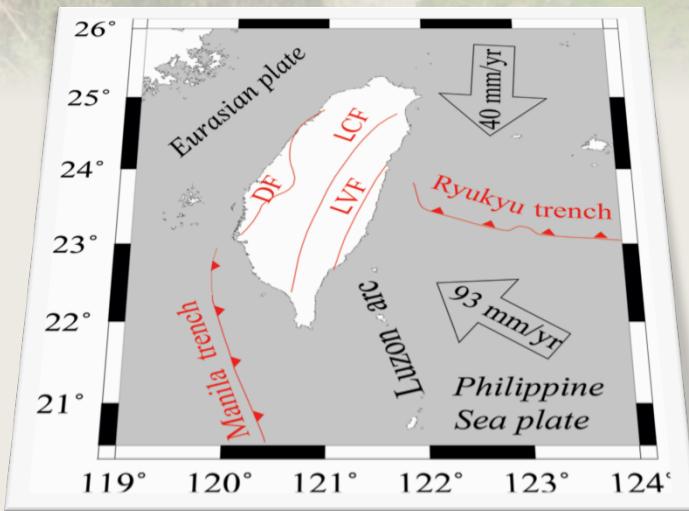




Longitudinal Valley, Taiwan



SEISMIC VS ASEISMIC BEHAVIOR ON THE LONGITUDINAL VALLEY FAULT : WHAT CONTROLS THE SLIP MODE?



Strasbourg
17/10/14

M. Thomas, J.-P. Avouac, N. Lapusta, J.-P. Gratier, J.-C. Lee

■ Motivation:

- Define the distribution of seismic/aseismic slip on fault
- Document the factors that control this distribution
- Develop physical model of the seismic cycle



Longitudinal Valley Fault, Taiwan

■ Motivation:

- Define the distribution of seismic/aseismic slip on fault
- Document the factors that control this distribution
- Develop physical model of the seismic cycle

■ Approach:

- Target : **Longitudinal Valley Fault, Taiwan**
- Data : geodesy, seismology
- Inversion: temporal and spatial evolution of slip at depth
- Implication for fault friction and the governing factors
- 3D dynamic modeling
- Deformation mechanisms that control the mode of slip



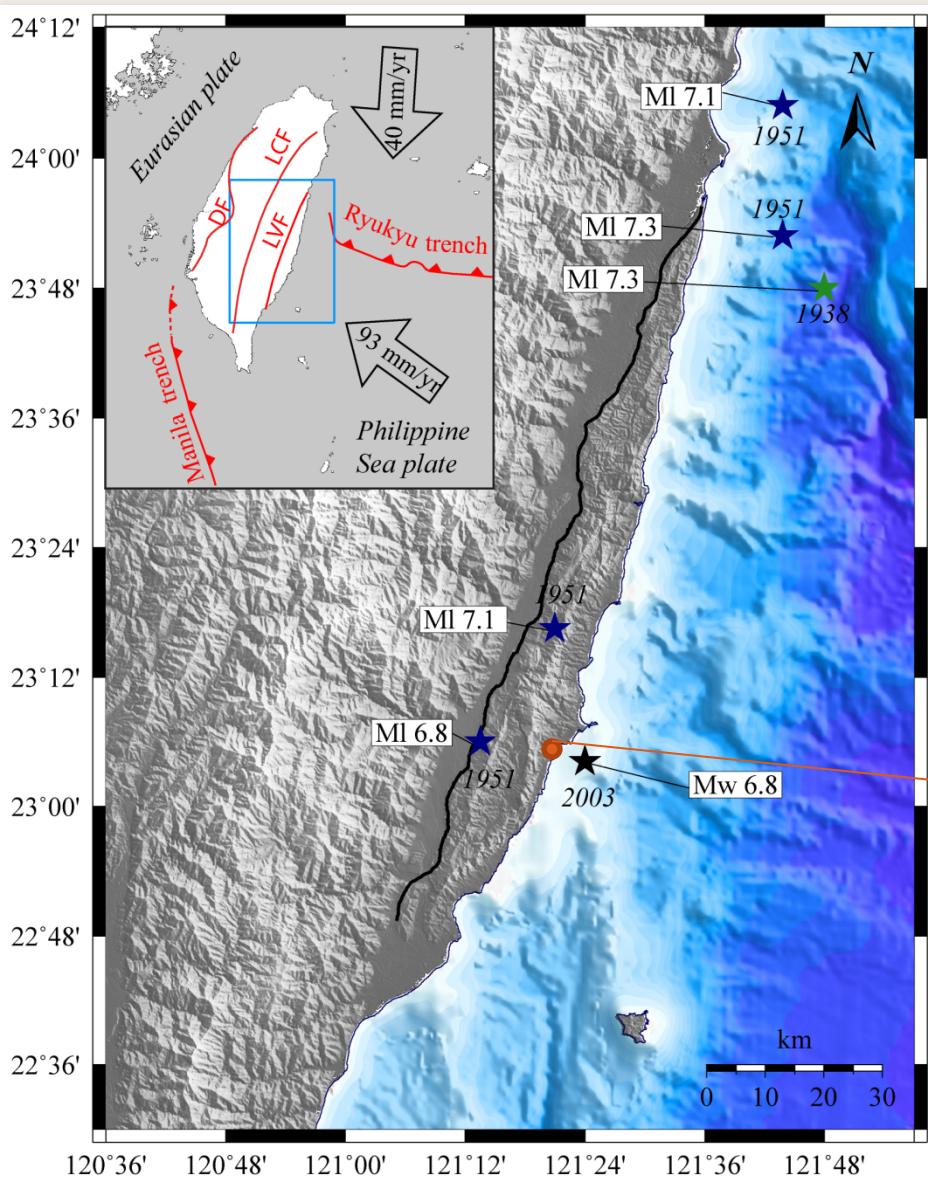
Longitudinal Valley Fault, Taiwan

- PART 1: Geological and plate tectonic setting of the Longitudinal Valley fault
- PART 2: Spatio-temporal evolution of seismic and aseismic slip on the Longitudinal Valley Fault, Taiwan
- PART 3: Frictional properties derived for the geodetic analysis and Dynamic modeling of earthquakes sequences on the Longitudinal Valley Fault
- PART 4: Lithological control on the deformation mechanism and the mode of fault slip on the Longitudinal Valley Fault, Taiwan

GEOLOGICAL SETTING : LONGITUDINAL VALLEY FAULT (LVF), TAIWAN

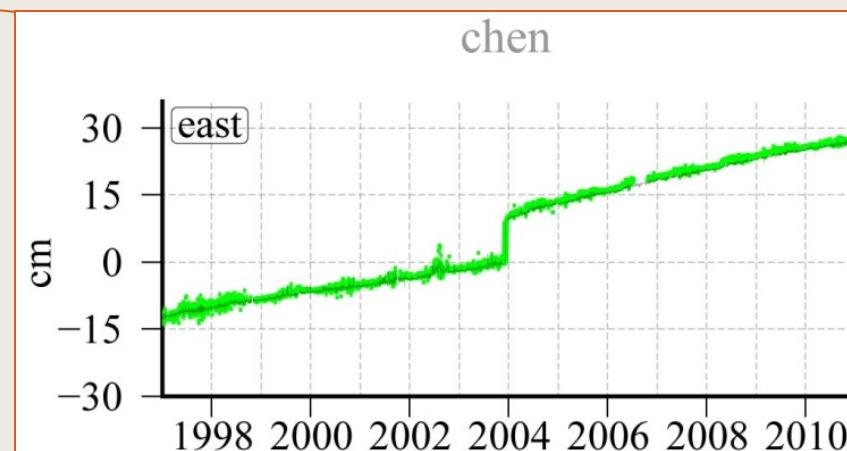
1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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The LVF is an exceptional laboratory to study the variations of frictional properties:

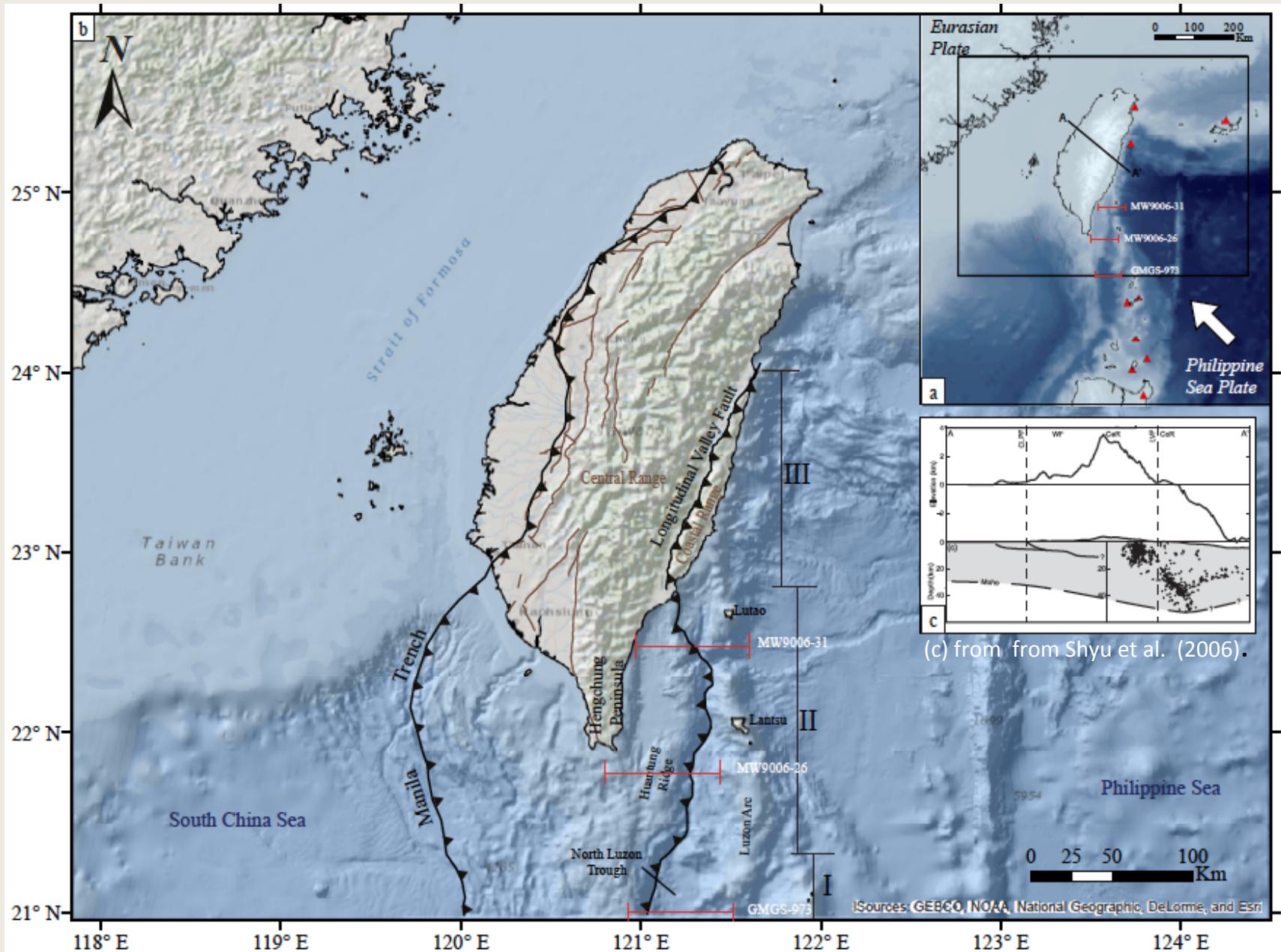
- LVF is part of very active plate boundary
- High slip rate: $> 4 \text{ cm/yr}$
- Aseismic creep accounts for a significant fraction of the fault slip
- Large earthquakes : $M>7$ 1951 ; $Mw 6.8$ 2003
- Thrust fault: an access to the lithology
- Great data set that records interseismic, coseismic postseismic periods.



GEOLOGICAL SETTING

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

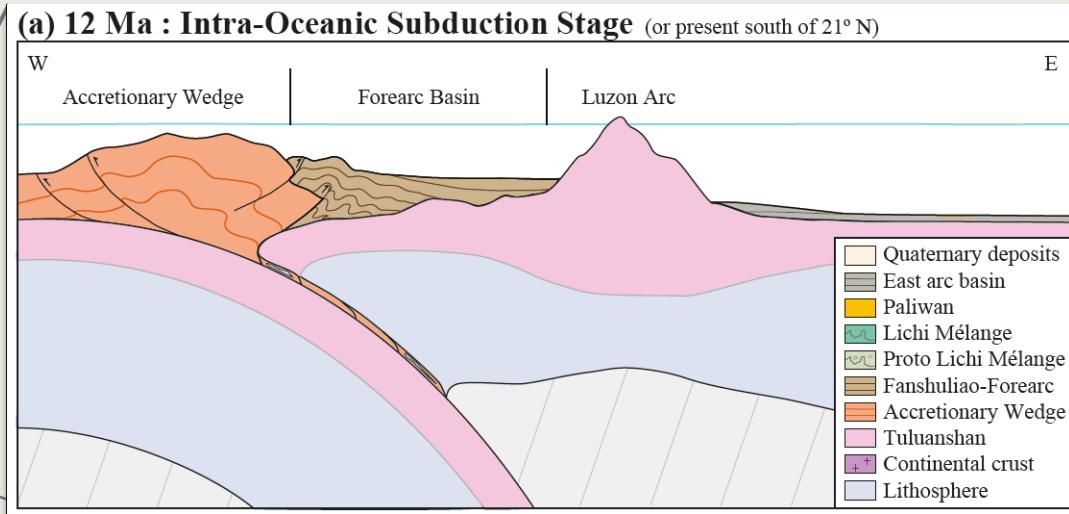
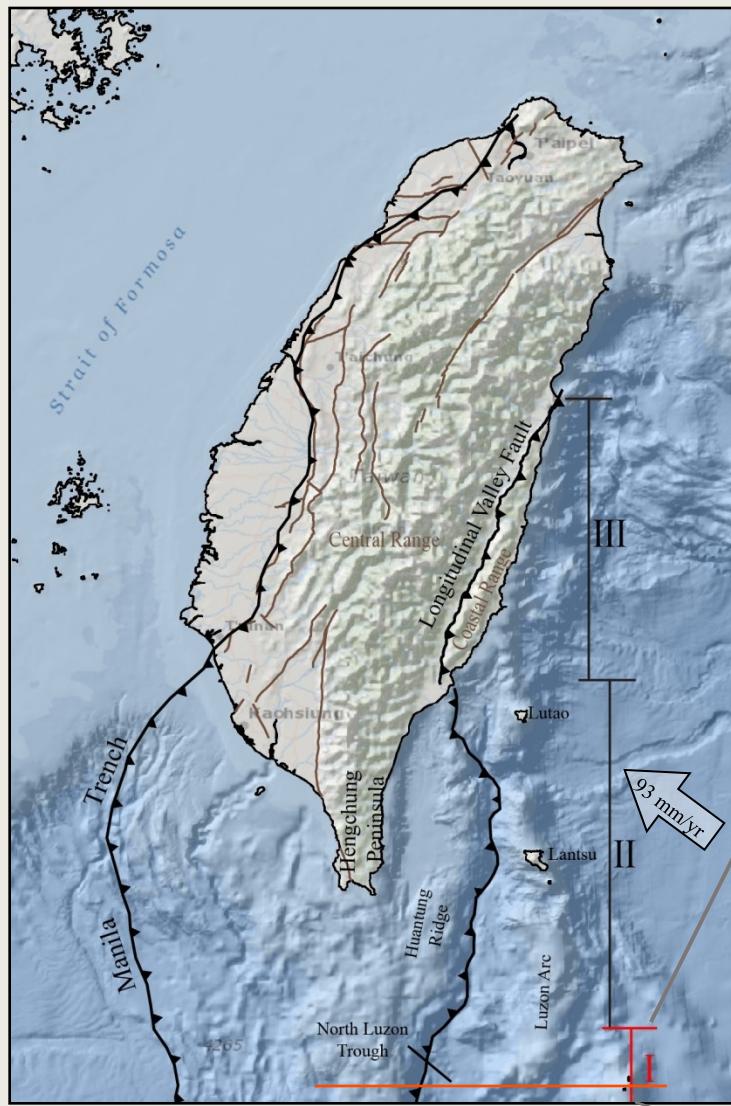
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GEOLOGICAL SETTING : TECTONIC SCENARIO, early stage

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

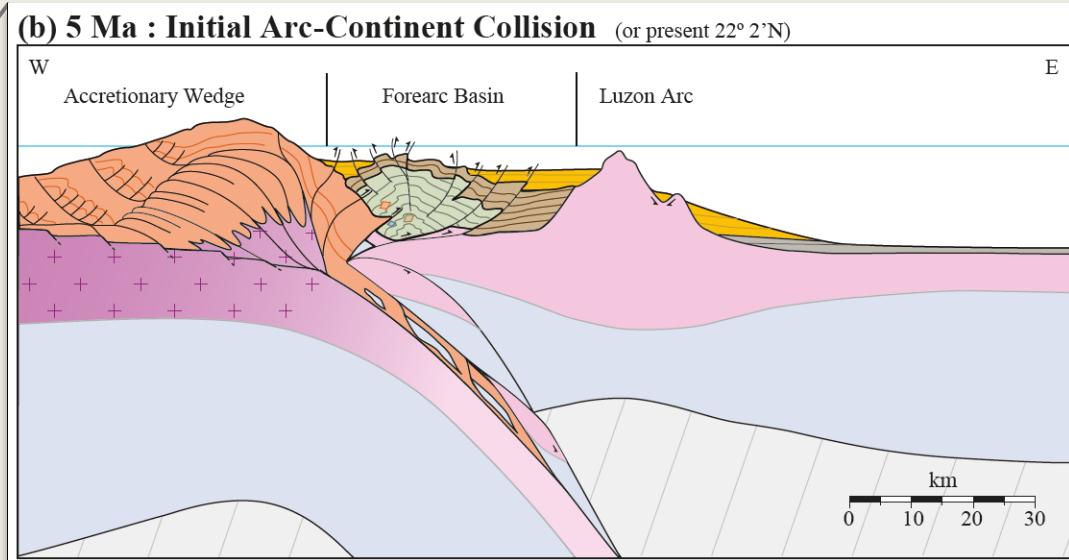
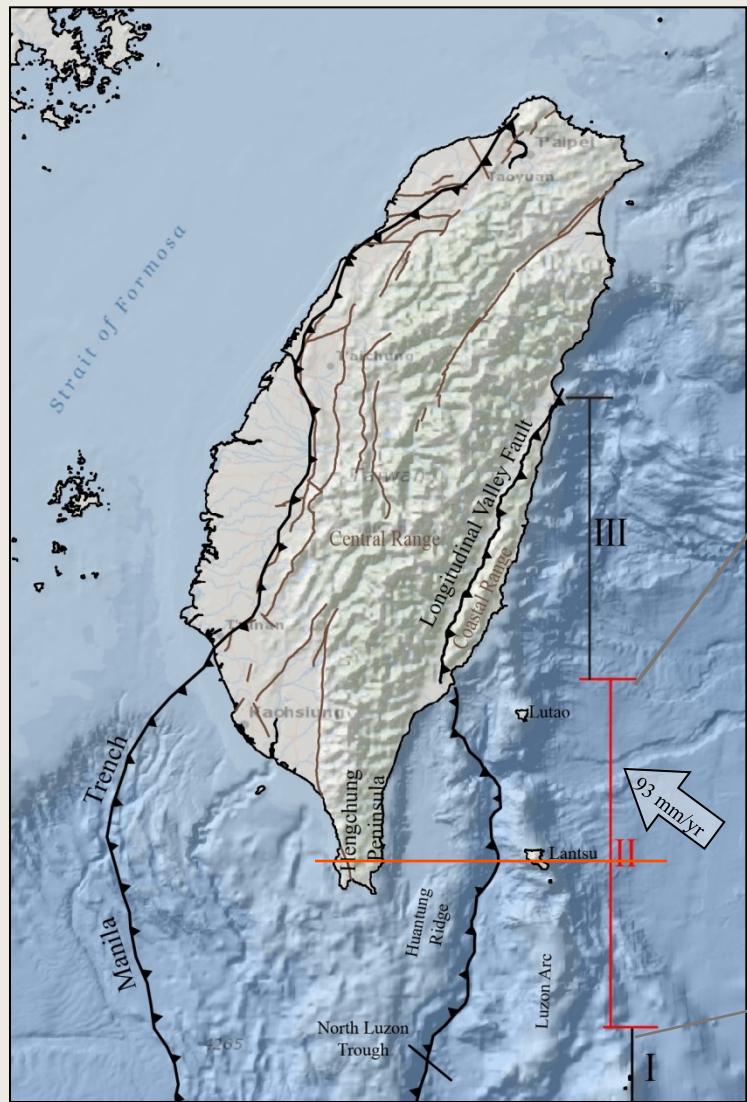
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GEOLOGICAL SETTING : TECTONIC SCENARIO, initial collision

