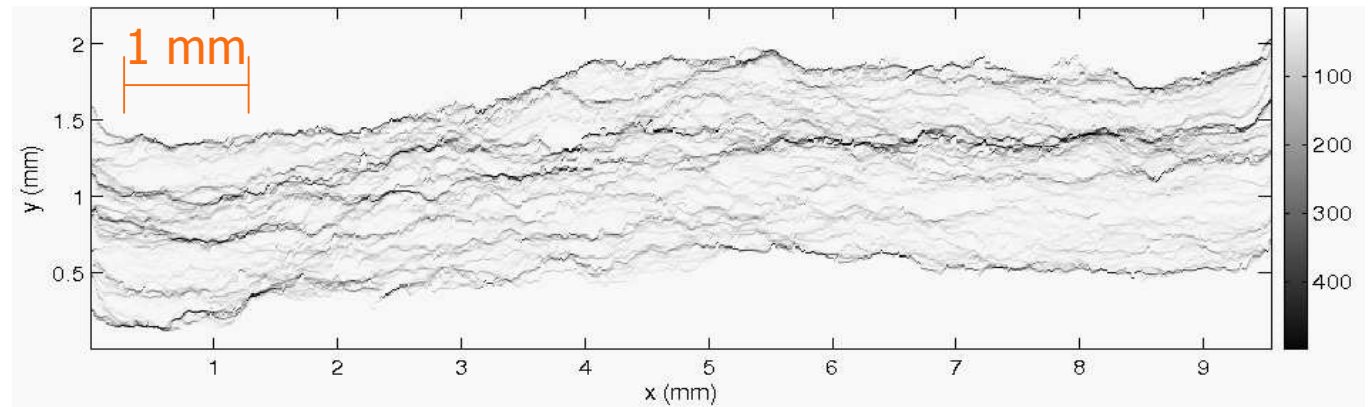


Conclusions on dynamics

- Distribution of velocities follows a power law \Rightarrow robust for different disorders and front speeds
- Preliminary results on AE show scaling law distributions of amplitudes and waiting times

Building catalogs

Waiting time matrix $W(x,y)$



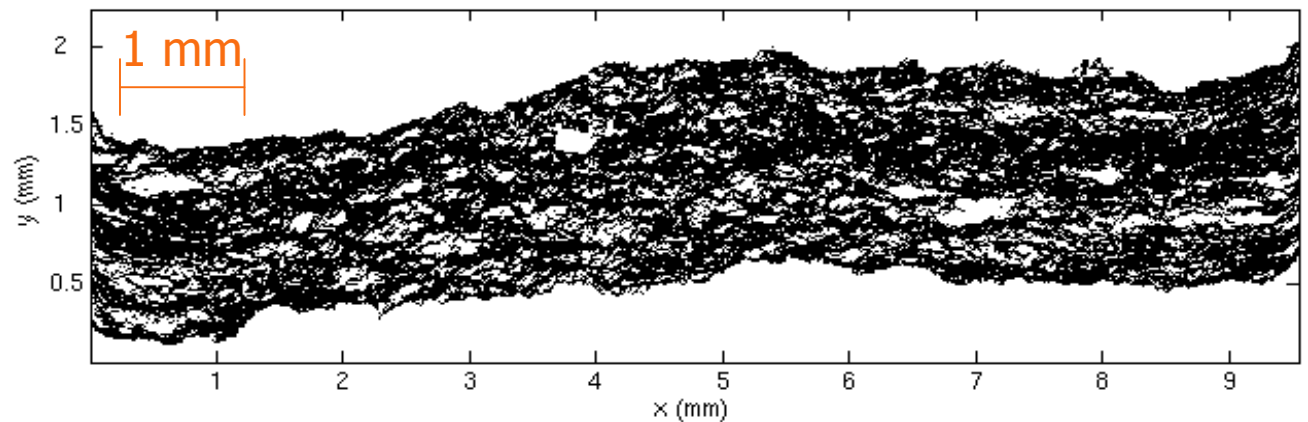
Velocity matrix:

$$V(x,y) = \frac{\alpha}{\delta t} \frac{1}{W(x,y)}$$

$$\begin{cases} \alpha = 10 \mu\text{m} \\ \delta t = 1 \text{ ms} \end{cases}$$

$$v = \begin{cases} 1 & \text{if } v > C \langle v \rangle \\ 0 & \text{else} \end{cases}$$