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

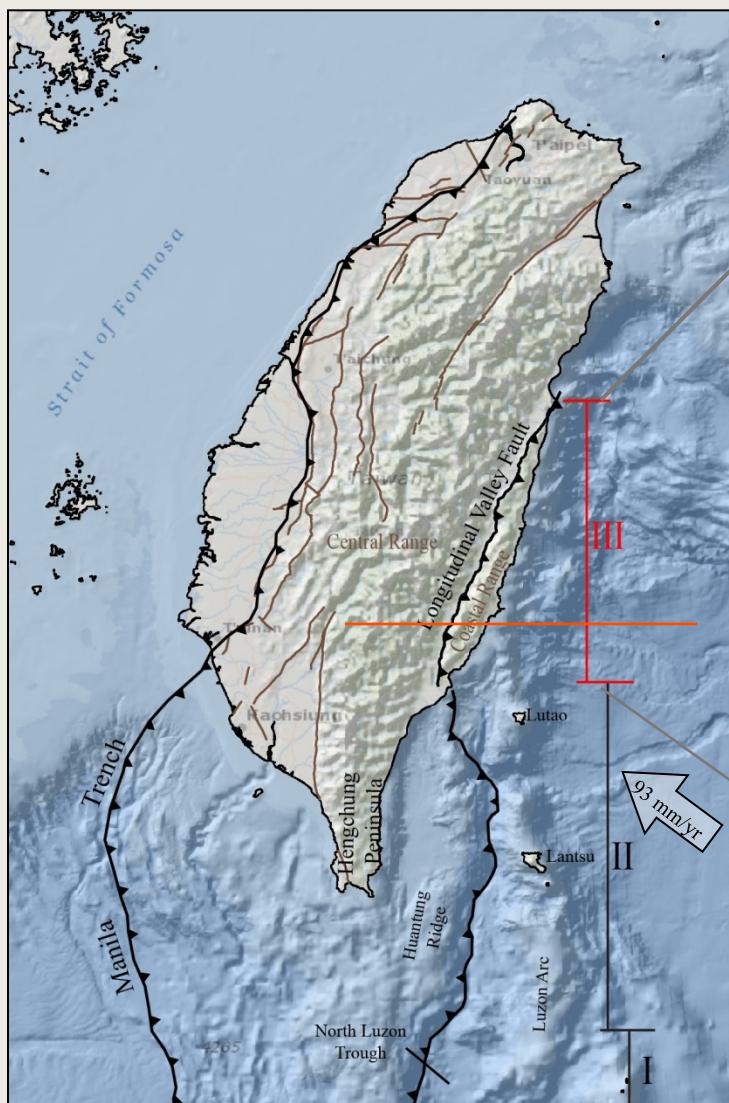
6/36



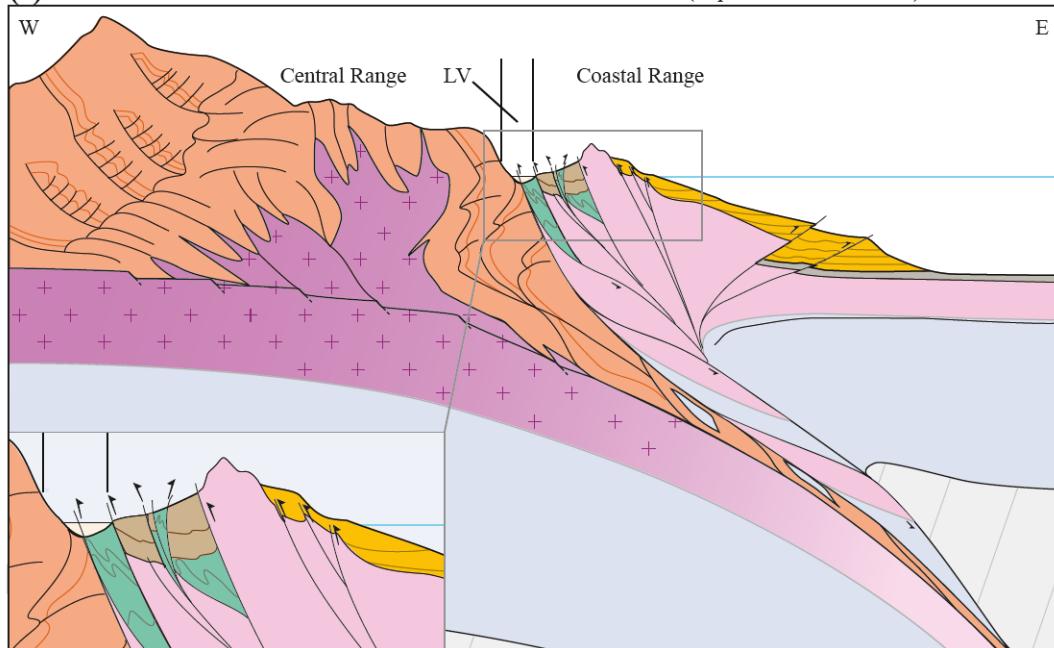
GEOLOGICAL SETTING : TECTONIC SCENARIO, advance collision

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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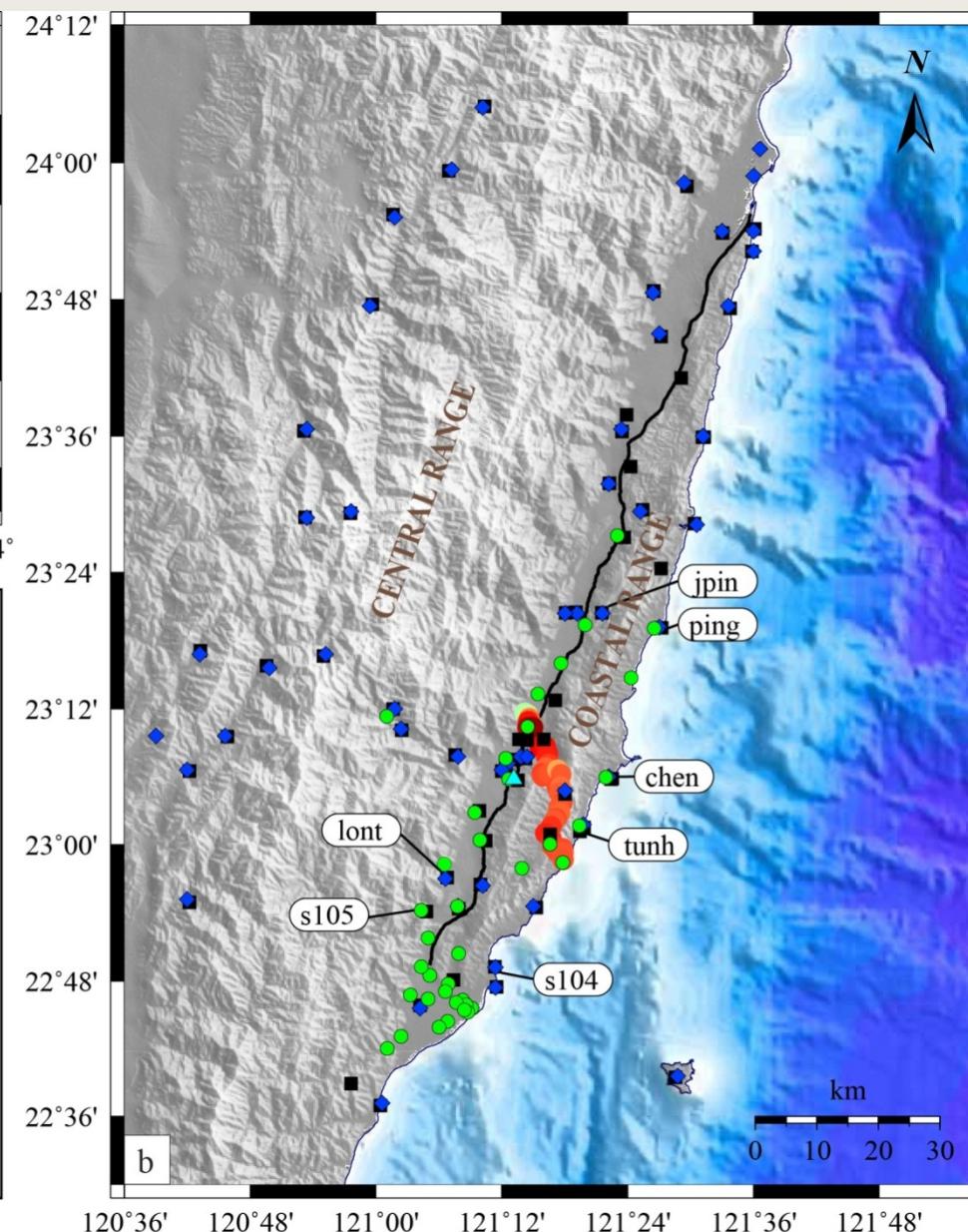
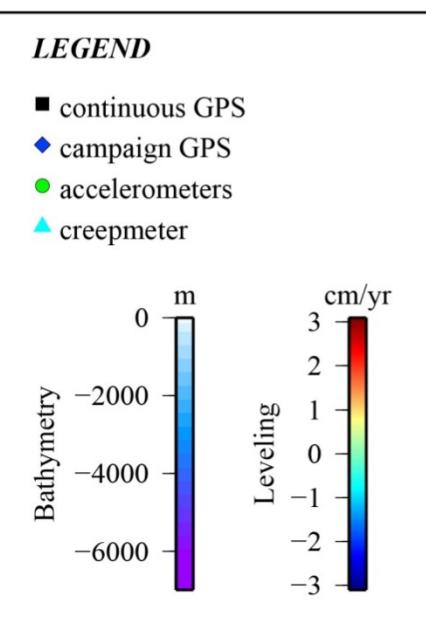
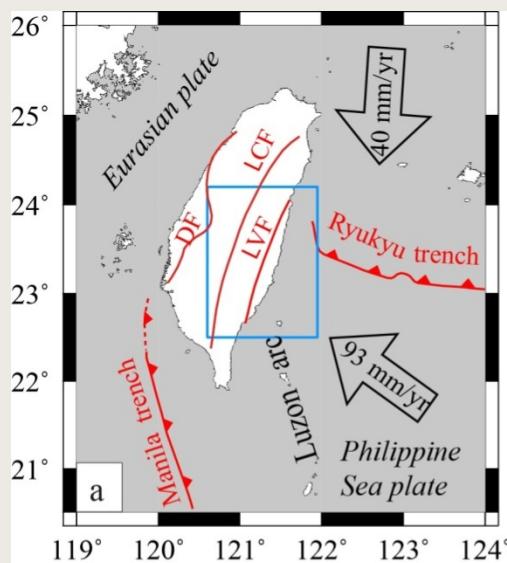
(c) Present : Advanced Arc-Continent Collision (or present north of 23° N)



AVAILABLE DATA

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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GPS times series
From 1994 to 2011
Tec websites
67 stations

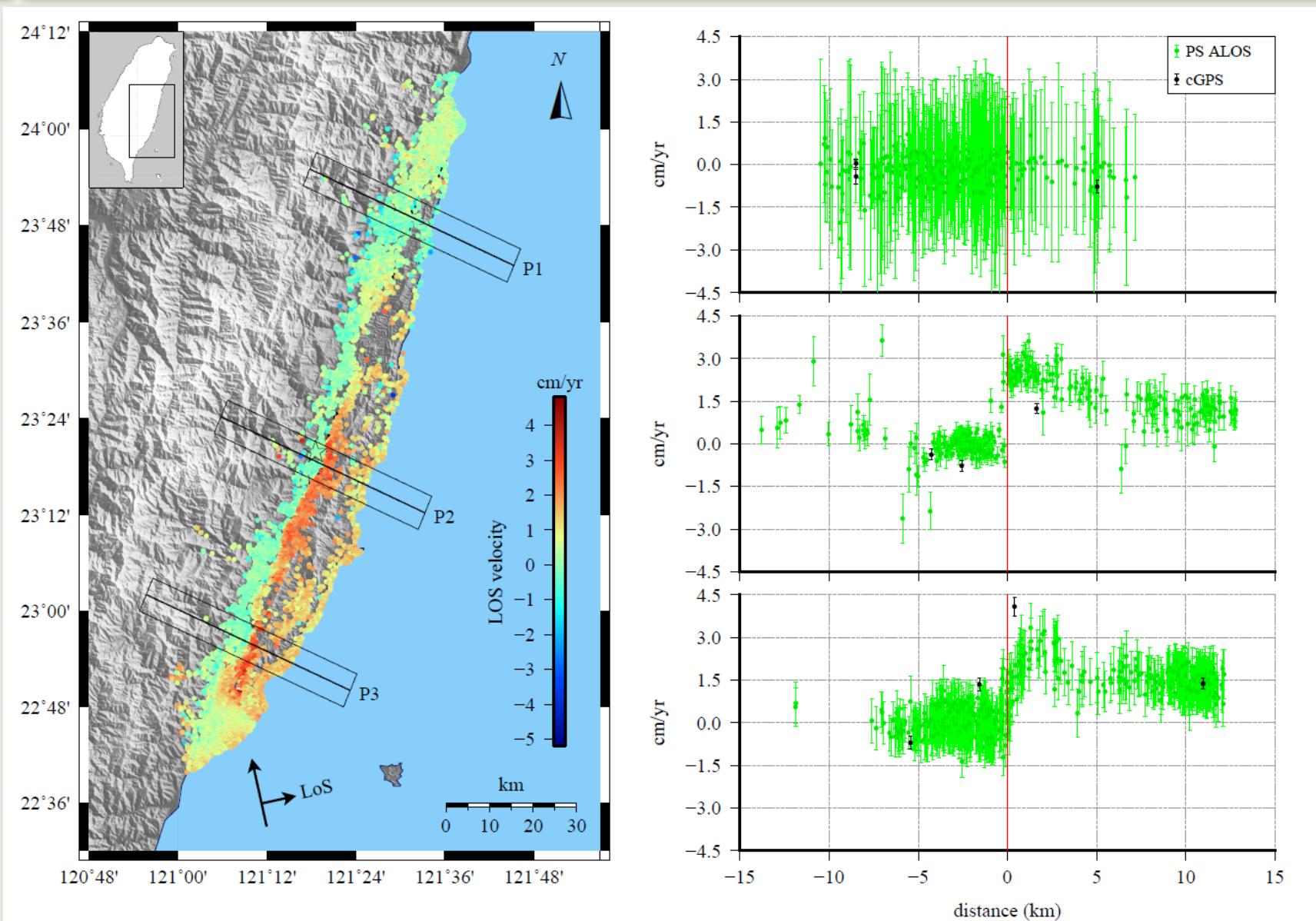
Campaign GPS
From 1992 to 1999
Yu et al, 2001
45 stations

Creepmeter
From 2009 to 2010
Lee et al, 2001

Accelerometers
2003 Chengkung
EQ
Wu et al, 2006
38 stations

Leveling
From 2007 to 2010
Chen et al, 2012

AVAILABLE DATA

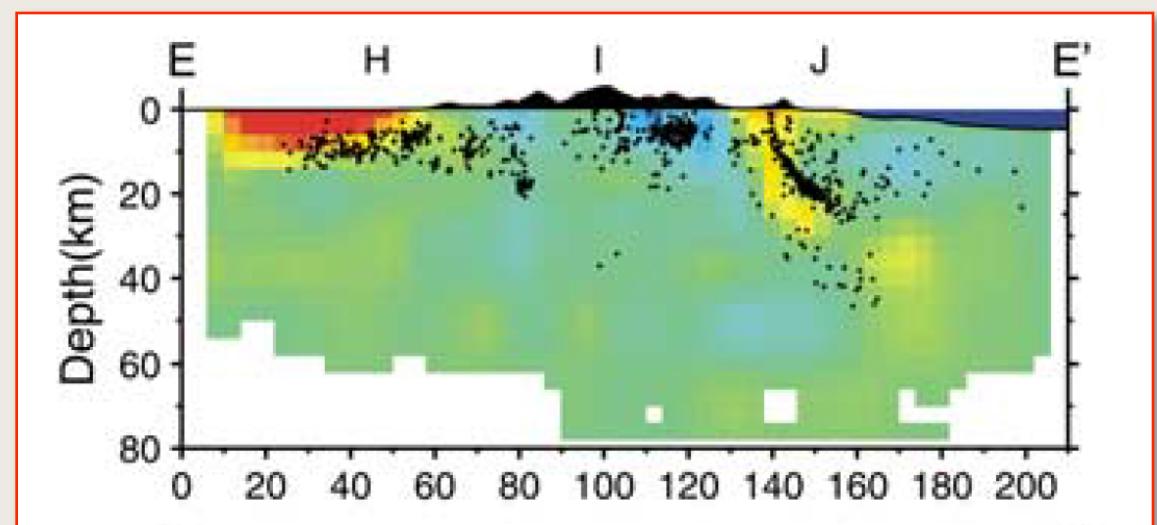
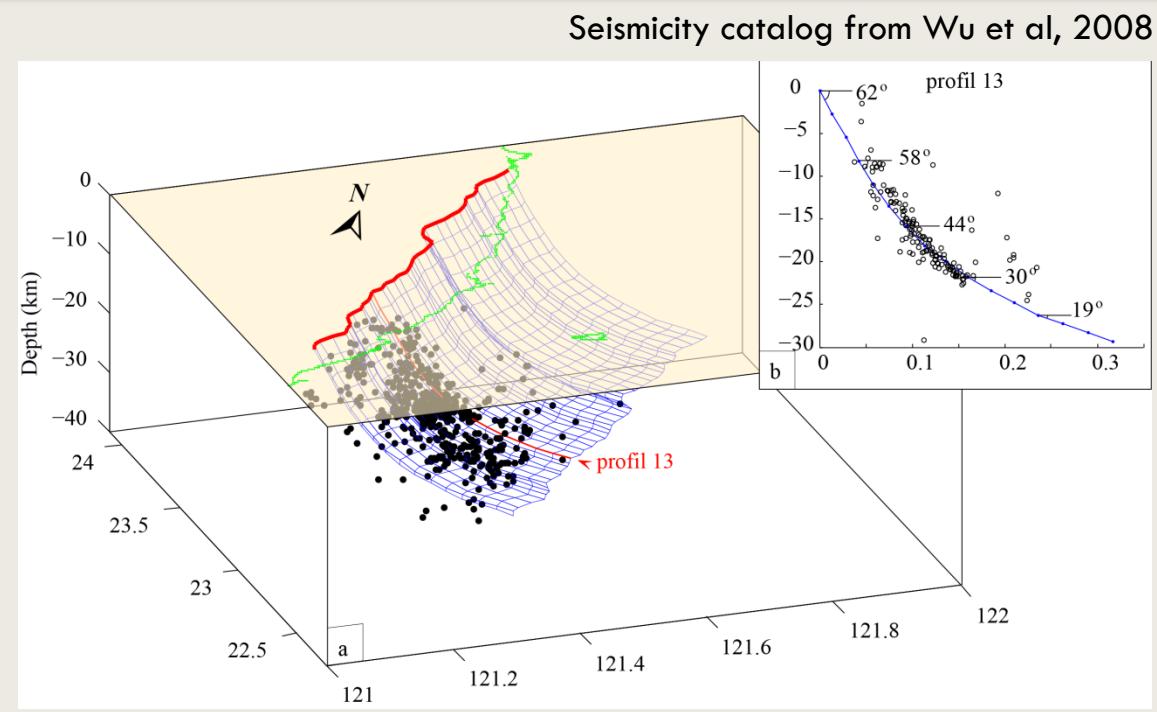
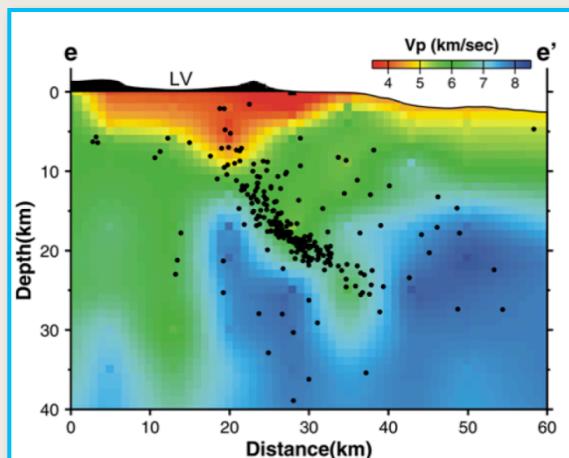
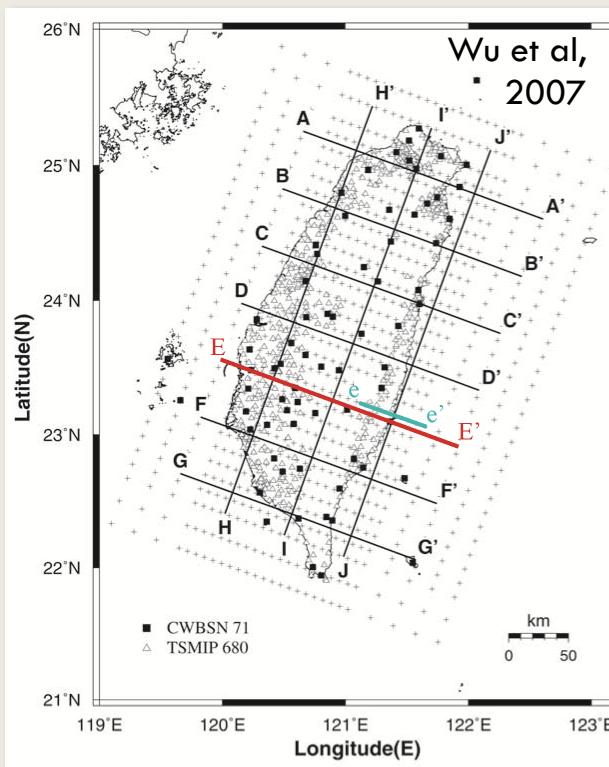


ALOS PS-InSAR mean velocities, From 2007 to 2010, Champenois et al, 2012

FAULT GEOMETRY

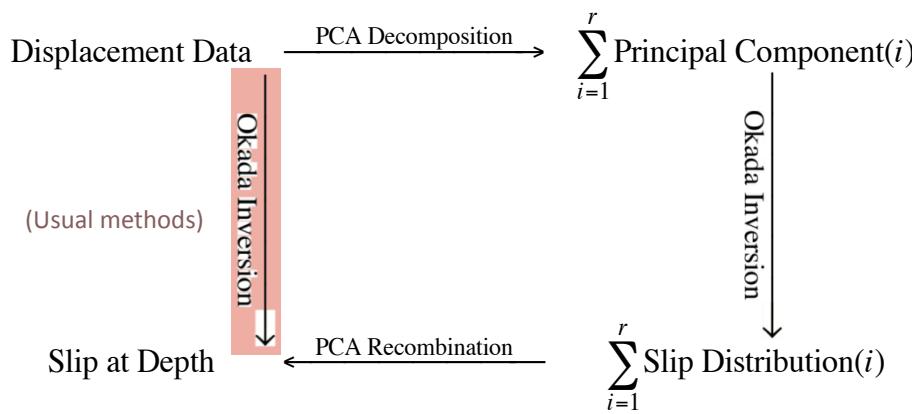
1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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- Surface displacements is converted to slip based on theory of dislocation in elastic half-space (Okada 1985).
- Regularization: Laplacian proportional to resolution.
- Time - dependent inversion : PCAIM

PCAIM METHOD



$$\begin{aligned}
 X &= USV^t \\
 U &= GG \cdot L \\
 X &= (GG \cdot L) SV^t \\
 X &= GG (LSV^t)
 \end{aligned}$$

Singular Value Decomposition
of surface displacement series
+
least-square
inversion formulation
=
Slip decomposition

TIME-INDEPENDENT INVERSION: SECULAR MODEL, POLE CORRECTION

1. Introduction

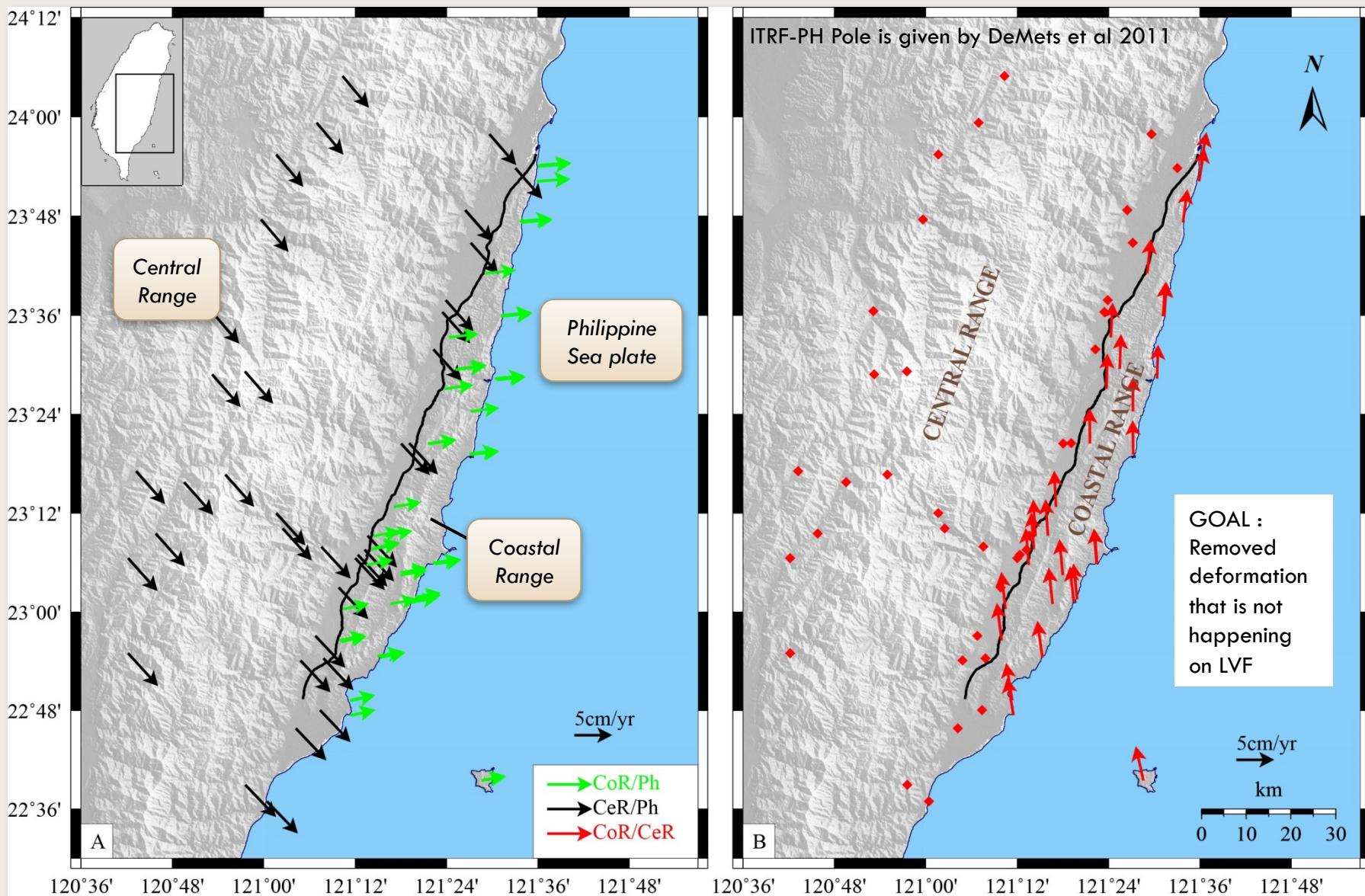
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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TIME-INDEPENDENT INVERSION: SECULAR MODEL

1. Introduction

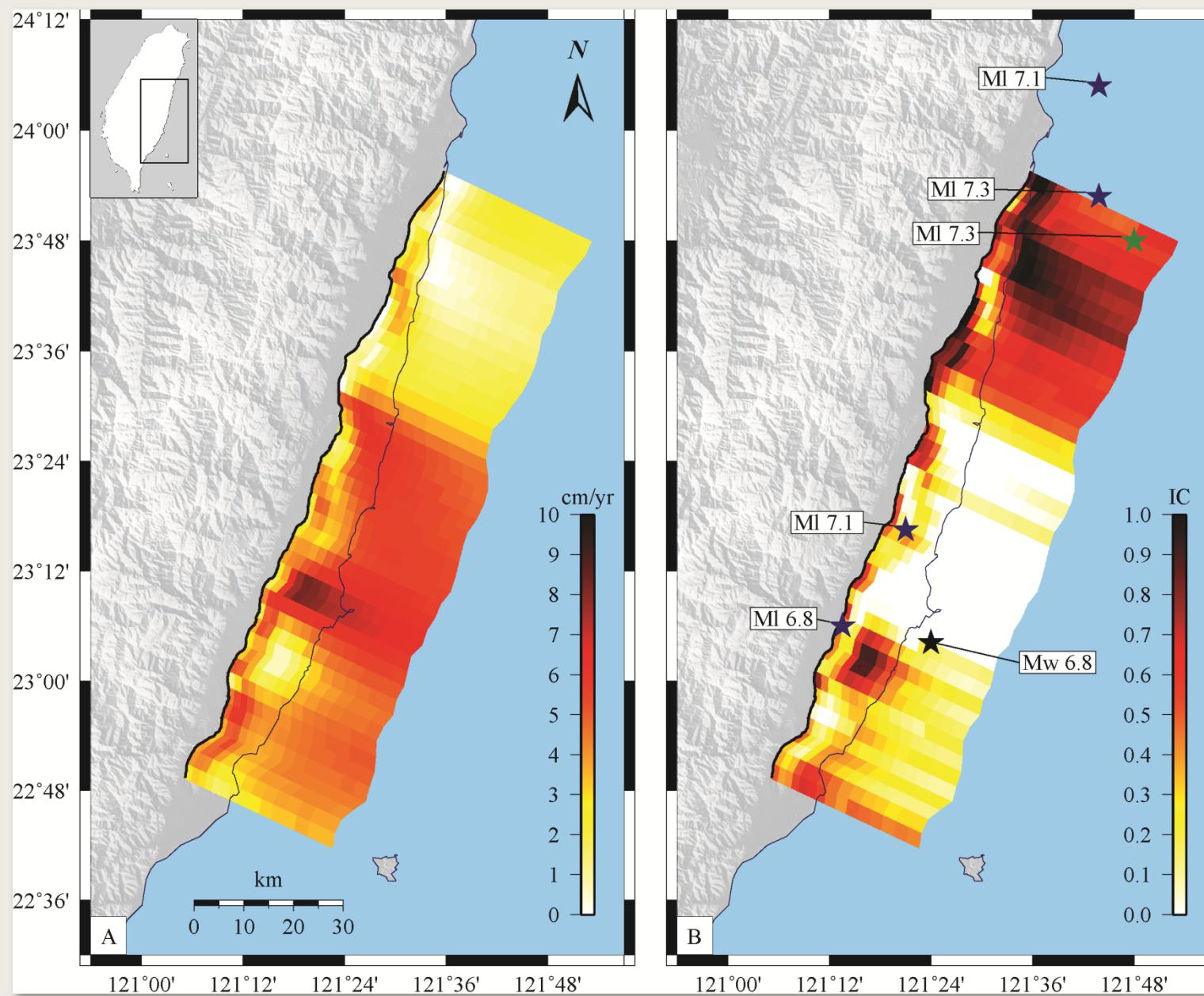
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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Figures :
A] = Slip at depth
(mm/yr)

B] = Coupling

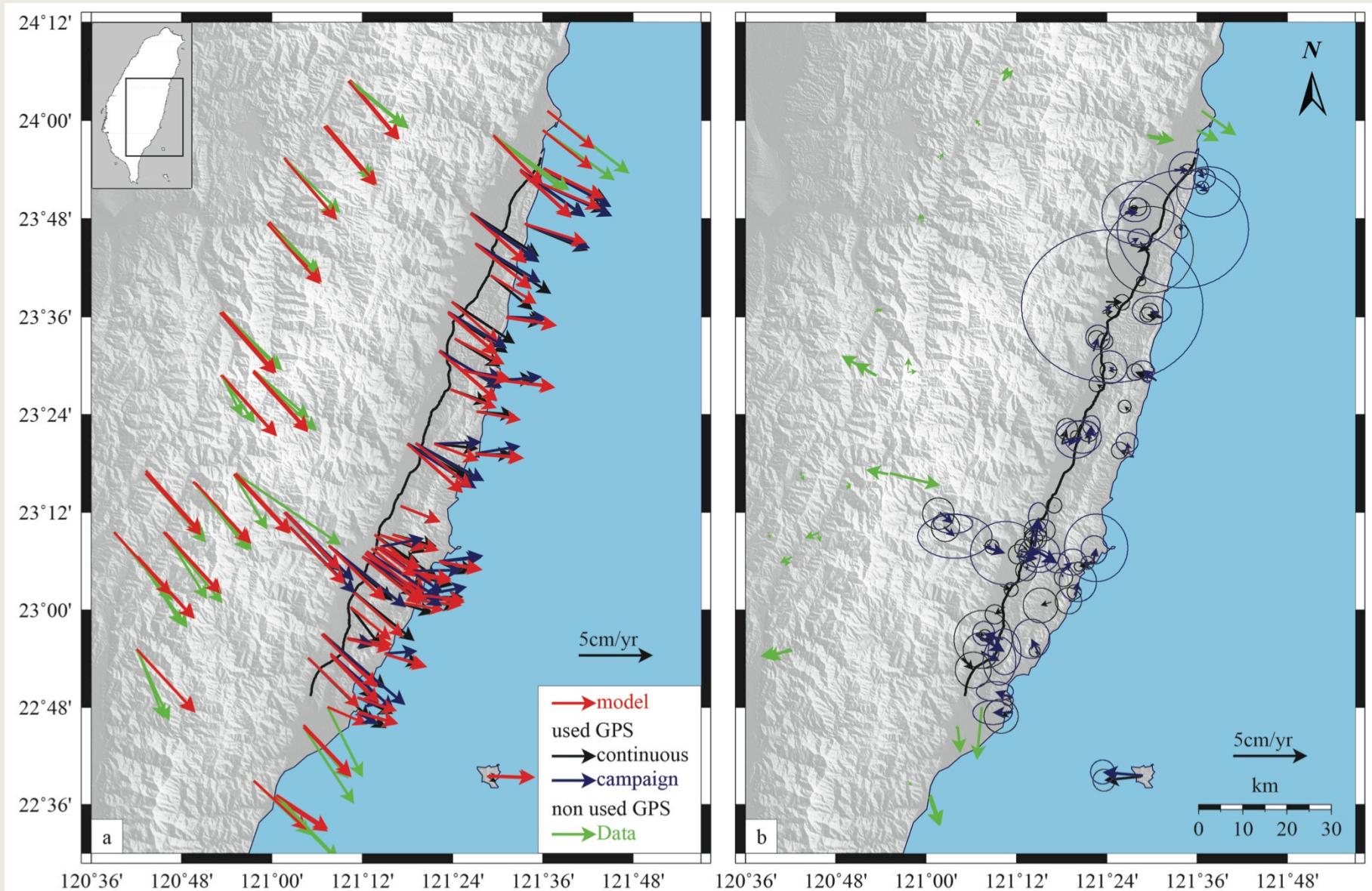
Inversion based on:

- campaign GPS (Yu, 2001),
- secular velocities from cGPS (TEC),
- PS ALOS (Champenois, 2012)
- leveling data (Chen, 2012)

TIME-INDEPENDENT INVERSION: SECULAR GPS FIT

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

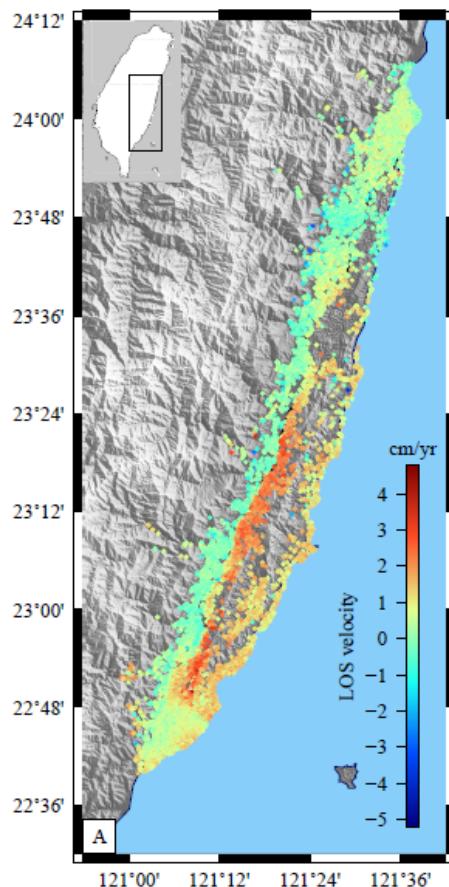
13/36



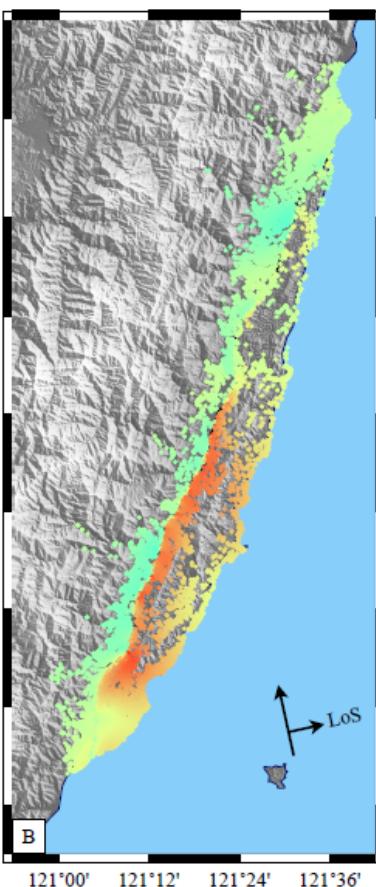
Data and model prediction of campaign GPS (Yu, 2001) and secular velocities from cGPS (TEC)

TIME-INDEPENDENT INVERSION: SECULAR PS ALOS AND LEVELING FIT

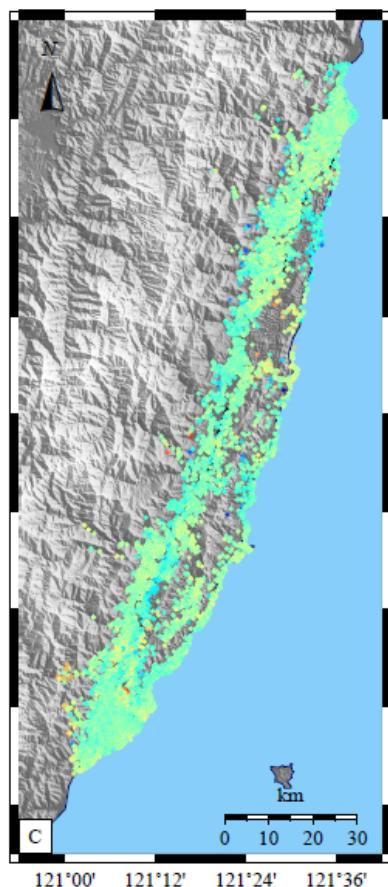
Data



Model



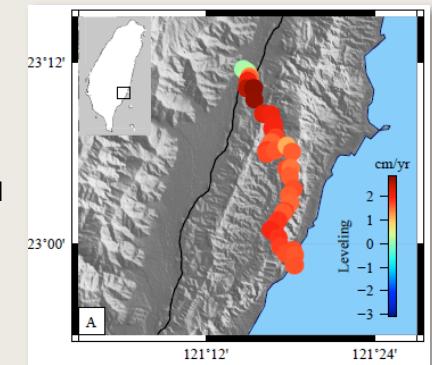
Residuals



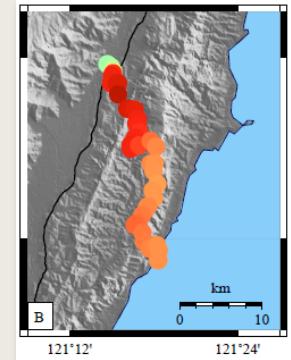
PS ALOS mean velocities (data from Champenois et al, 2012)

leveling measurements
(data from Chen, 2012)

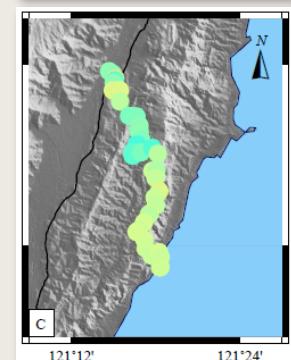
Data



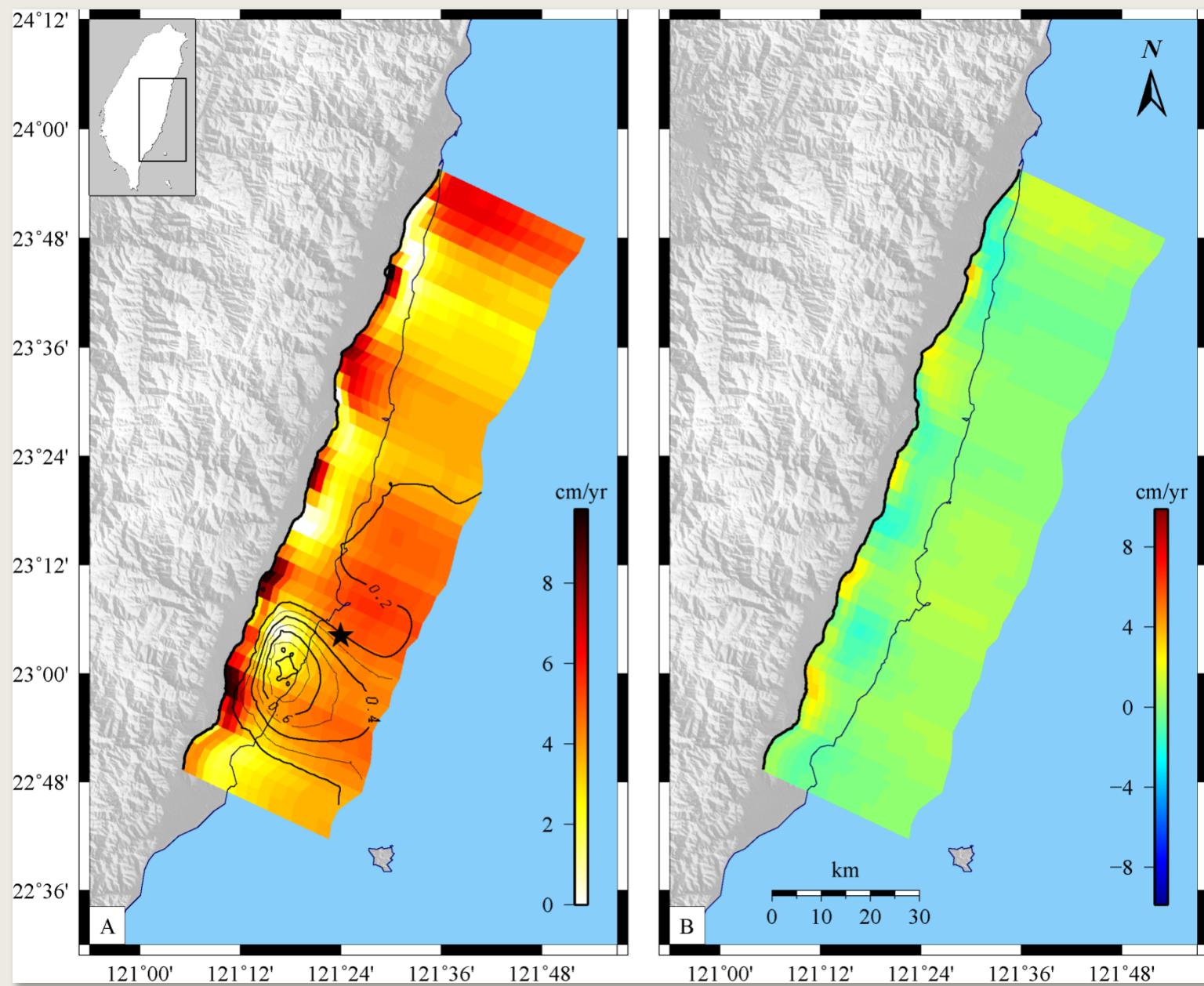
Model



Residuals



PCAIM: PRESEISMIC MODEL

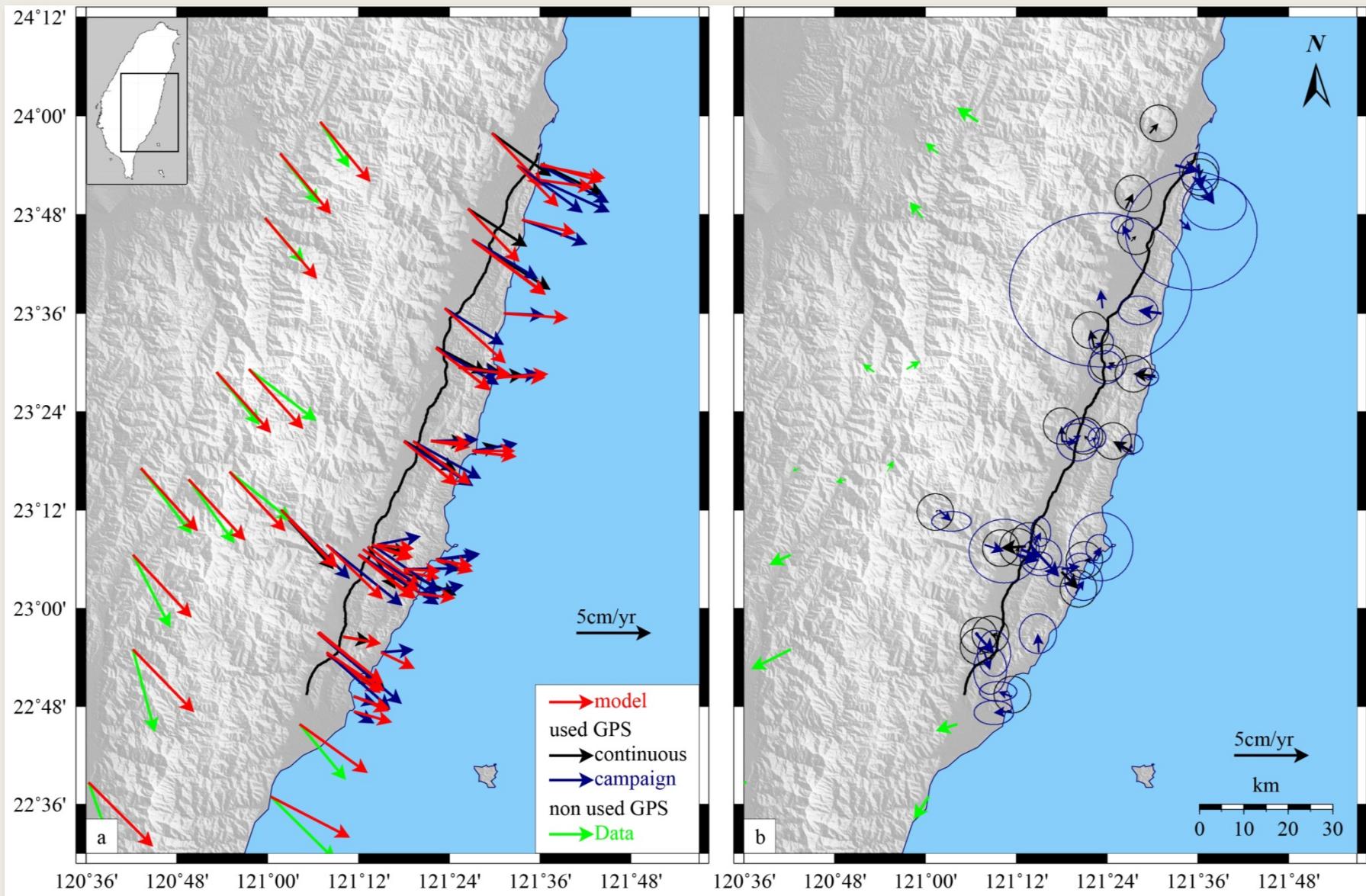


Figures :
A] = PCAIM
inversion for Slip at
depth (mm/yr)