$$150 \mu\text{m/s} < \langle v \rangle < 1000 \mu\text{m/s}$$



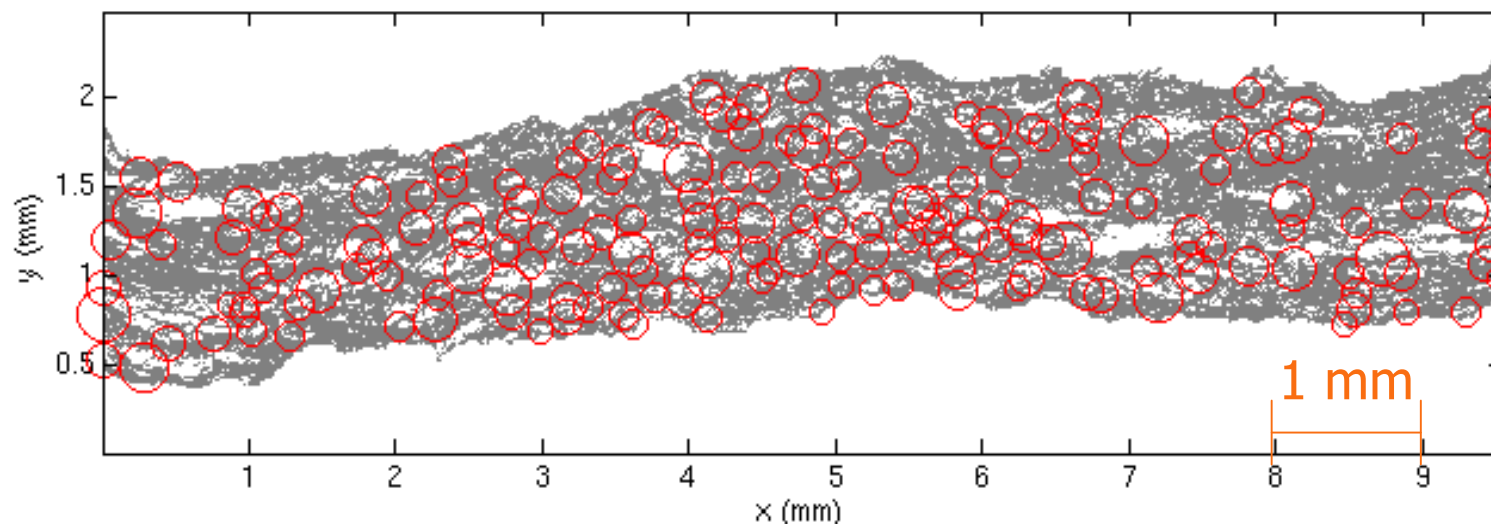
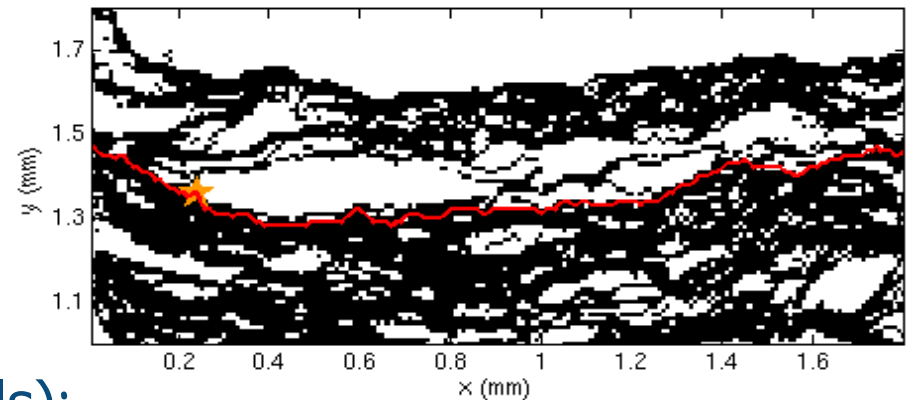
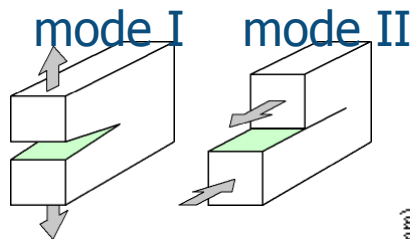
Building catalogs

Parameters for each event:

- Time of occurrence t
- Epicenter position (x,y)
- Moment $M \approx \text{area } A \text{ of event (nb of pixels):}$

$$M \approx E_I \times A \times \text{Opening} \quad (\text{constant})$$

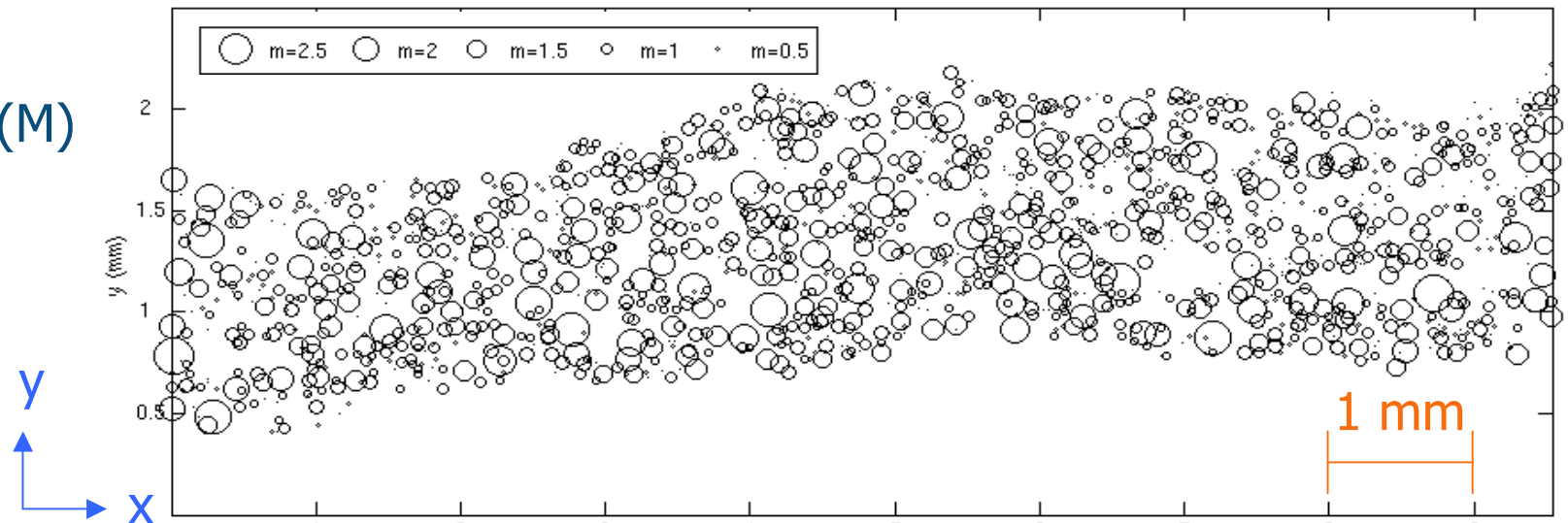
(Seismic moment: $M_0 \approx \mu \times S \times D$
with S =cracked area & D =fault offset)



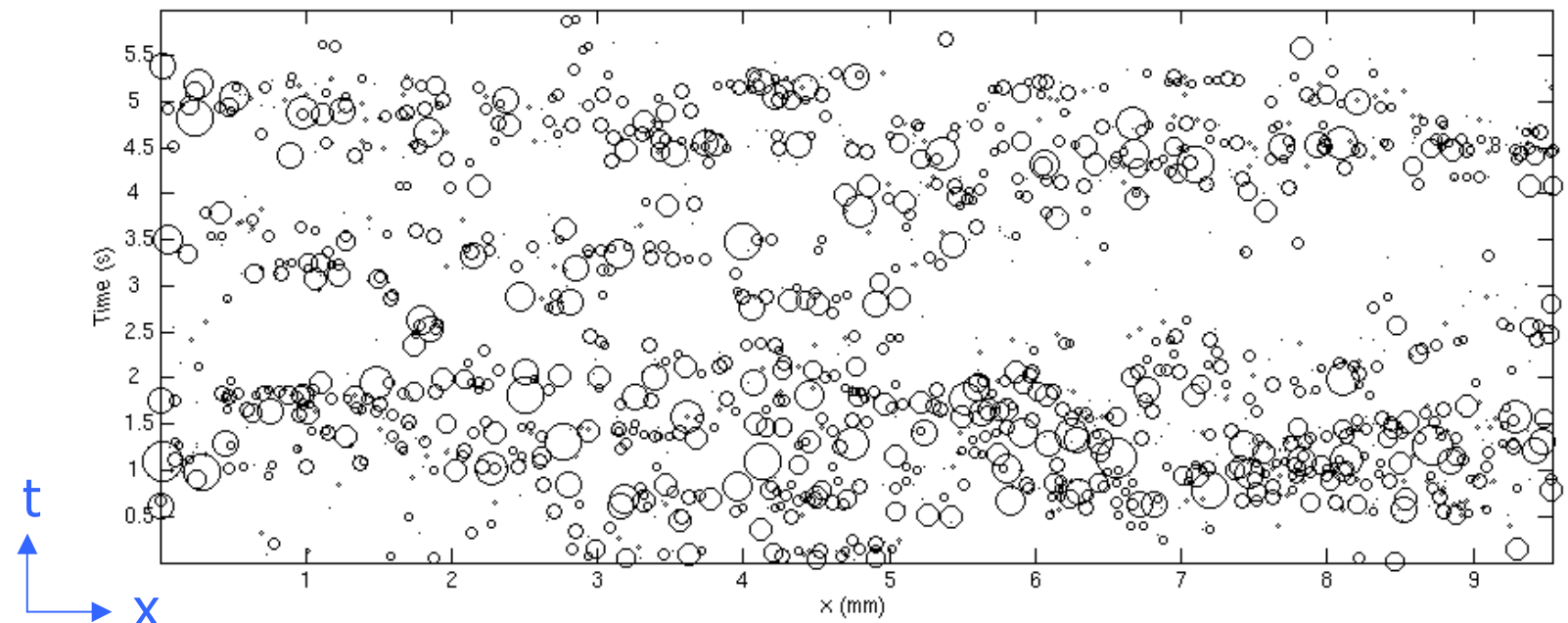
- Circles = events
- Diameter of circles $\approx \log_{10}(M)$
- Only events with $\log_{10}(M) > 1.5$ represented

- Circles = events
- Diameter $\approx \log_{10}(M)$

x – y map

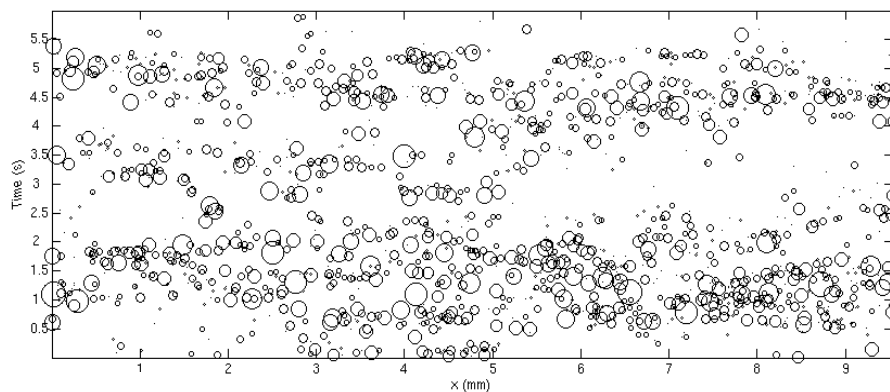


x – t map



- Definition of event = avalanche
- Building quake catalogs similar to seismicity catalogs