B] = PCAIM inversion
minus secular model

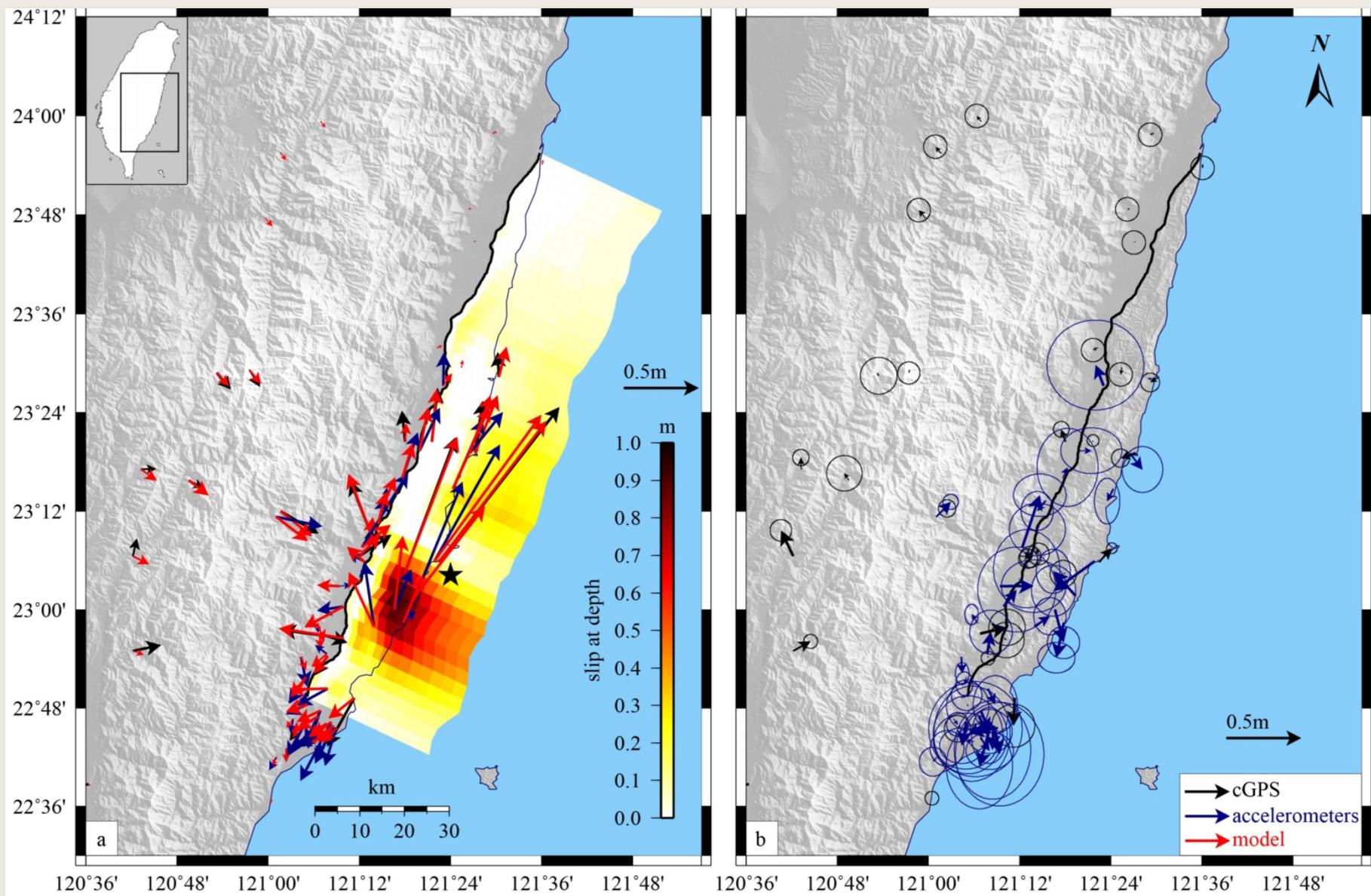
Inversion based on:

- campaign GPS (Yu, 2001),
- Continuous GPS (TEC),
- Creepmeter (Lee et al, 2001)



Data and model prediction of campaign GPS (Yu, 2001) and continuous GPS (TEC)

TIME-INDEPENDENT INVERSION: COSEISMIC, Mw 6.8 CHENGKUNG EQ (2003)



Model based on GPS (TEC), and accelerometers (Wu et al, 2006)

TIME-INDEPENDENT INVERSION: COSEISMIC & SECULAR MODEL

1. Introduction

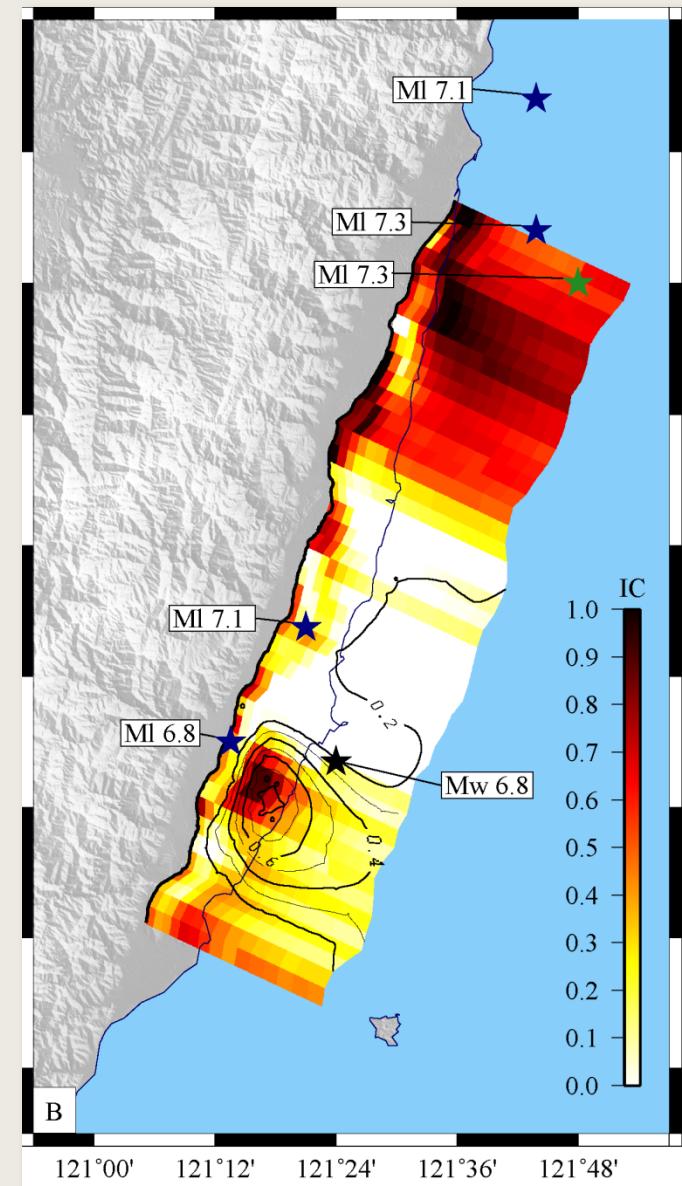
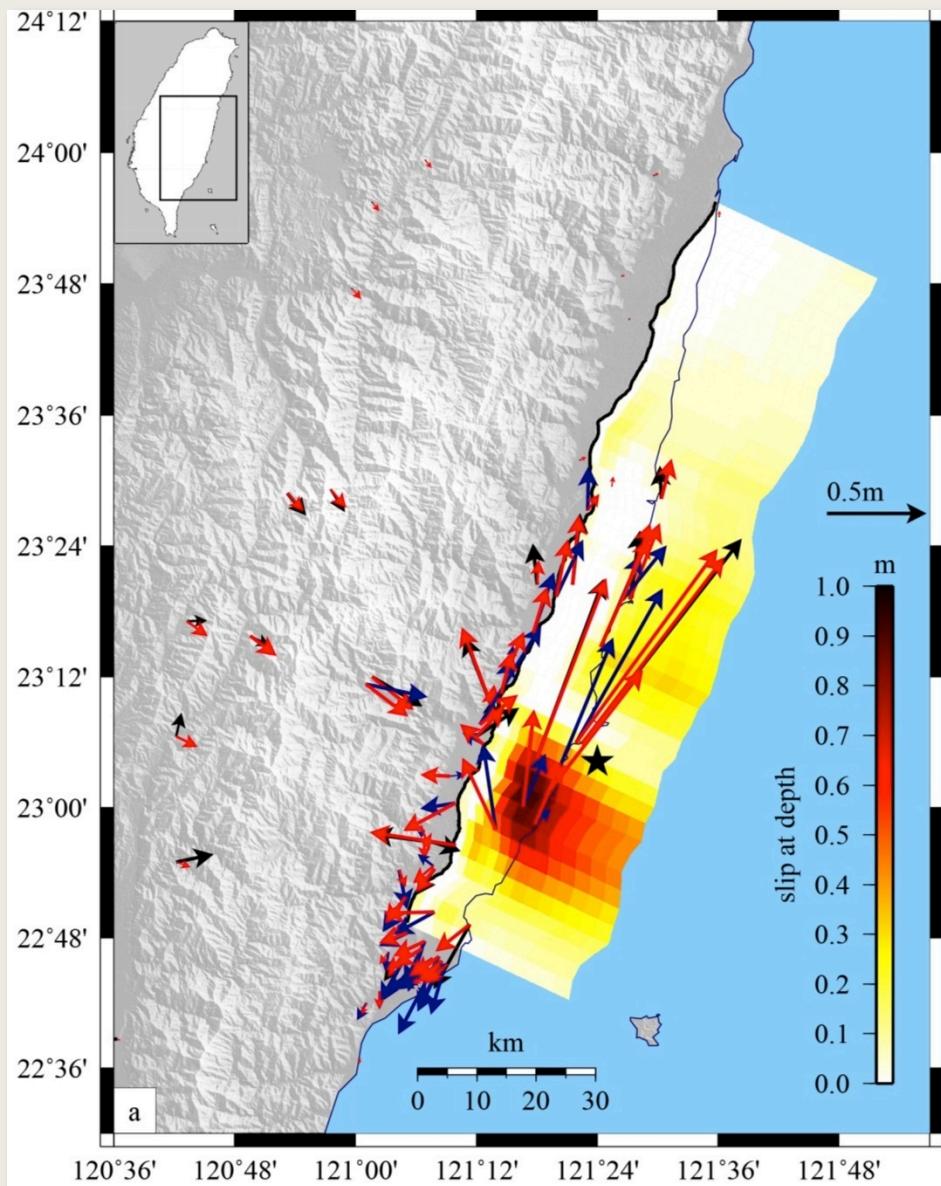
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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Model based on GPS (TEC), and accelerometers (Wu et al, 2006)

PCAIM: POSTSEISMIC MODEL, Mw 6.8 CHENGKUNG EARTHQUAKE (2003)

1. Introduction

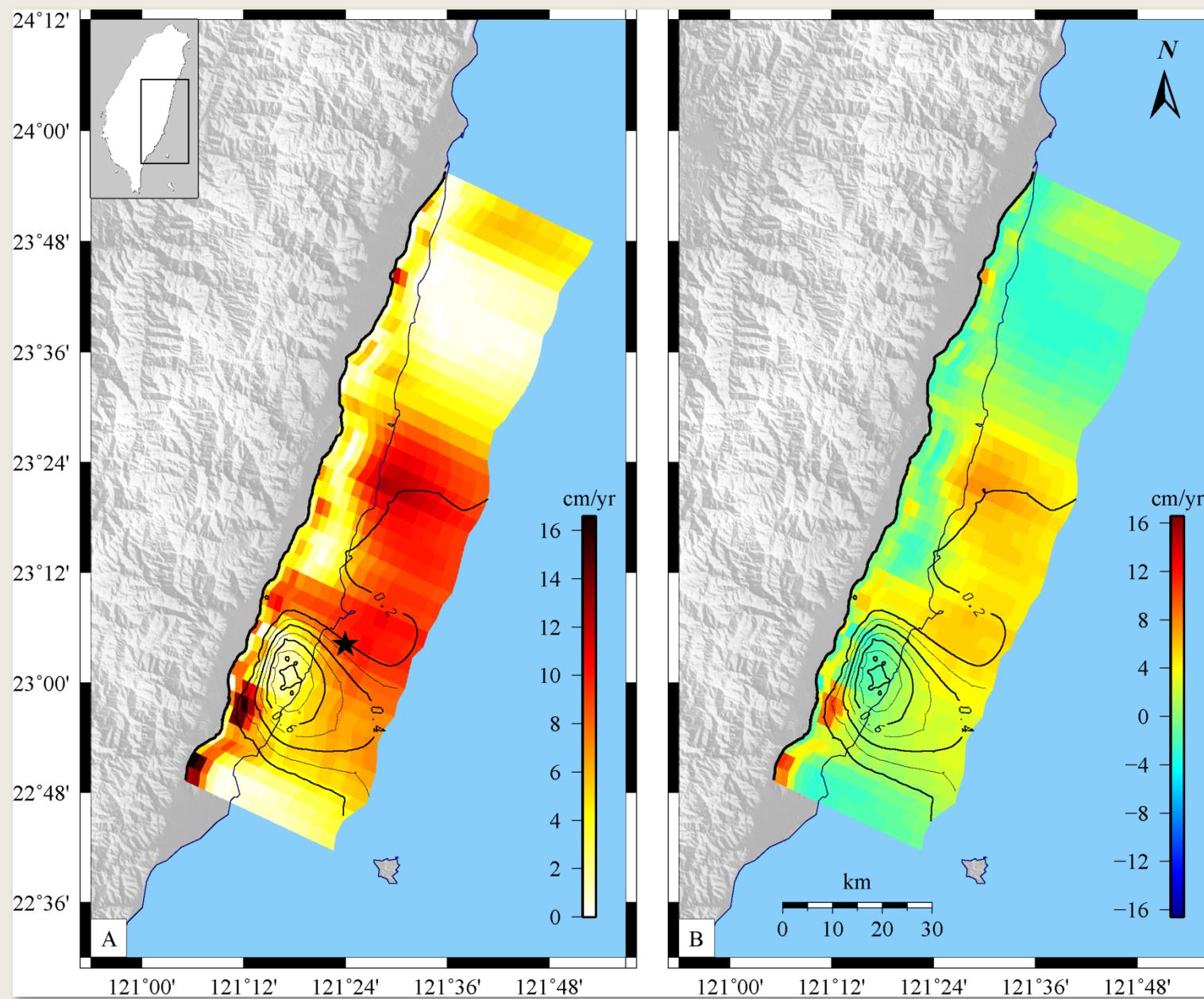
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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Figures :

A] = PCAIM
inversion for Slip at
depth (mm/yr)

B] = PCAIM inversion
minus secular model

Inversion based on:

- Continuous GPS (TEC)
- PS ALOS (Champenois, 2012)
- Leveling data (Chen, 2012)
- Creepmeter (Lee et al, 2001)

PCAIM: POSTSEISMIC GPS FIT, Mw 6.8 CHENGKUNG EARTHQUAKE (2003)

1. Introduction

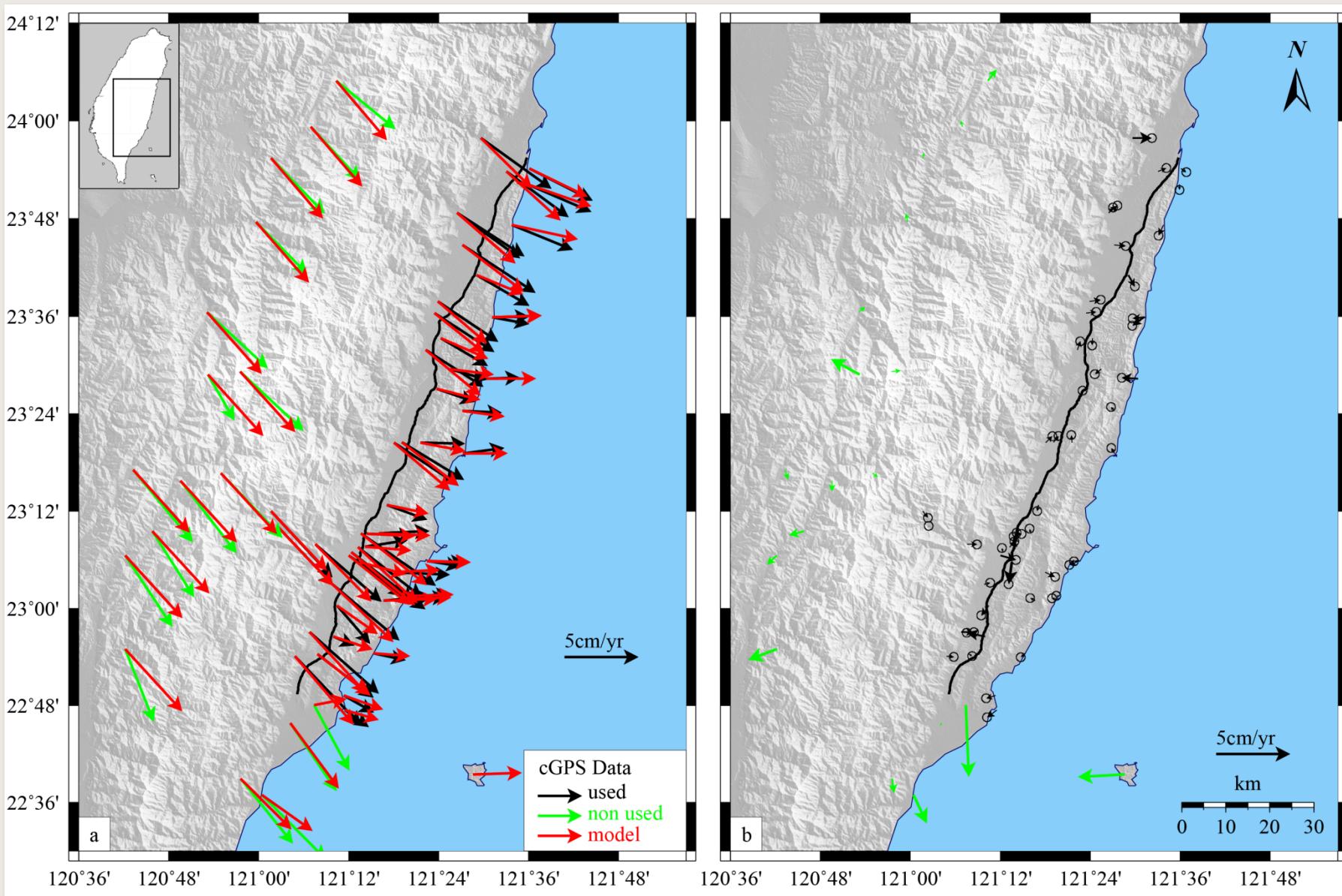
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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Data and model prediction of continuous GPS (TEC)

PCAIM: POSTSEISMIC ALOS FIT, Mw 6.8 CHENGKUNG EARTHQUAKE (2003)

1. Introduction

2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

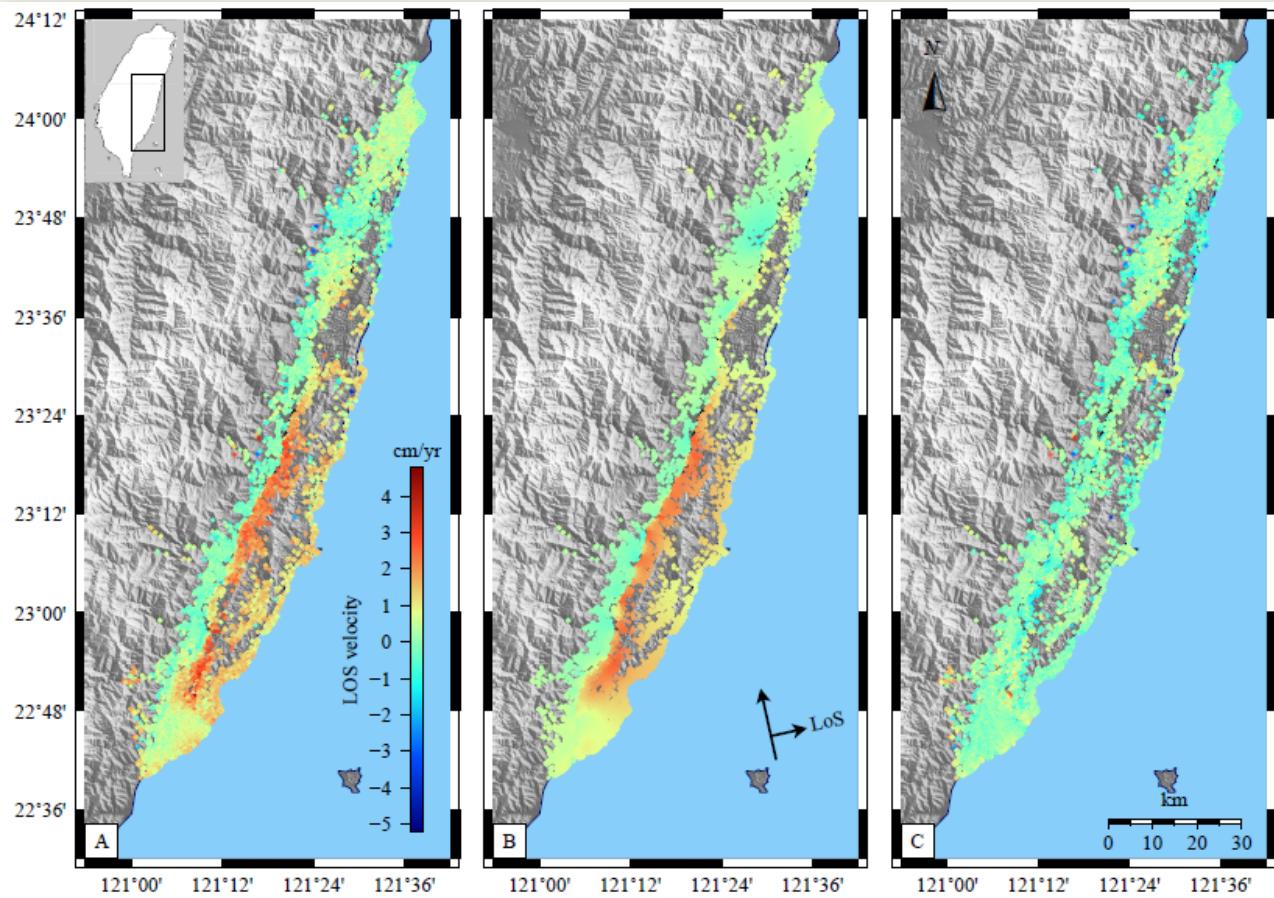
5. Conclusion

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Data

Model

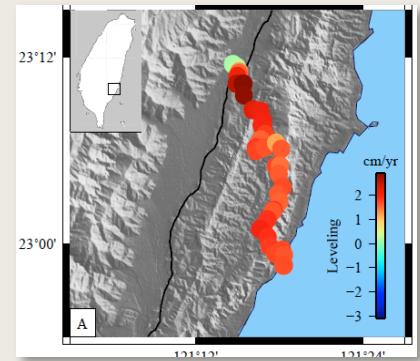
Residuals



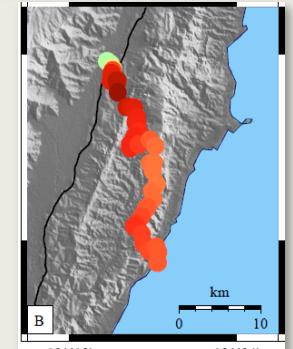
PS ALOS mean velocities (data from Champenois et al, 2012)

leveling measurements
(data from Chen, 2012)