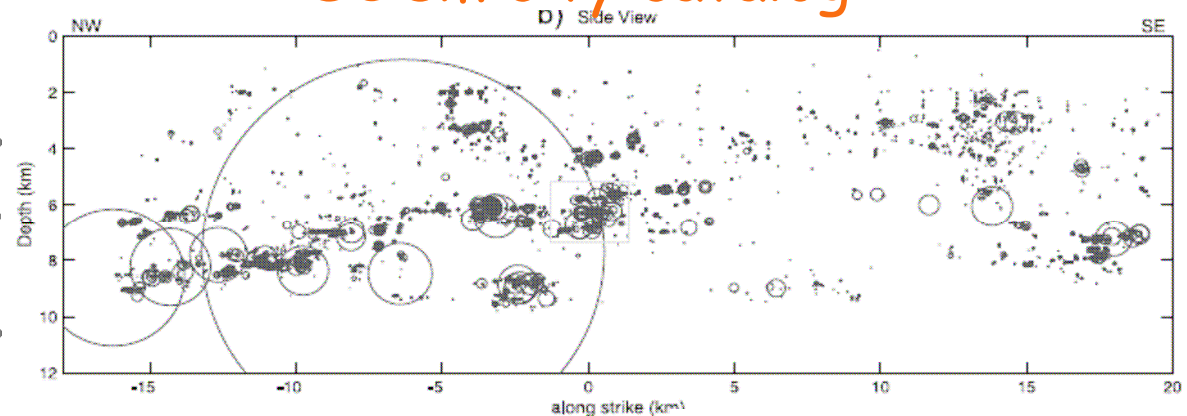
Experimental catalog



1 mm



Seismicity catalog

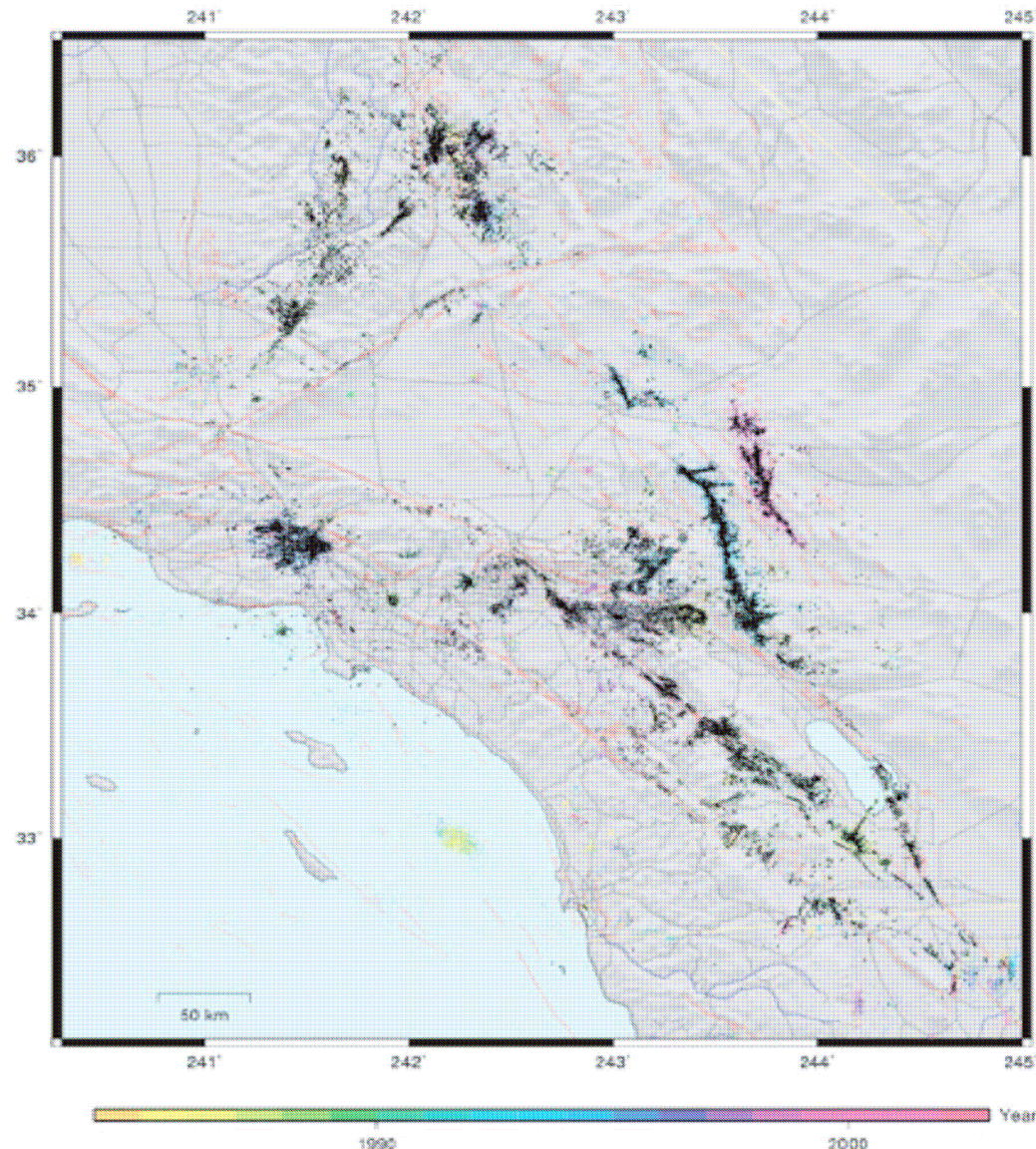


5 km



(Shaff *et al.*, JGR, 2002)

- ⇒ Link between the two catalogs?
- ⇒ What explanation for the similarities?



Southern California seismicity 1984-2002
 (Shearer *et al.*, BSSA, 2005)

- Homogeneous from 1984 to 2002
- Complete for earthquakes with magnitude > 2.5
- Area (120.5°W, 115.0°W) x (32.5°N, 36.0°N)
- 22217 events
- Magnitude $M_w \Rightarrow$ seismic moment M_0 (in N.m)

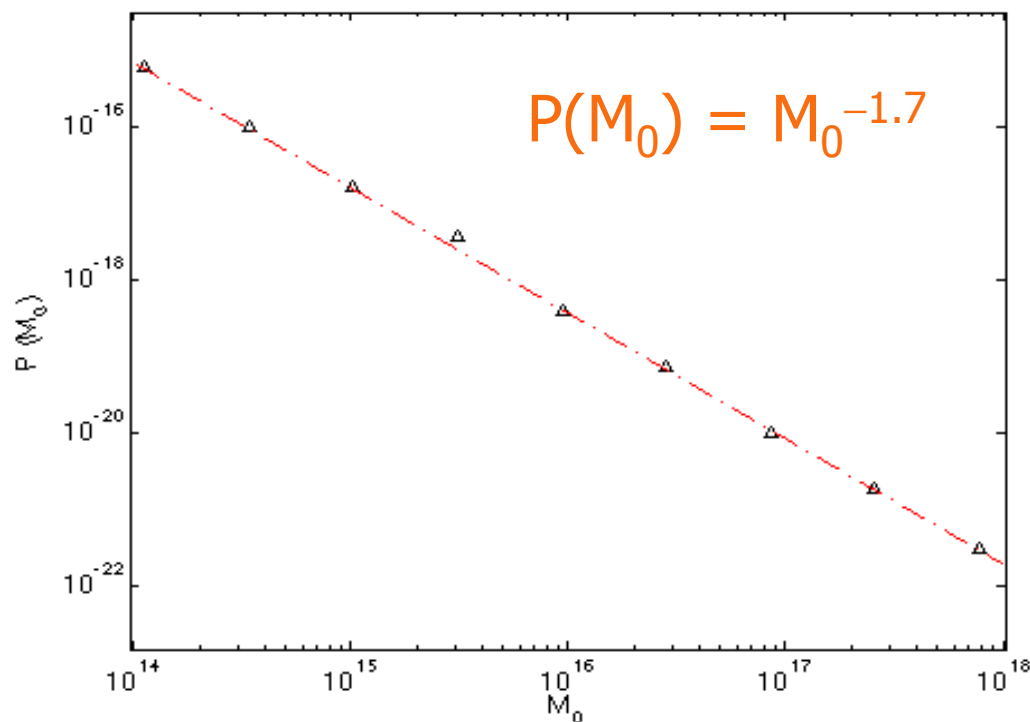
$$\log_{10}(M_0) = \frac{3}{2} M_w + 9.1$$

(Kanamori, JGR, 1977)

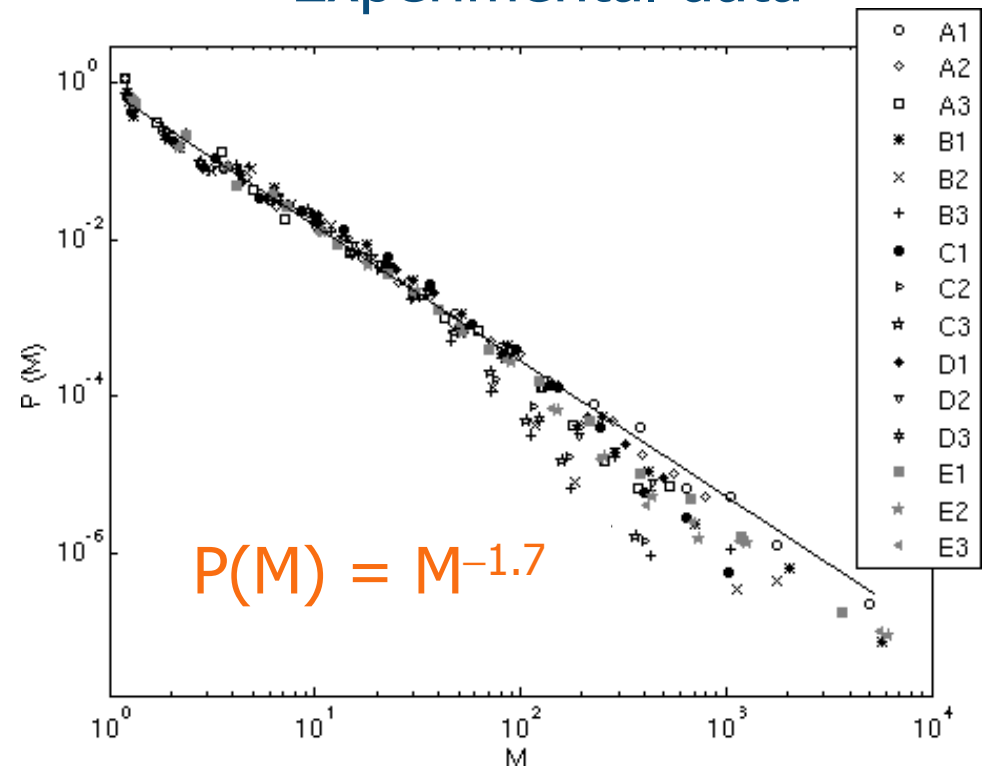
Gutenberg-Richter relationship: $N(M_0) \approx M_0^{-1-\beta}$

(Gutenberg and Richter, BSSA, 1944)