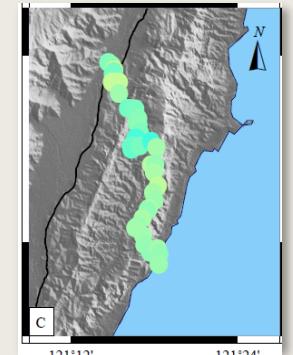
Data



Model



Residuals



DATA FIT: GPS STATION “CHEN”

1. Introduction

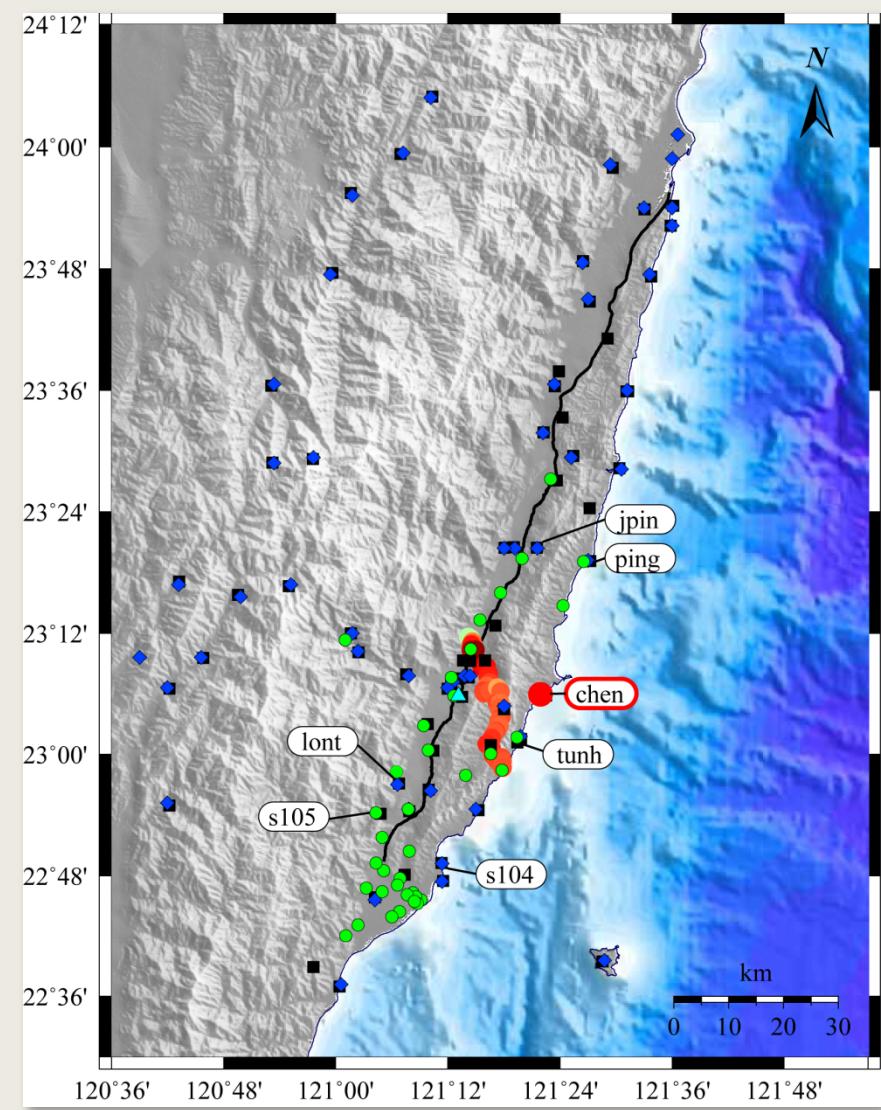
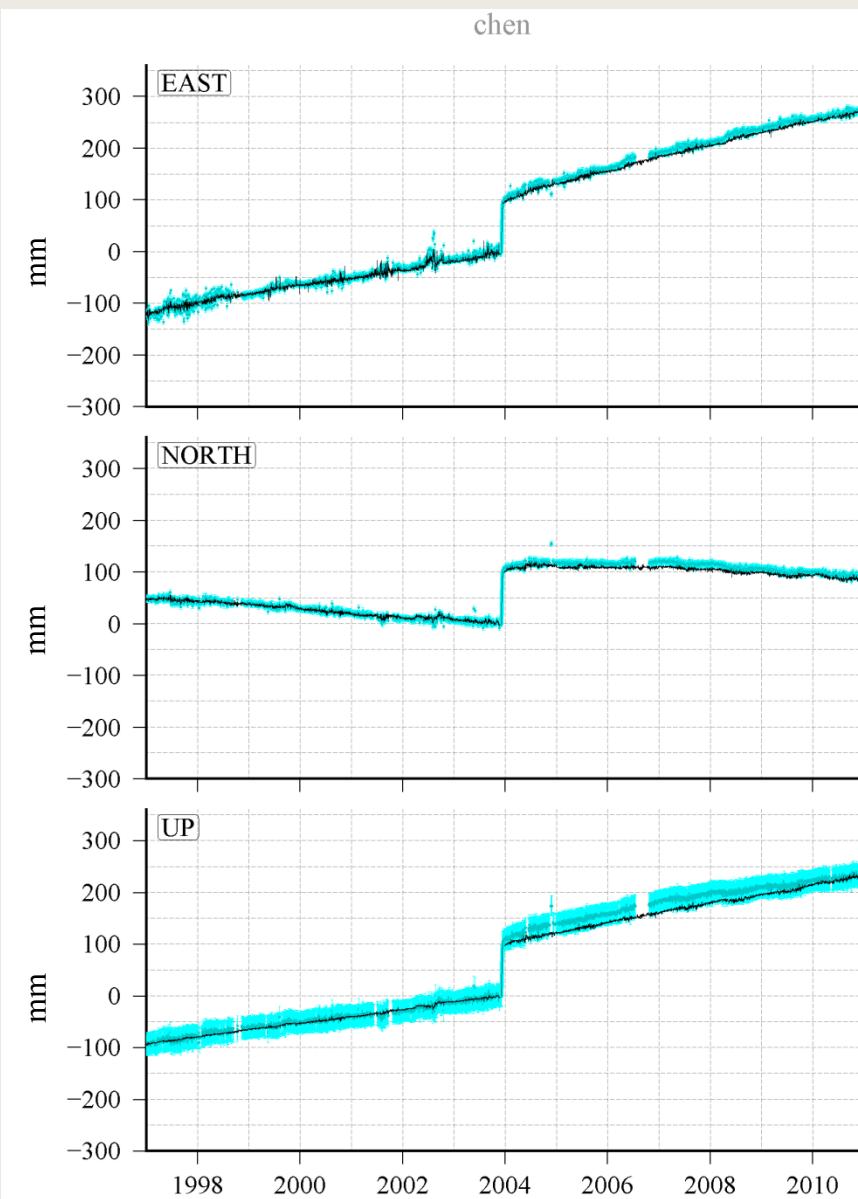
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

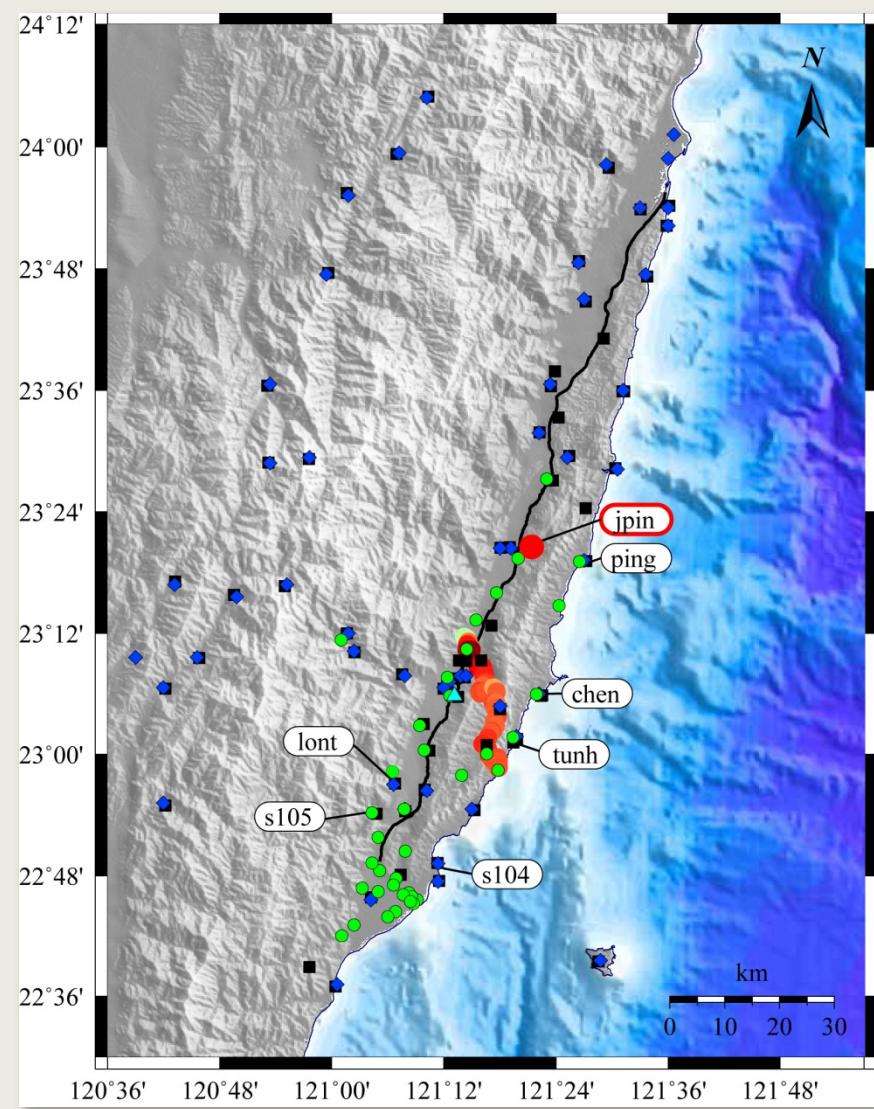
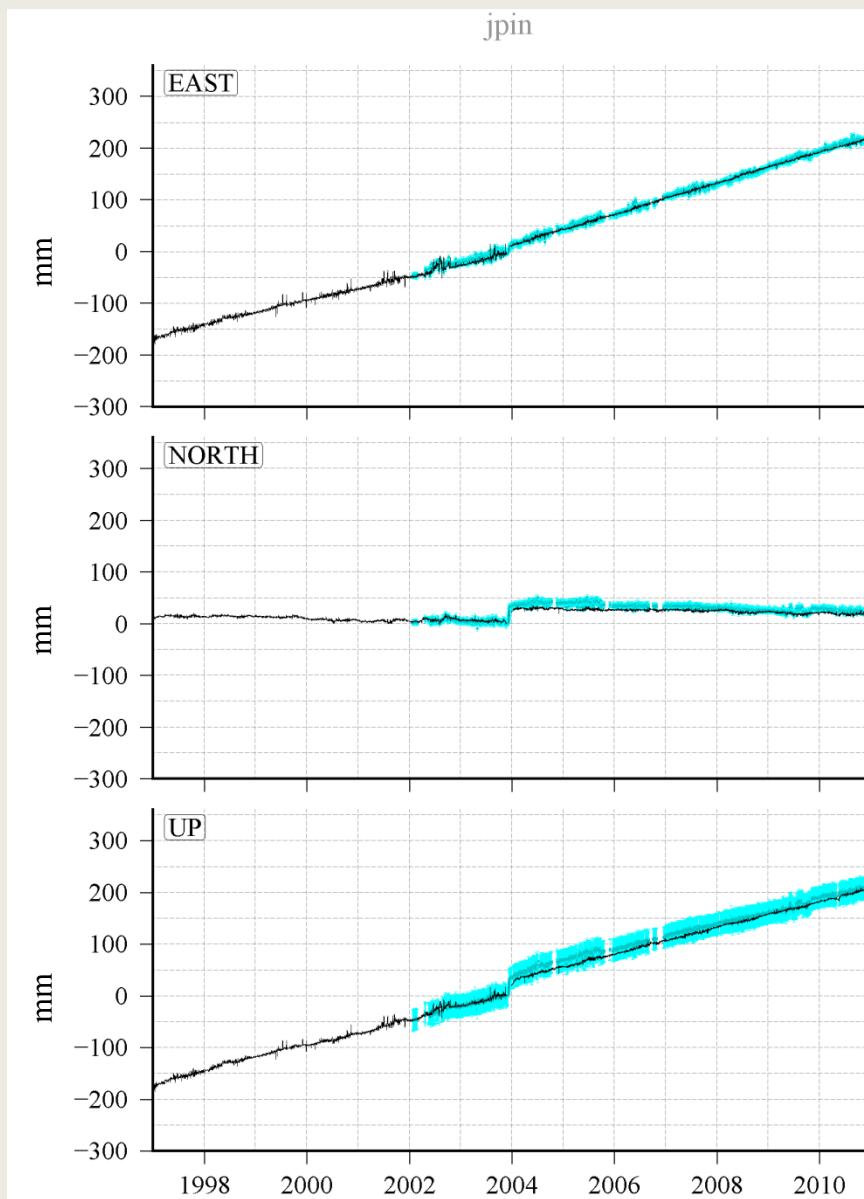
4. Deformation Mechanisms

5. Conclusion

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DATA FIT: GPS STATION "JPIN"



DATA FIT: GPS STATION “LONT”

1. Introduction

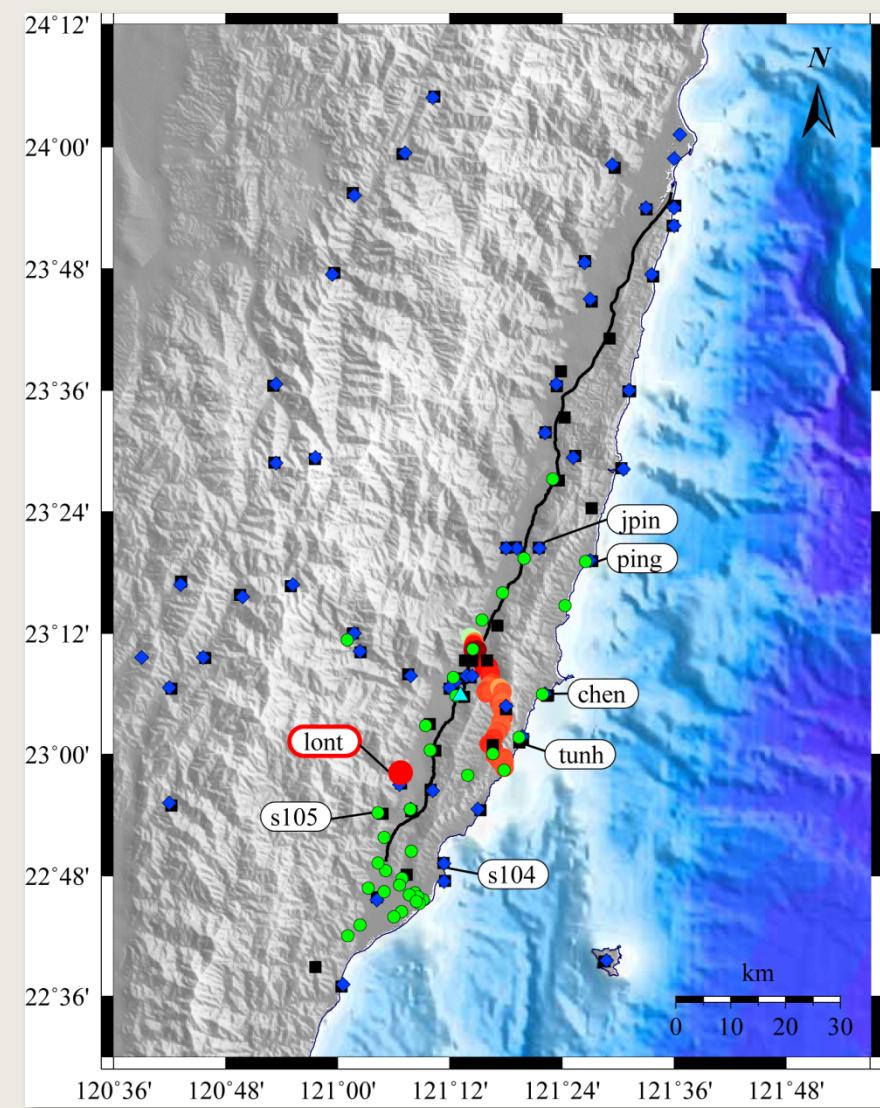
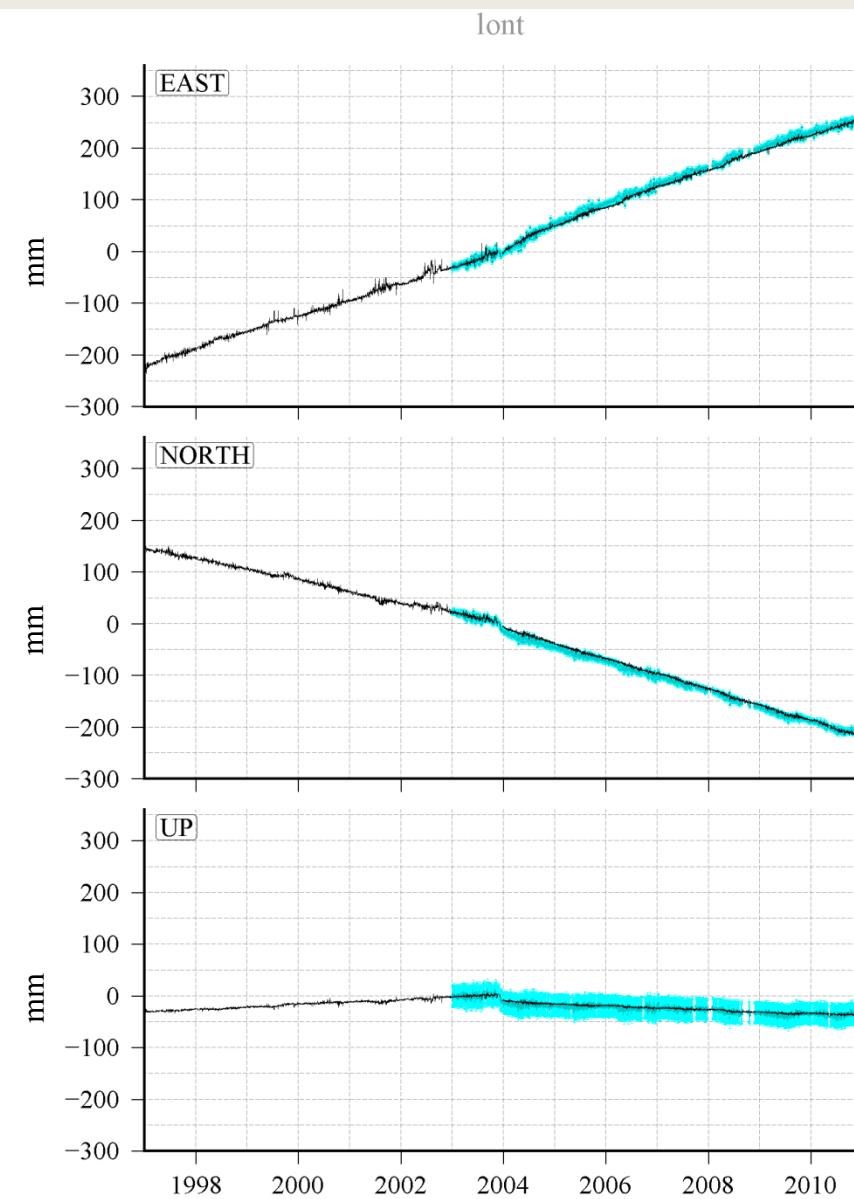
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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DATA FIT: GPS STATION “PING”