Seismicity data



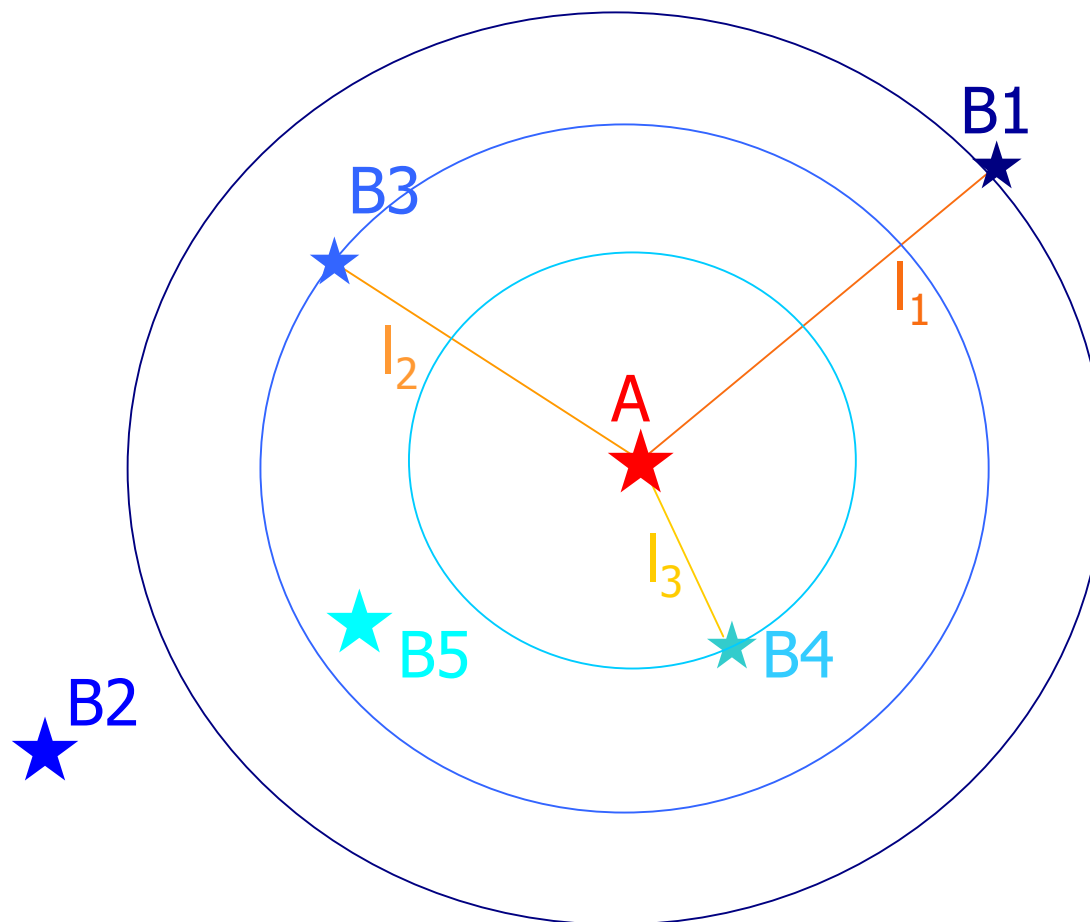
Experimental data



15 experimental catalogs from 5 experiments, each with 3 different C values

B is a record of A if no event happens within the disc of radius AB (distance l) centered on A during $[t_A, t_B]$, with $t_A < t_B$ (time interval $T = t_B - t_A$).

(Davidsen *et al.*, GRL, 2006)

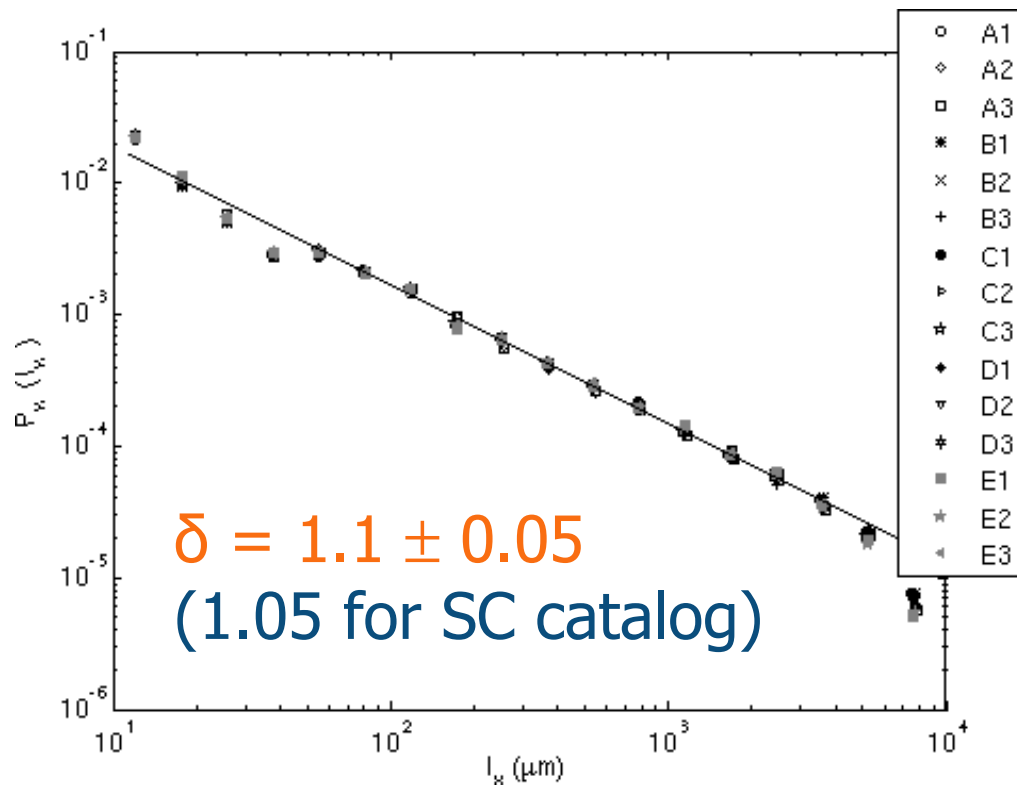


- All events B happen after event A.
- Numbers represent the order of occurrence of events in the catalog.
- Records of A = B1, B3 and B4.
- Distributions of distances:

$$l_i = |x_0 - x_i|$$

- Distributions of time intervals:

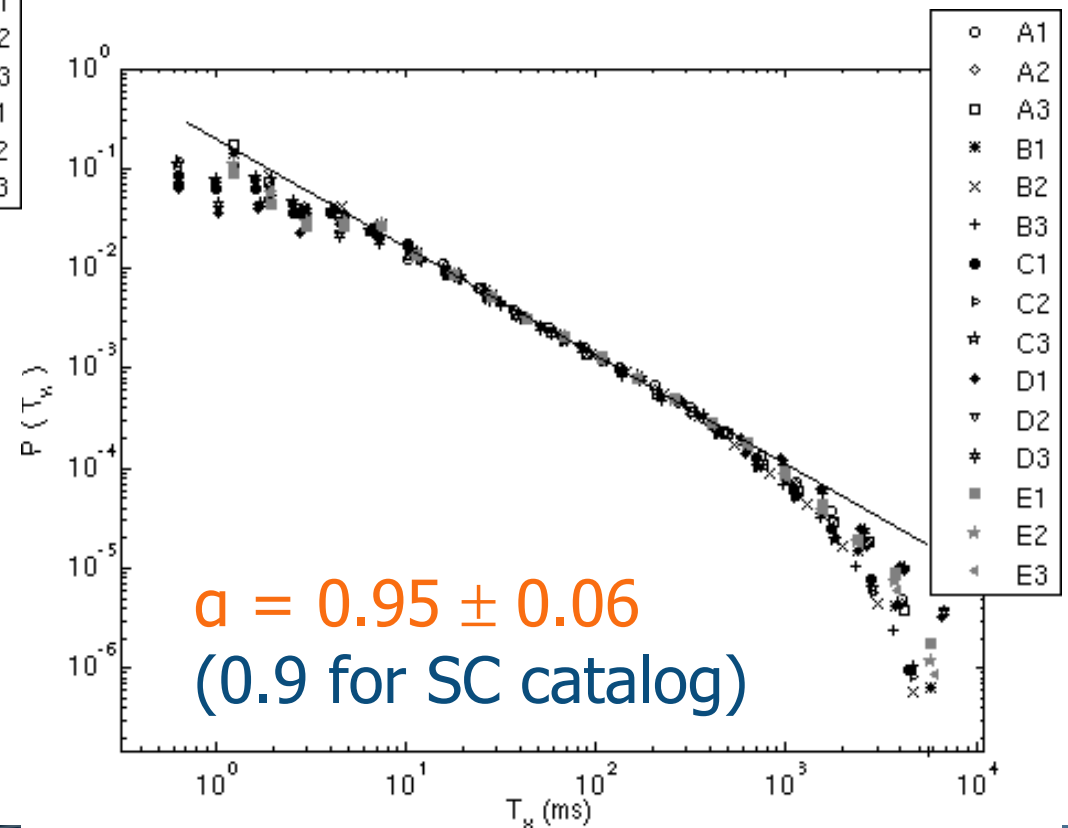
$$T_i = t_0 - t_i$$



Distribution of distances l

15 experimental catalogs from 5 experiments, each with 3 different C levels

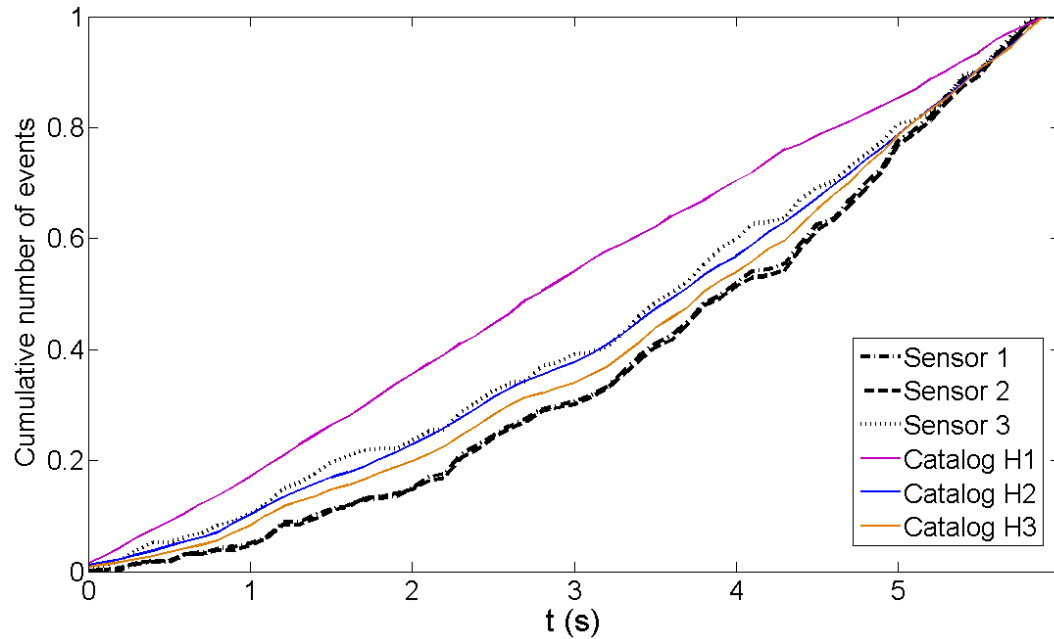
Distribution of time intervals T



Conclusions for comparison with large scale data

- Quake catalogs with a large number of events (typically a few thousands)
 - Obey same scaling laws as seismicity data (Gutenberg-Richter, distribution of recurrent distances, distribution of recurrent time intervals) despite different spatial and time scales, different physical mechanisms and different geometries
-
- ⇒ Microstructures control the dynamics of crack propagation at large scales
 - ⇒ Global dynamics of rupture propagation depend on event interactions
 - ⇒ The long range elastic coupling between heterogeneous microstructures control these interactions

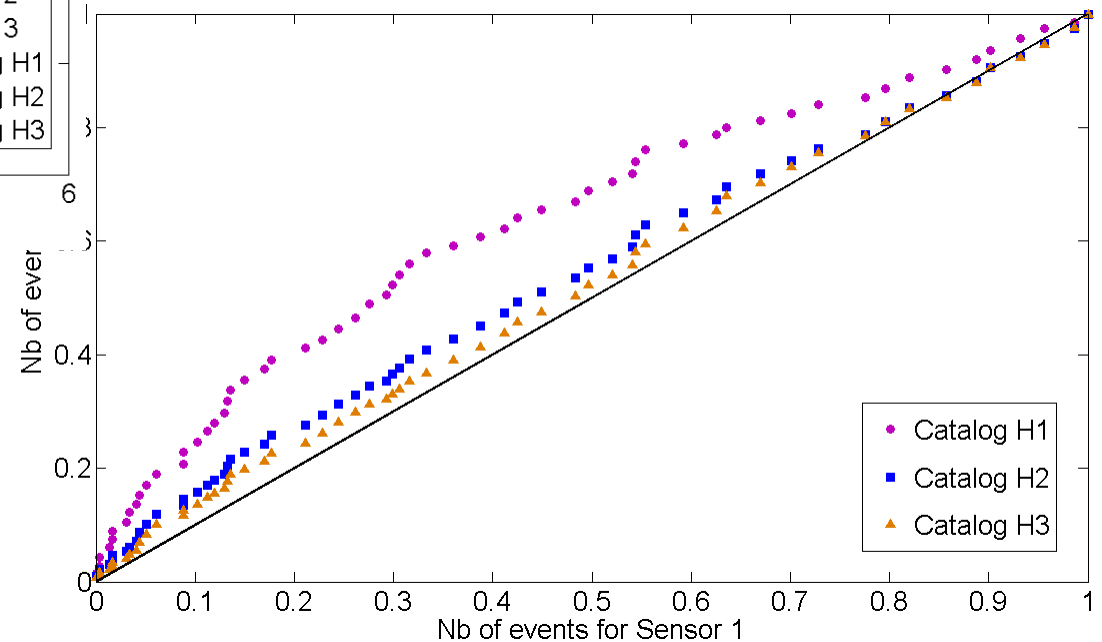
- Optical and acoustic monitoring of a crack propagation along a heterogeneous interface at high spatial resolution or high time rate
- Two roughness regimes, $\zeta = 0.6$ at small and $\zeta = 0.35$ at large scales, separated by a typical length scale, robust for different parameter changes
- Distributions of quakes ranked in catalogs obey same scaling laws as seismicity data (Gutenberg-Richter, distribution of recurrent distances, distribution of recurrent time intervals) despite different spatial and time scales, rupture mechanisms and configurations