1. Introduction

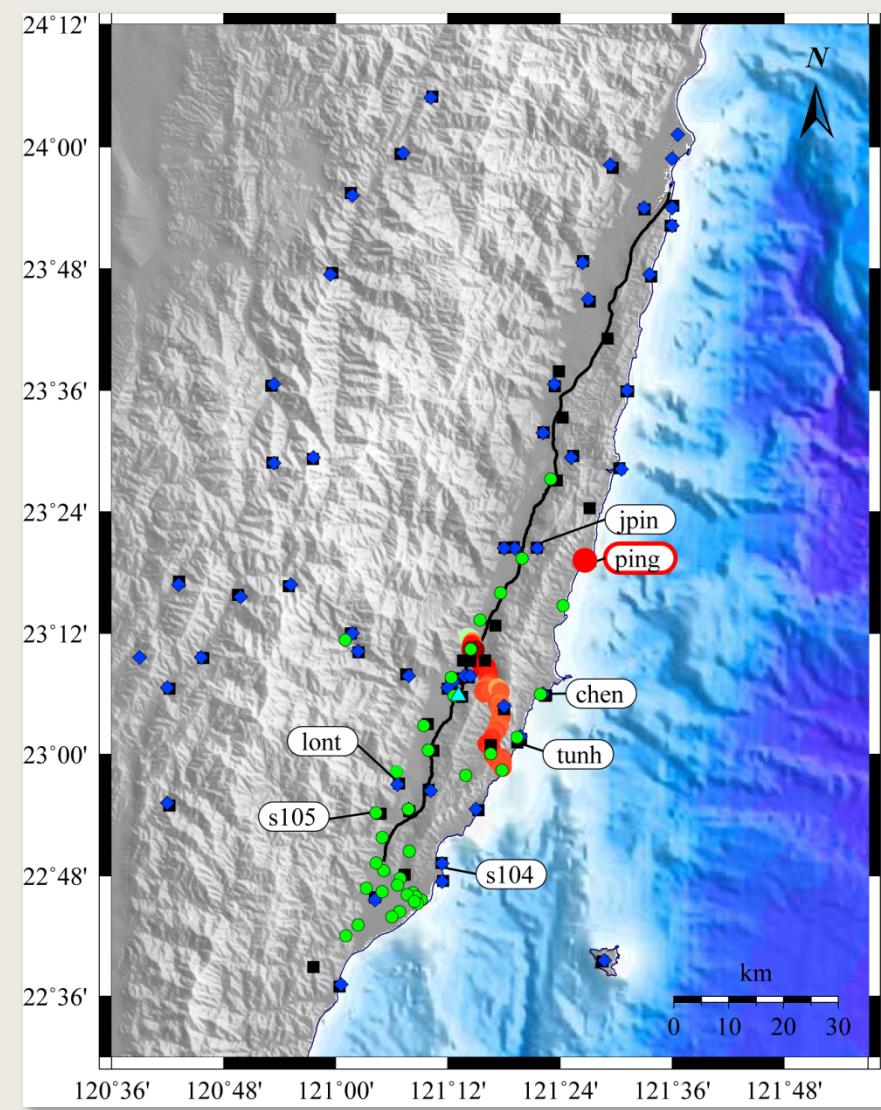
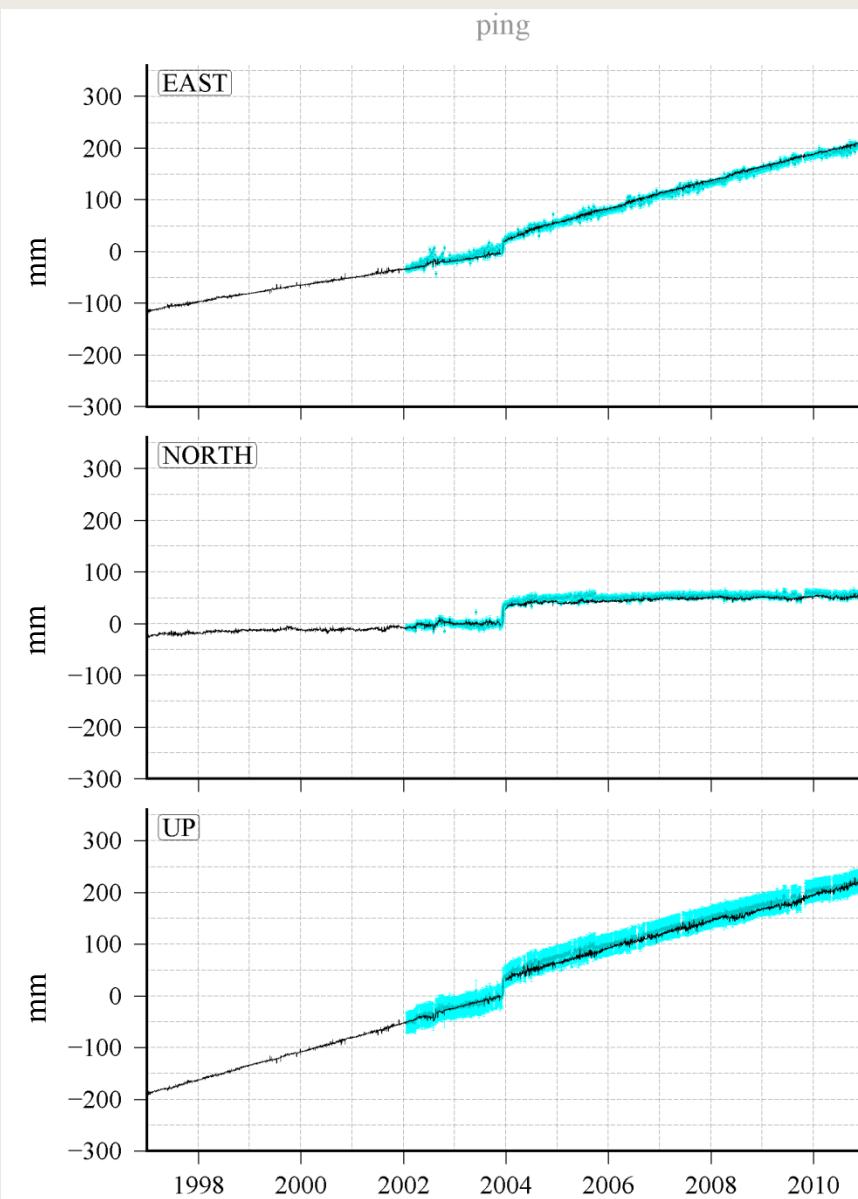
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

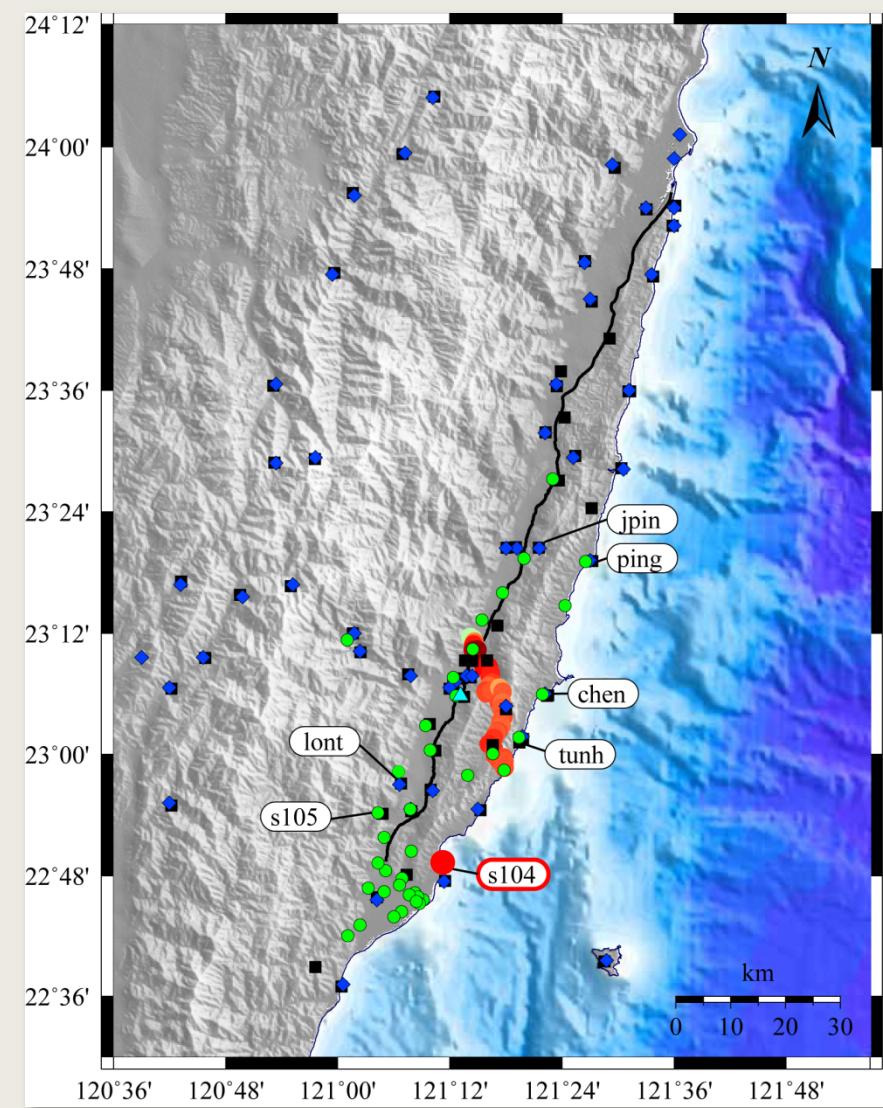
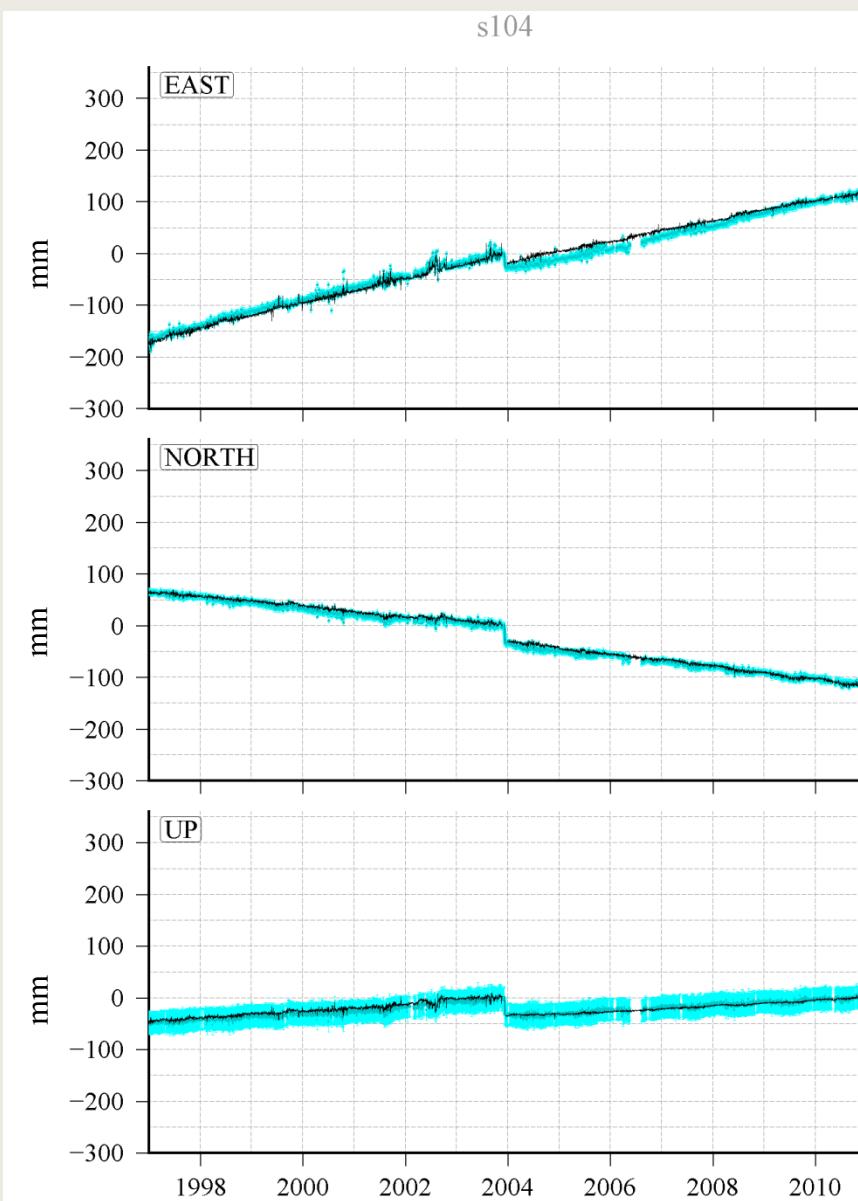
4. Deformation Mechanisms

5. Conclusion

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DATA FIT: GPS STATION “S104”



DATA FIT: GPS STATION “S105”

1. Introduction

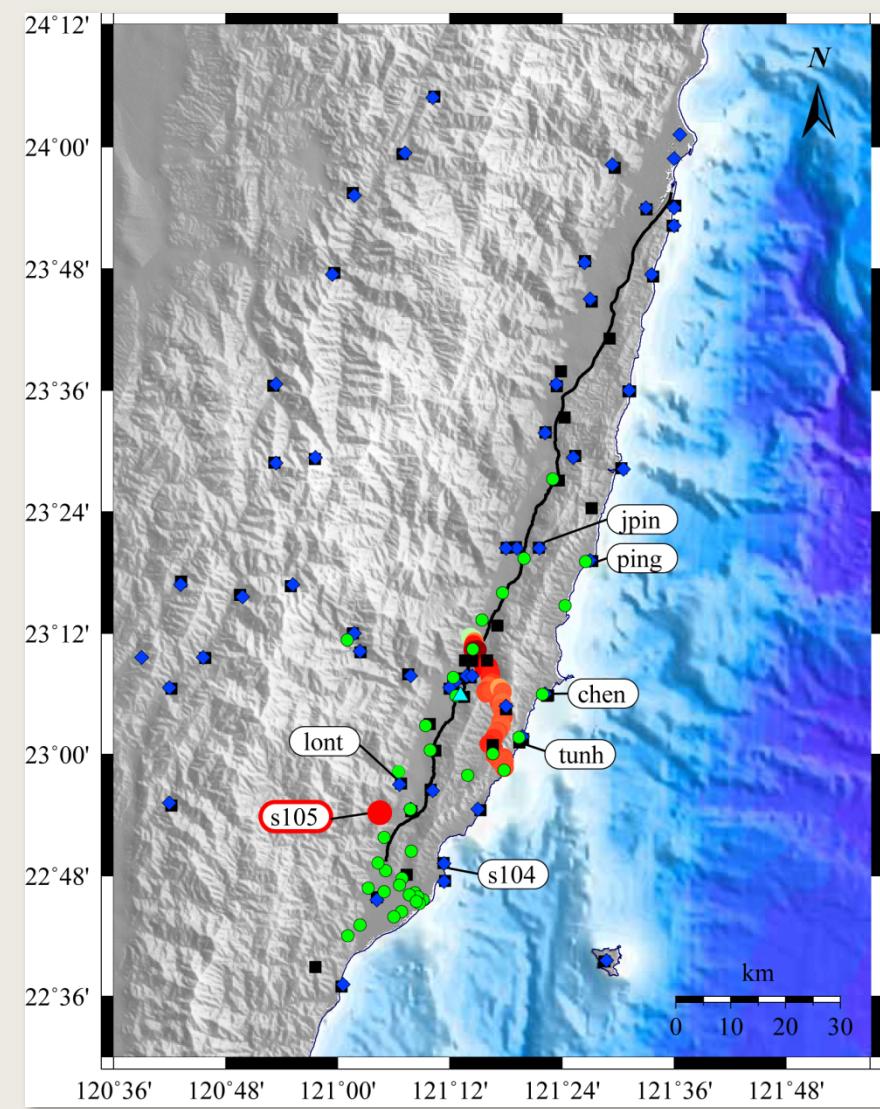
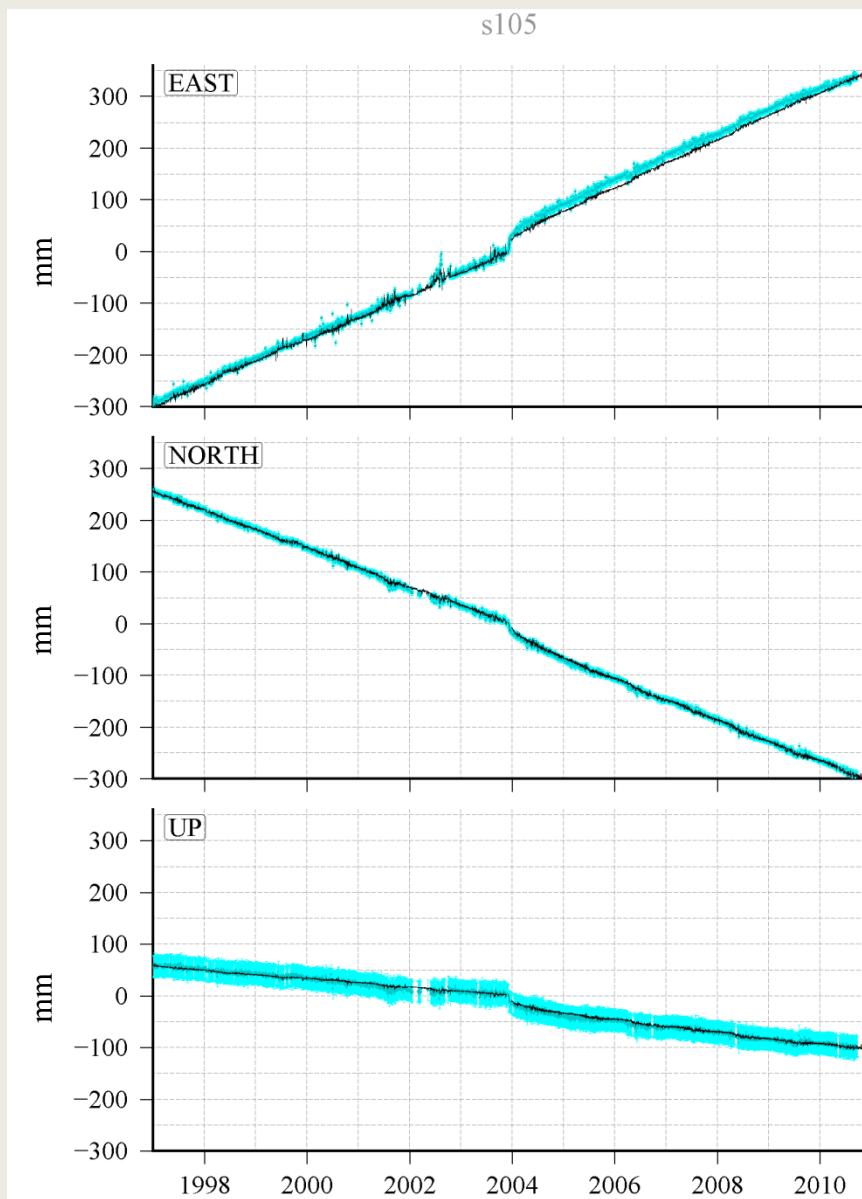
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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DATA FIT: GPS STATION “TUNH”

1. Introduction

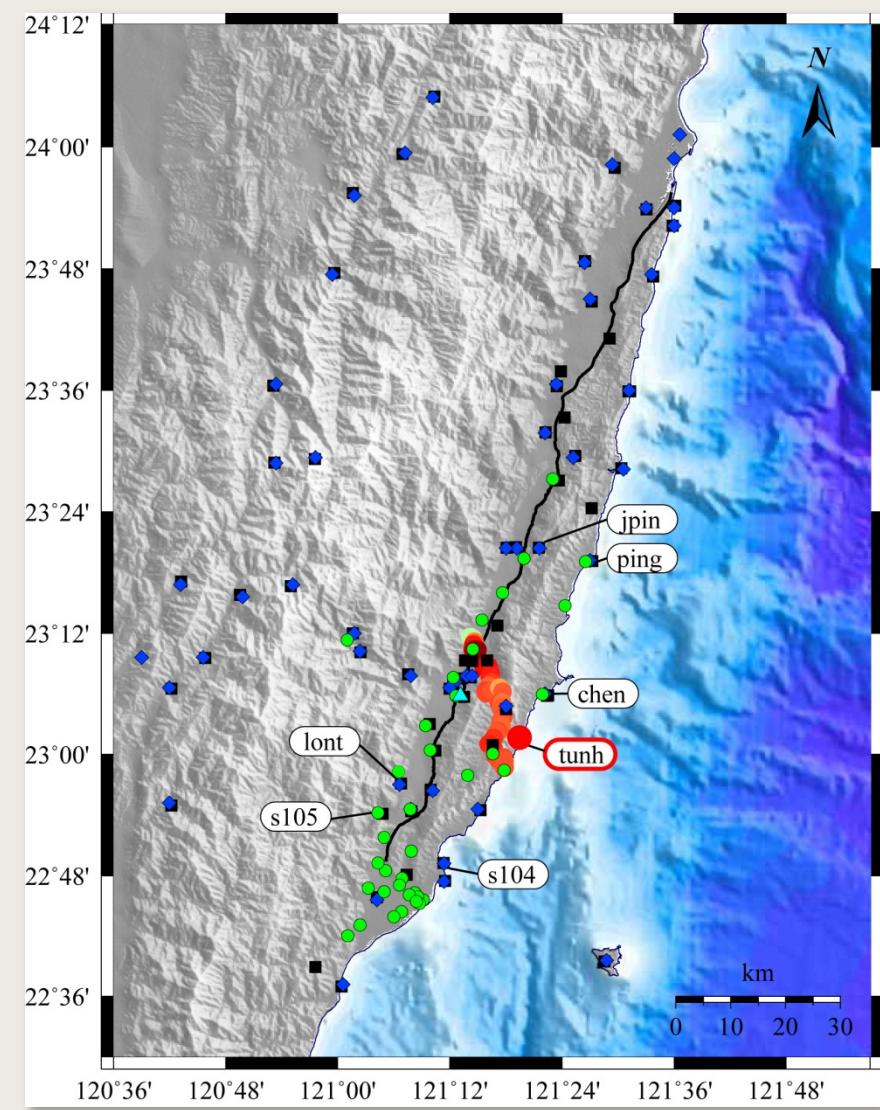
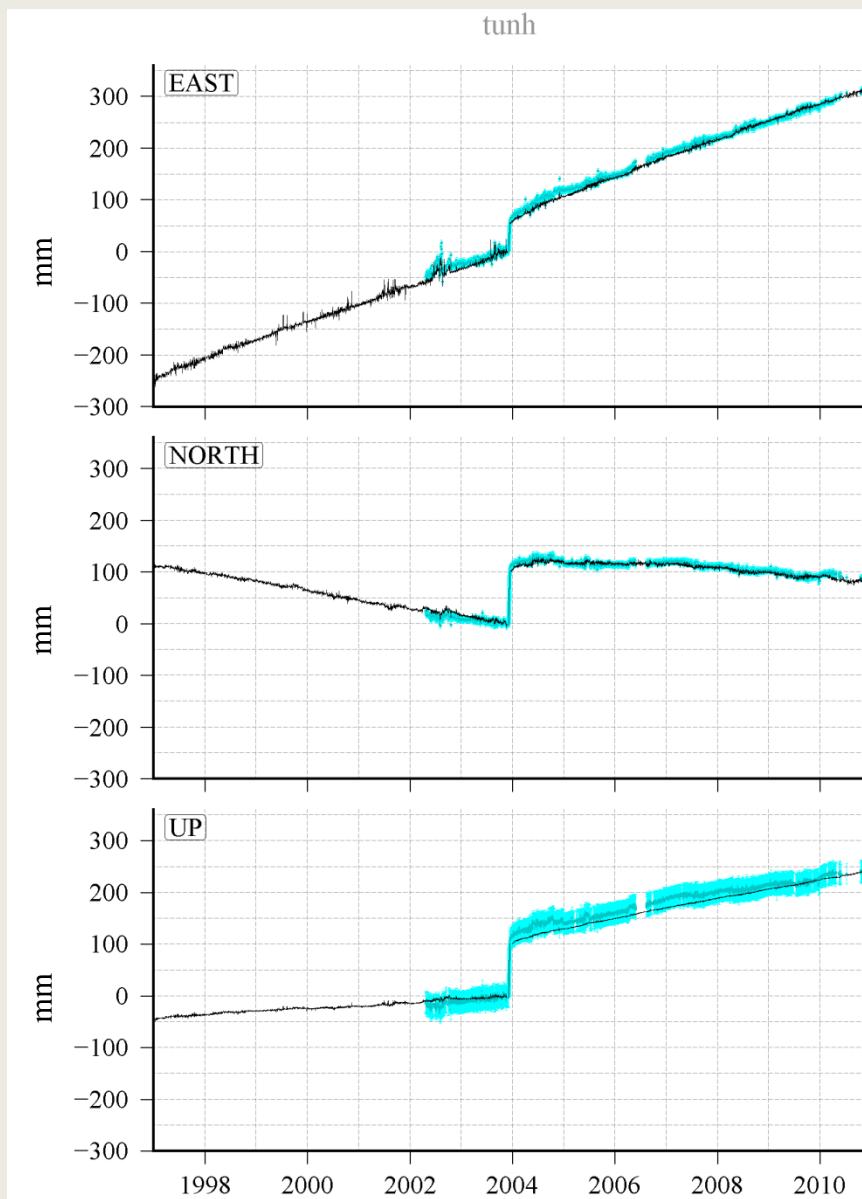
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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DATA FIT: CREEPMETER