- Acoustic emissions probably due to local depinning of the rupture front

Comparison between AE time series and optical catalogs

H1, H2 and H3 = 3 catalogs from same experiment with \neq velocity thresholds

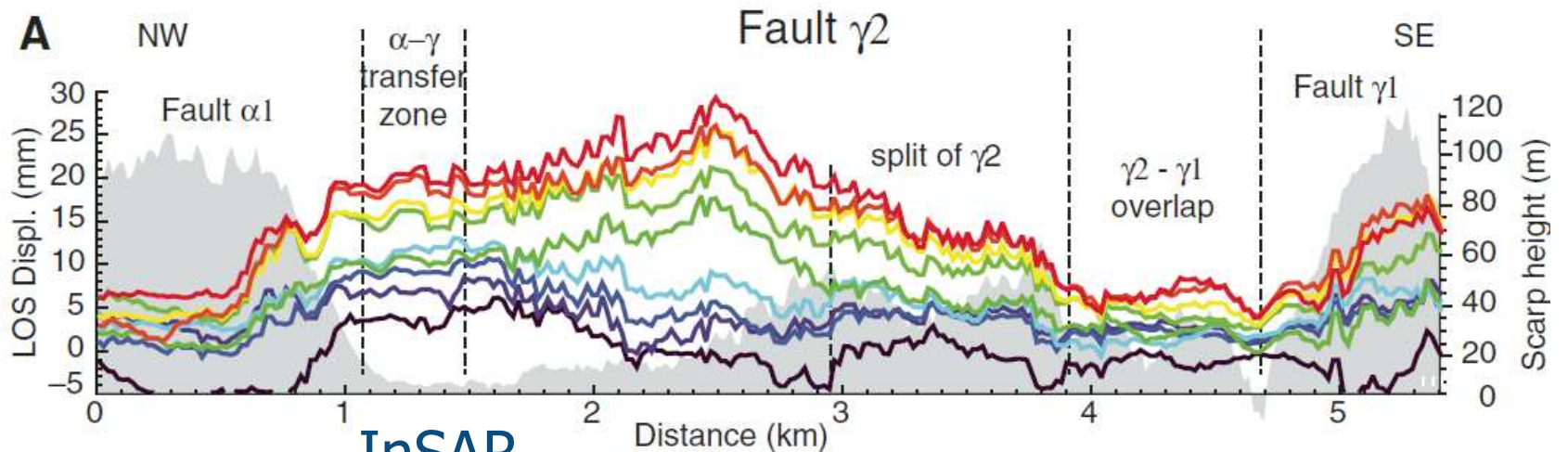


⇒ Building catalogs from AE analysis to compare with optical events

Perspectives

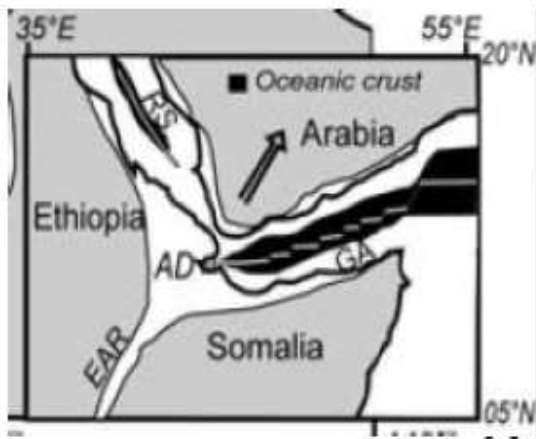
⇒ Comparison with other large scale data sets

Doubre et al.
(Geology, 2005)



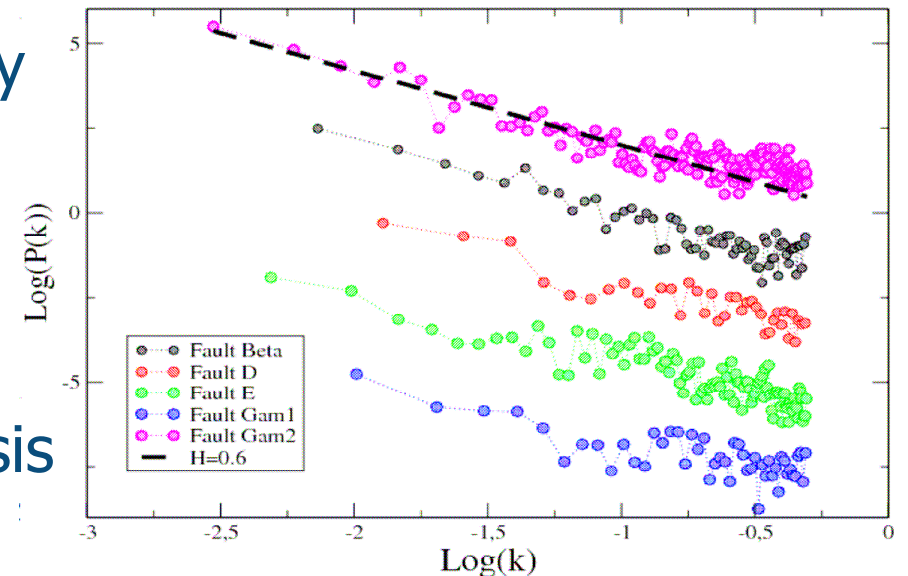
InSAR

1997-2005 slip history



Asal Rift

Slip front
morphology analysis



Thanks for your attention...



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