1. Introduction

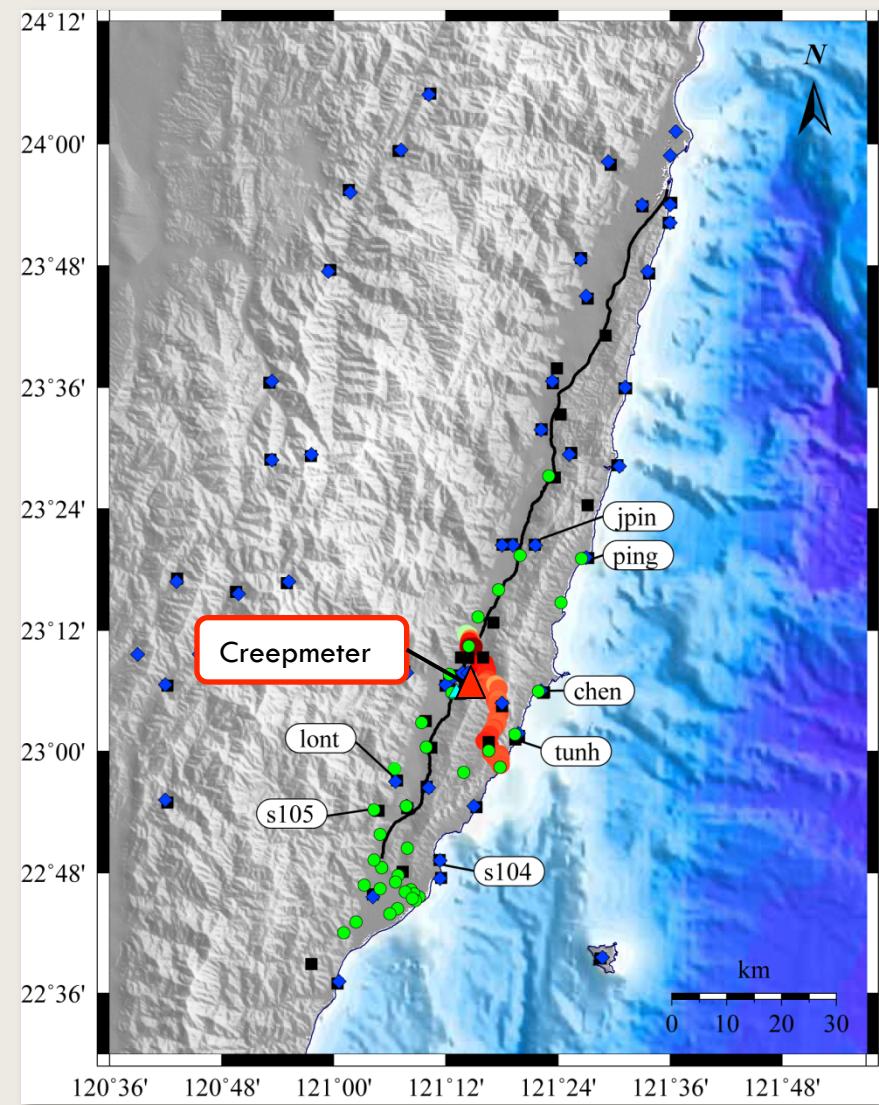
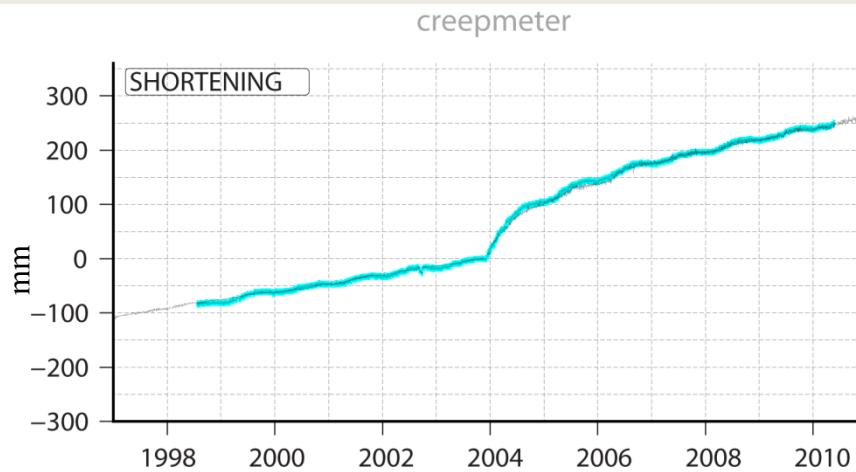
2. Aseismic vs seismic slip mapping

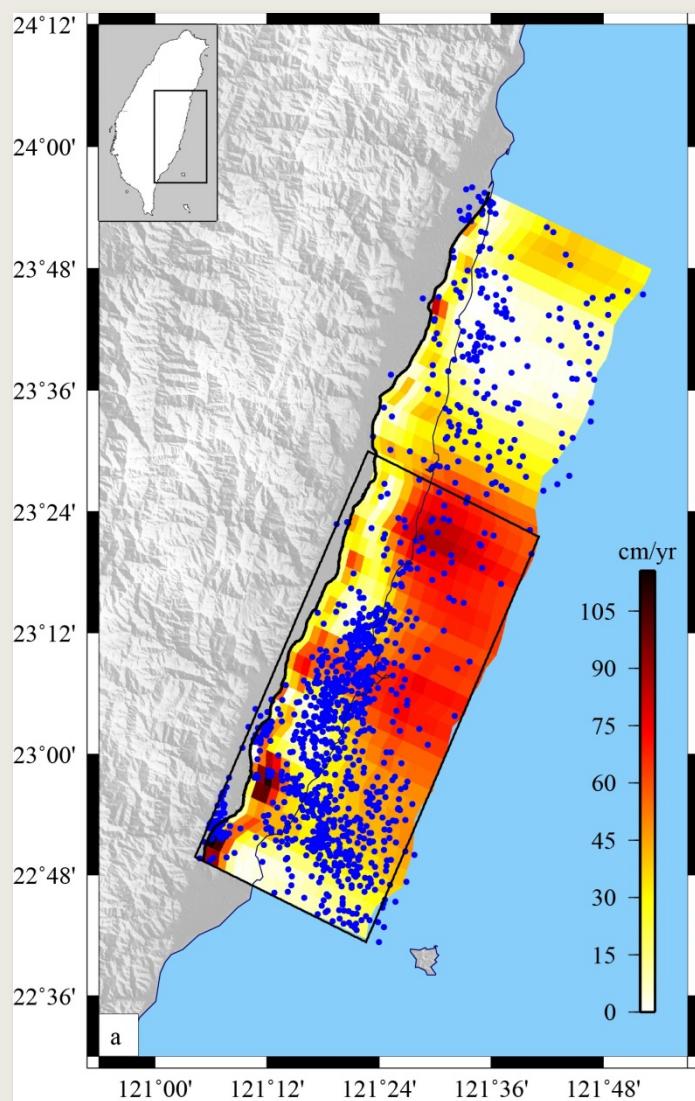
3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

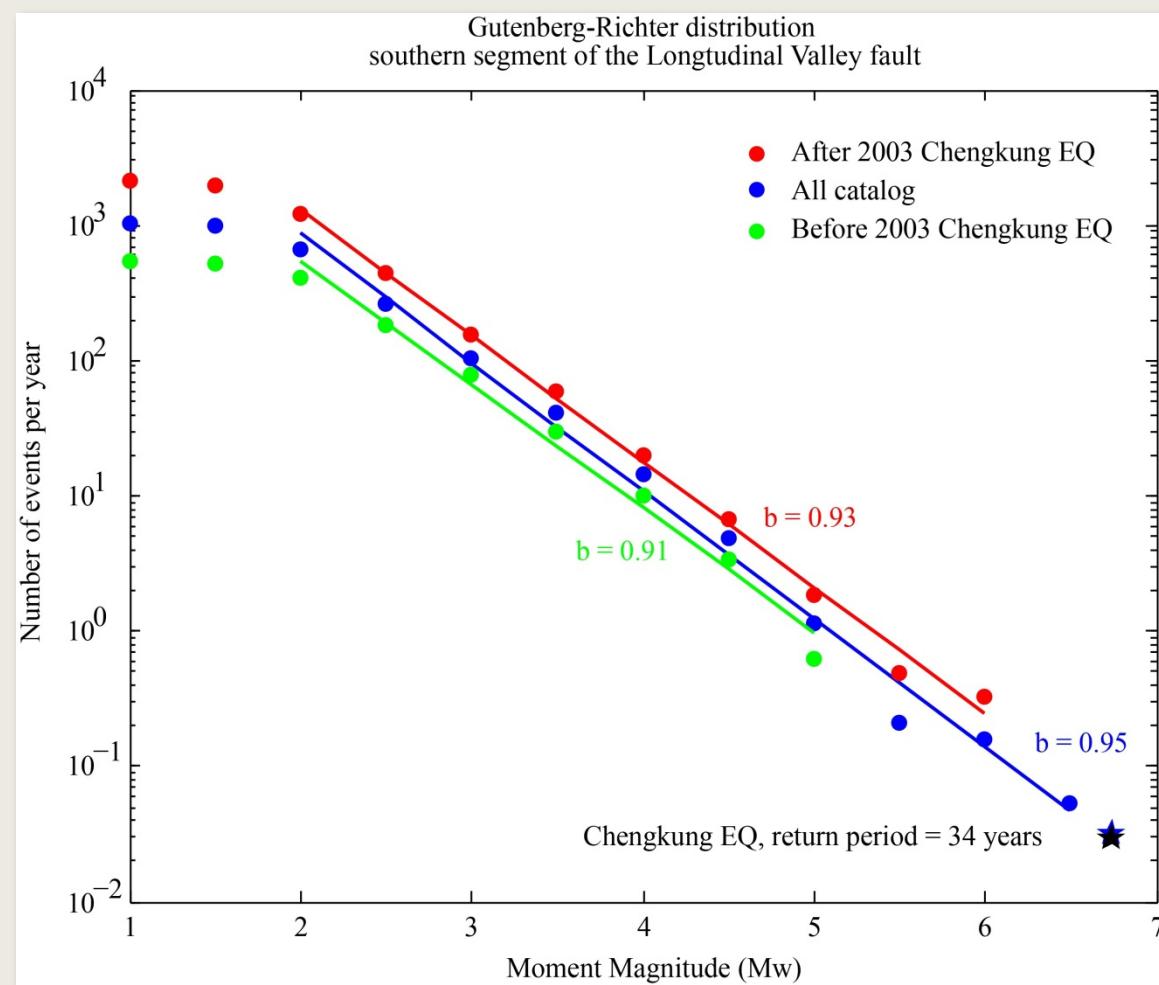
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Seismicity ($M_w > 3$) during 7 year after 2003 EQ

Return period:

$$T = \frac{M_{0_{coseismic}} + M_{0_{postseismic}}}{M_{0_{deficit}}}$$



Seismicity catalog from Wu et al., 2008

SLIP AT DEPTH, TEMPORAL HISTORY

1. Introduction

2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

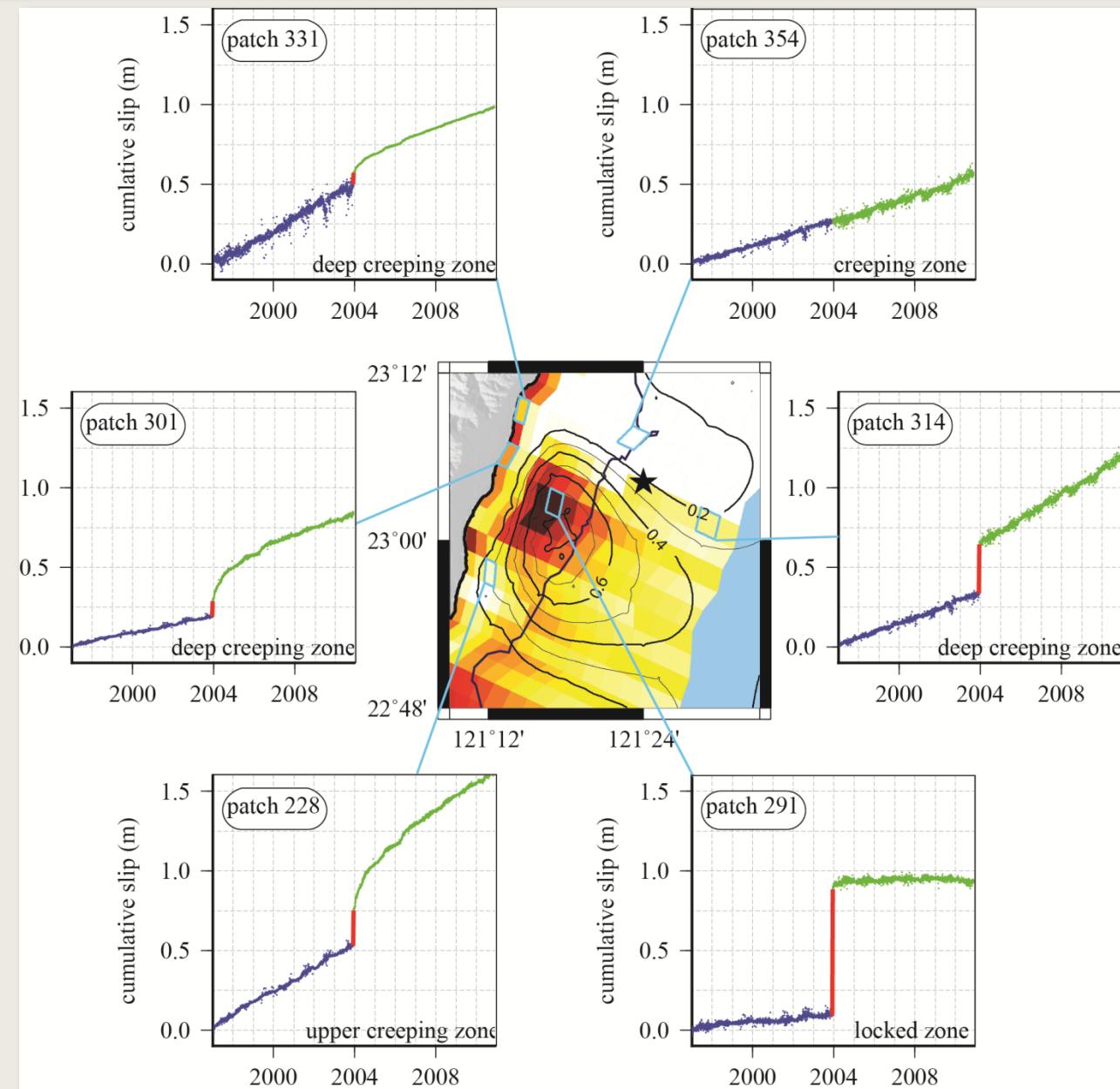
5. Conclusion

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PCAIM inversion
yields to a slip
history at depth.

Upper patches
creeps before and
after the Chengkung
events

Locked patch
at ~10 to 18 km
depth, that only
recorded seismic slip



SLIP AT DEPTH, TEMPORAL HISTORY

1. Introduction

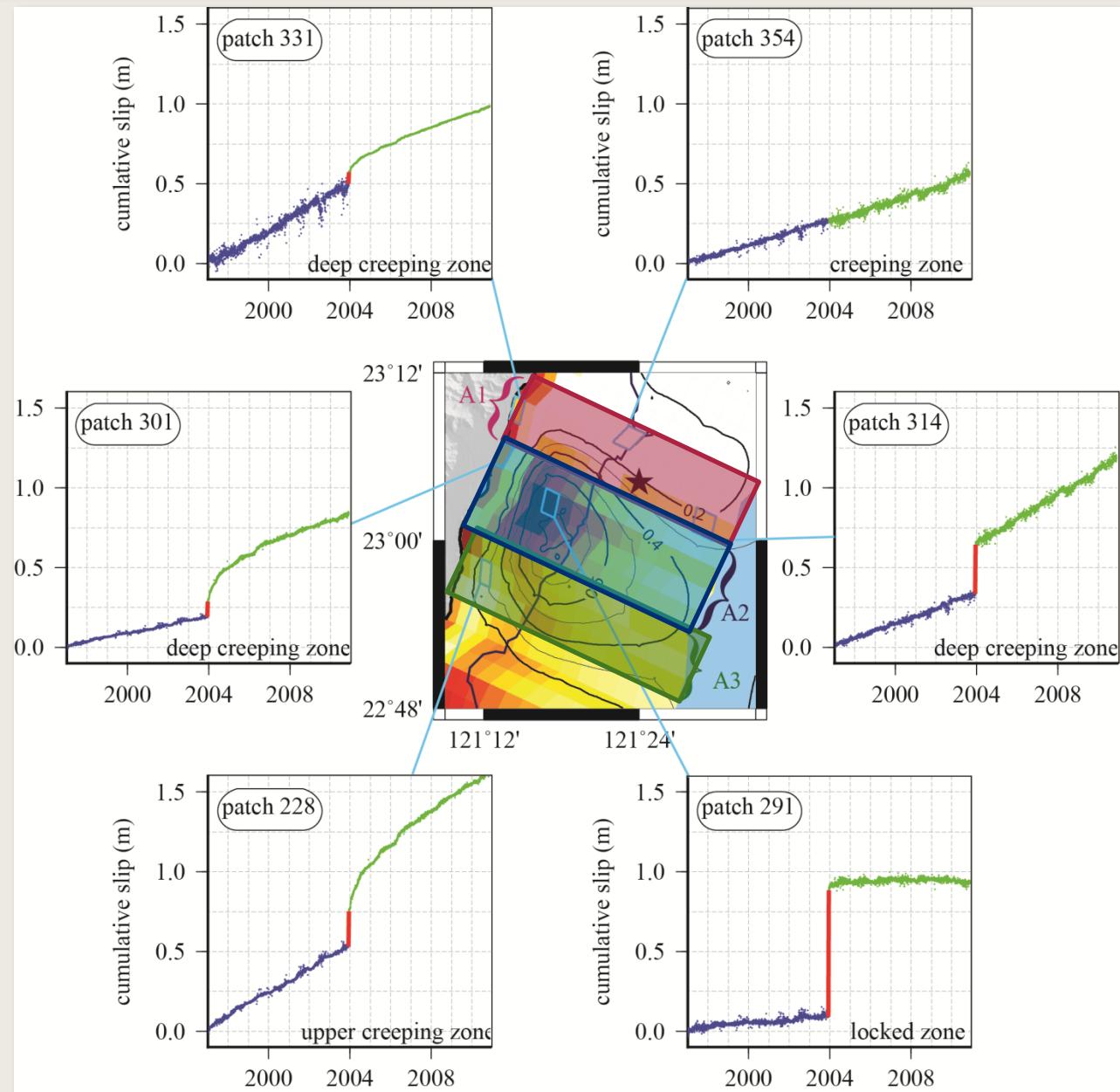
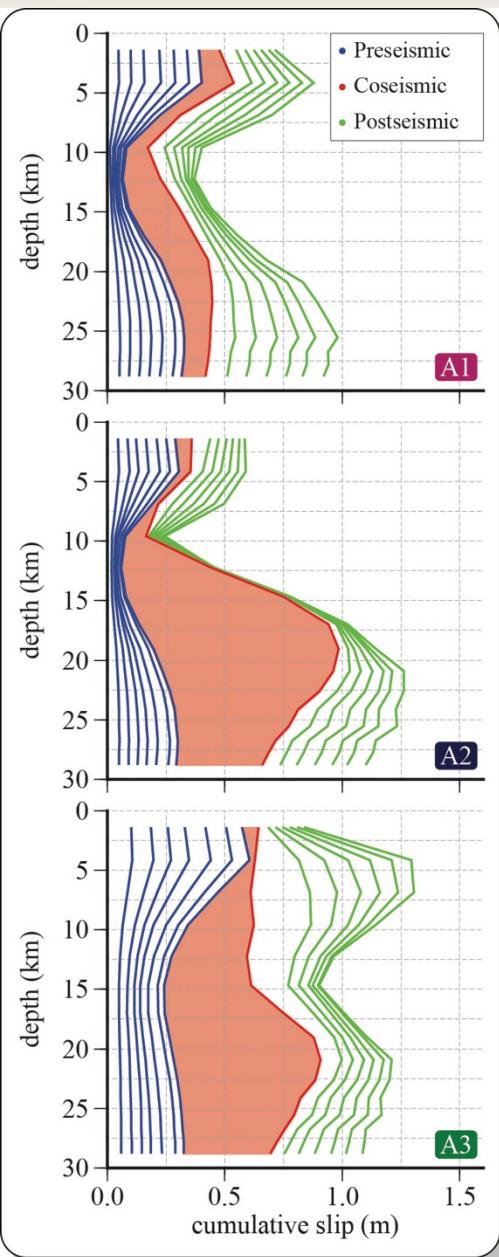
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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INSIGHTS ON FRICTIONAL PROPERTIES

1. Introduction

2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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Rate-and-state law

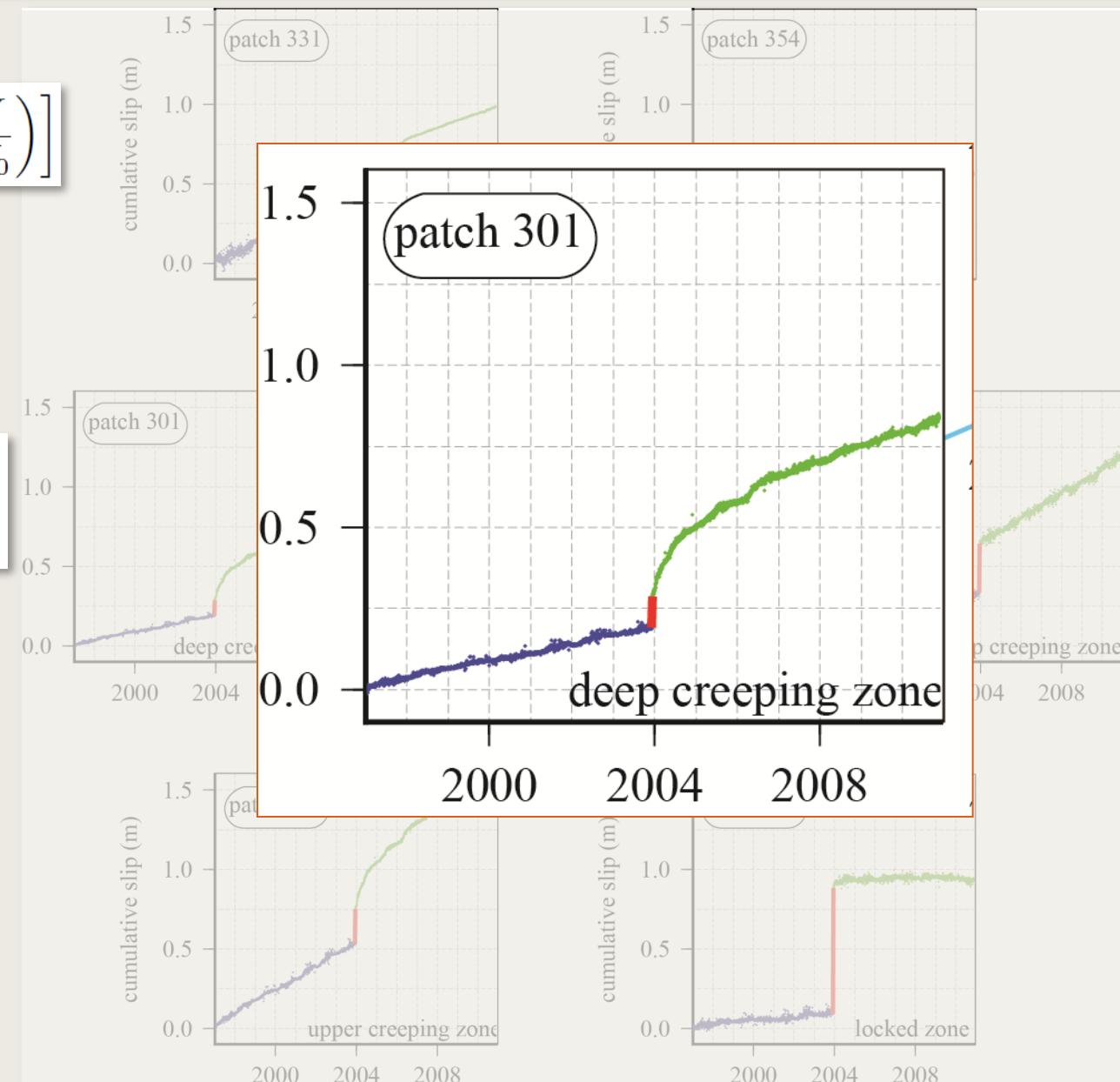
$$\tau_{ss} = (\sigma - p) \left[f_0 + (a - b) \ln \left(\frac{V}{V_0} \right) \right]$$

From Perfettini and Avouac., 2004

$$U(t) \approx V_{pl} t_r \log \left[1 + \frac{V^+}{V_{pl} t_r} t \right]$$

$$(a - b) = \frac{\Delta CFF}{\bar{\sigma} \log \left(\frac{V^+}{V_{pl}} \right)}$$

$$t_r = \frac{(a - b)\sigma}{\dot{\tau}}$$



INSIGHTS ON FRICTIONAL PROPERTIES

1. Introduction

2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

25/36

Rate-and-state law

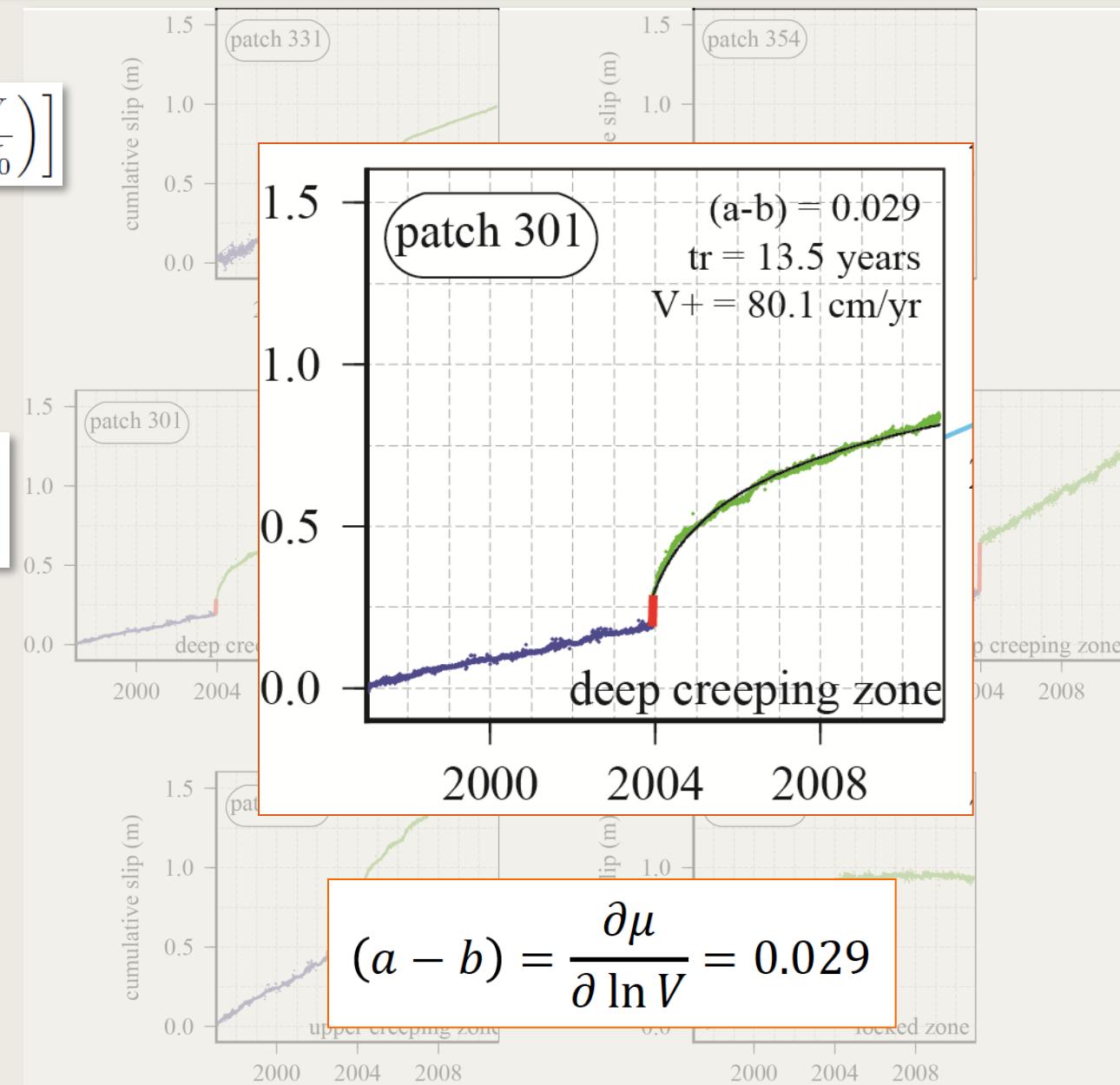
$$\tau_{ss} = (\sigma - p) \left[f_0 + (a - b) \ln \left(\frac{V}{V_0} \right) \right]$$

From Perfettini and Avouac., 2004

$$U(t) \approx V_{pl} t_r \log \left[1 + \frac{V^+}{V_{pl} t_r} t \right]$$

$$(a - b) = \frac{\Delta CFF}{\bar{\sigma} \log \left(\frac{V^+}{V_{pl}} \right)}$$

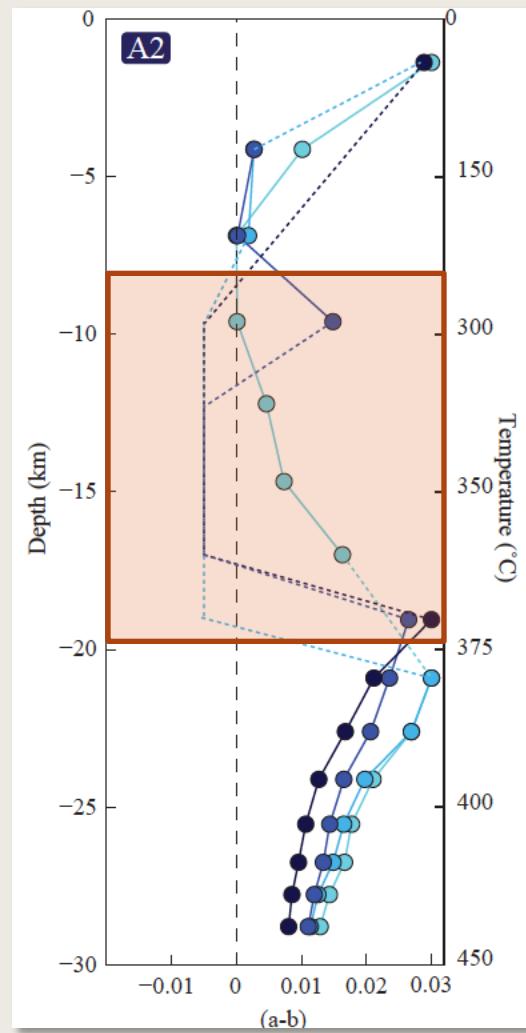
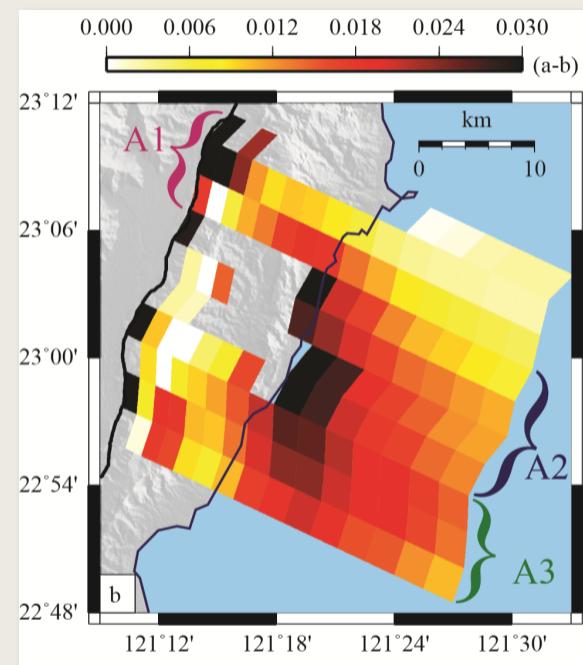
$$t_r = \frac{(a - b)\sigma}{\dot{\tau}}$$



INSIGHTS ON FRICTIONAL PROPERTIES

(a-b) derived from inversion models, in function of depth

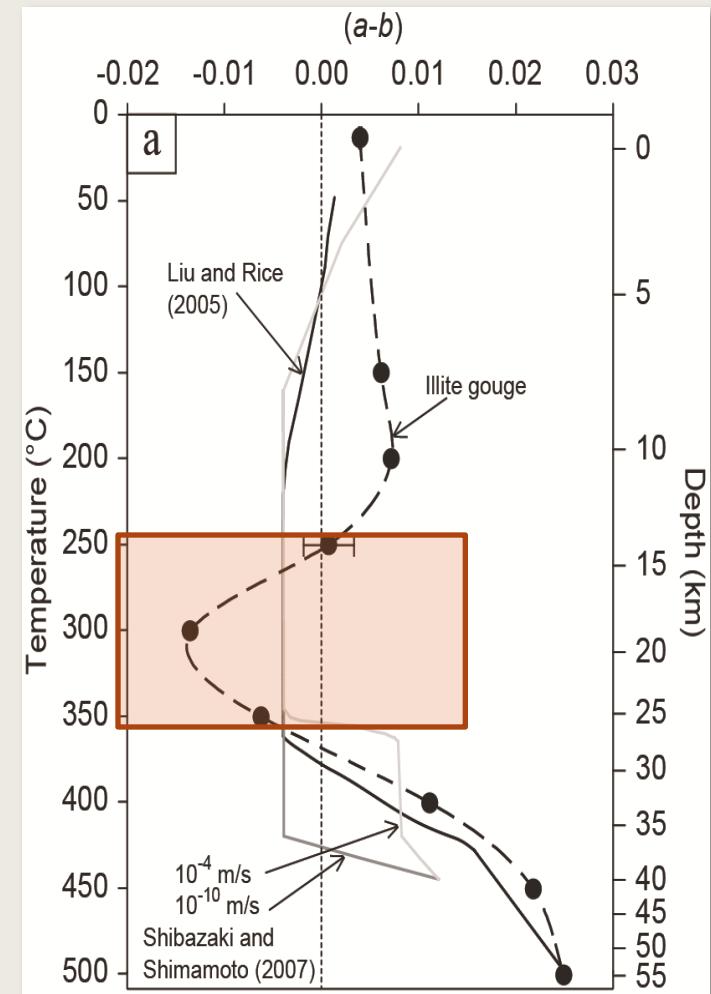
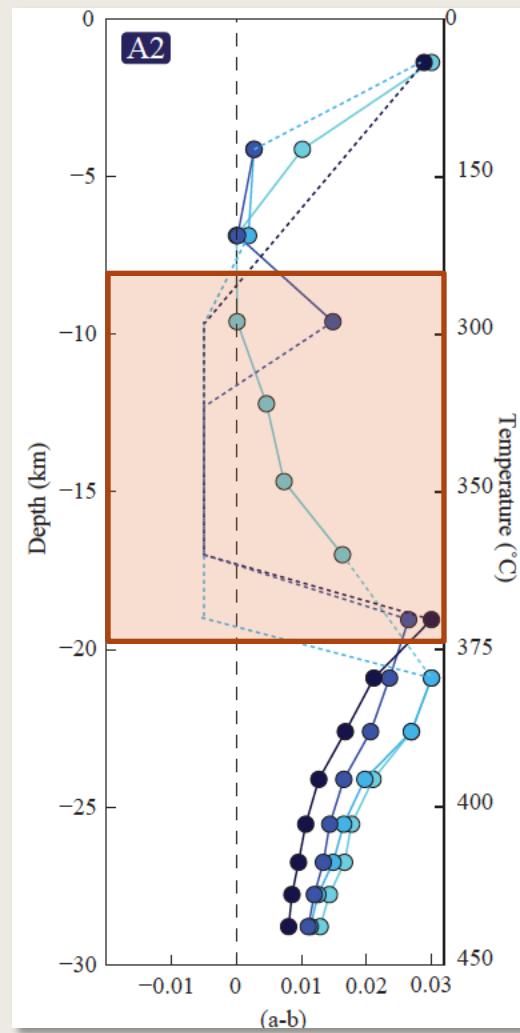
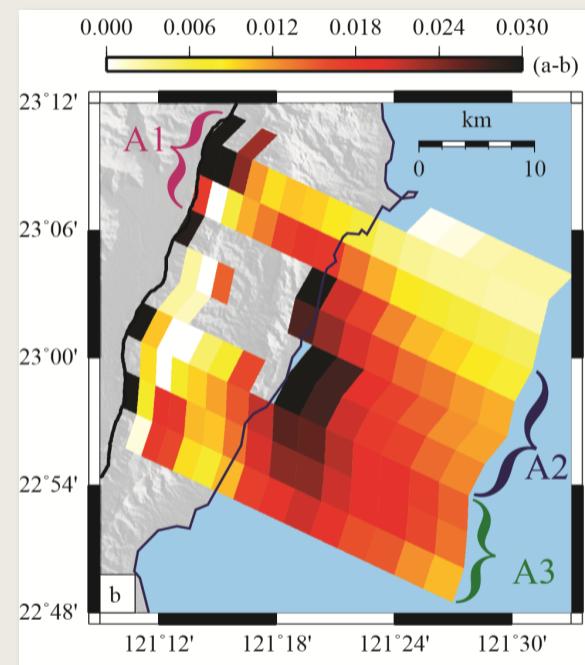
(a-b) derived from inversion models



INSIGHTS ON FRICTIONAL PROPERTIES

(a-b) derived from inversion models, in function of depth

(a-b) derived from inversion models



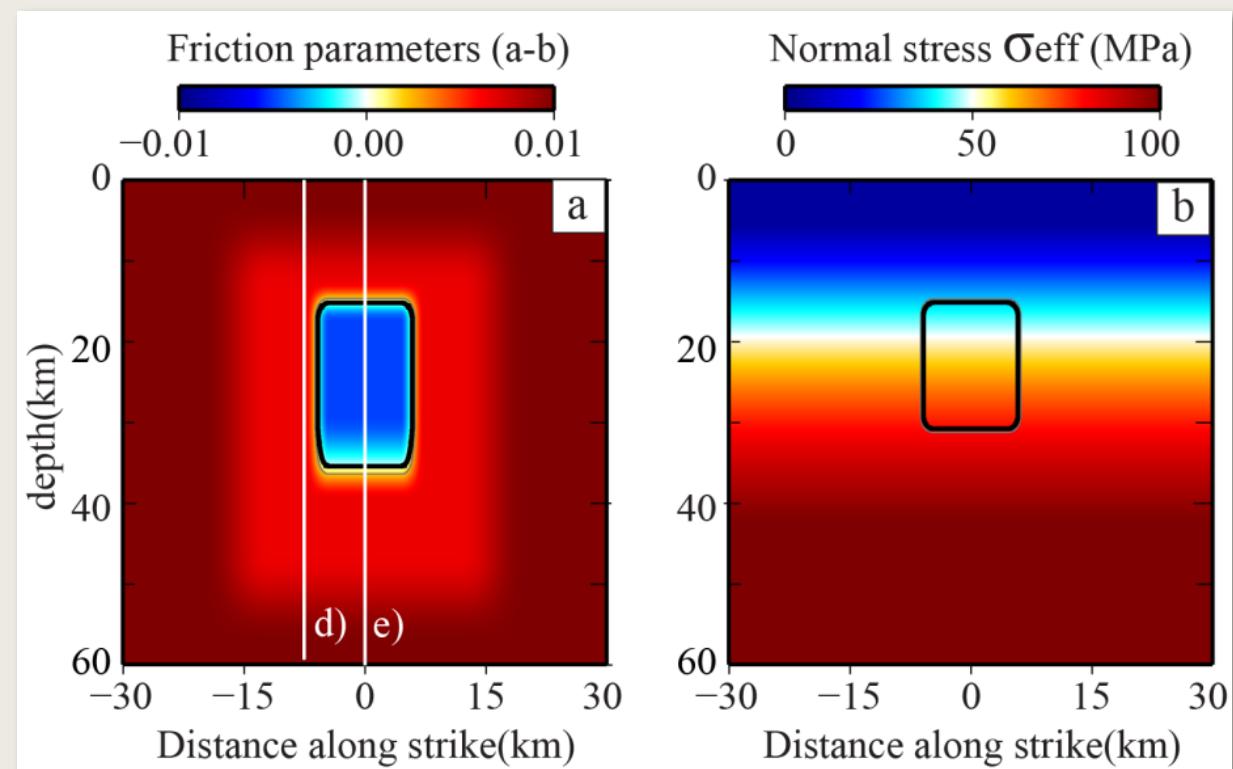
"BICycle" : Boundary Integration Cycle of Earthquakes

Allows simulating earthquake cycles in their entirety,
 from accelerating slip in slowly expanding nucleation zones
 to dynamic rupture propagation
 to post-seismic slip and interseismic creep
 to fault re-strengthening between seismic events.

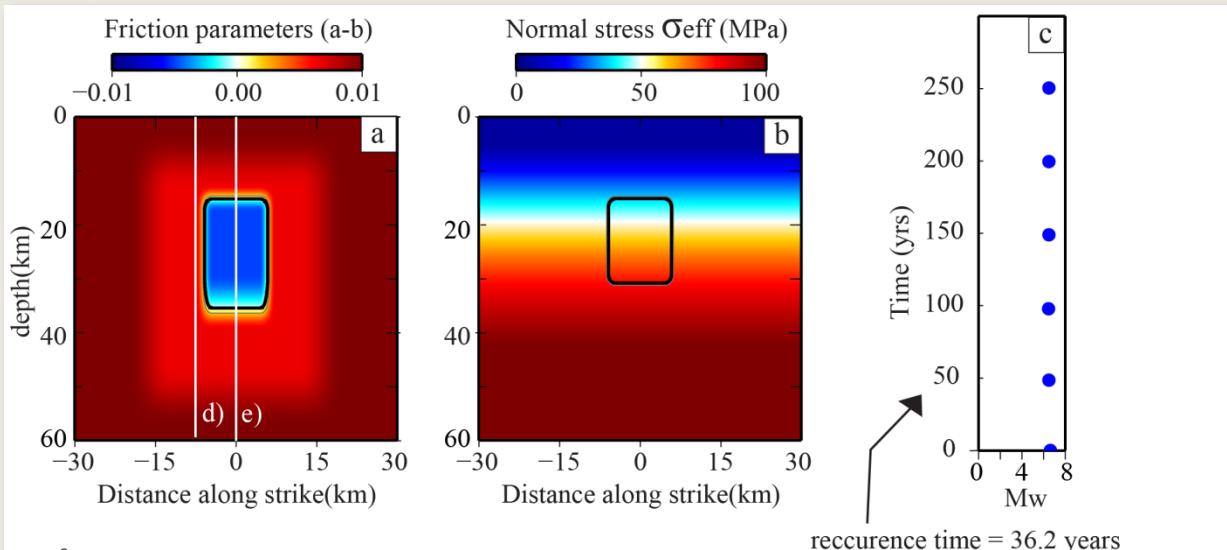
Rate and state law
 (Dieterich 1981, Ruina 1983) :

$$\tau = \bar{\sigma} \left(f_0 + a \ln \frac{V}{V_0} + b \ln \frac{V_0 \theta}{L} \right)$$

with $\dot{\theta} = 1 - \frac{V\theta}{L}$

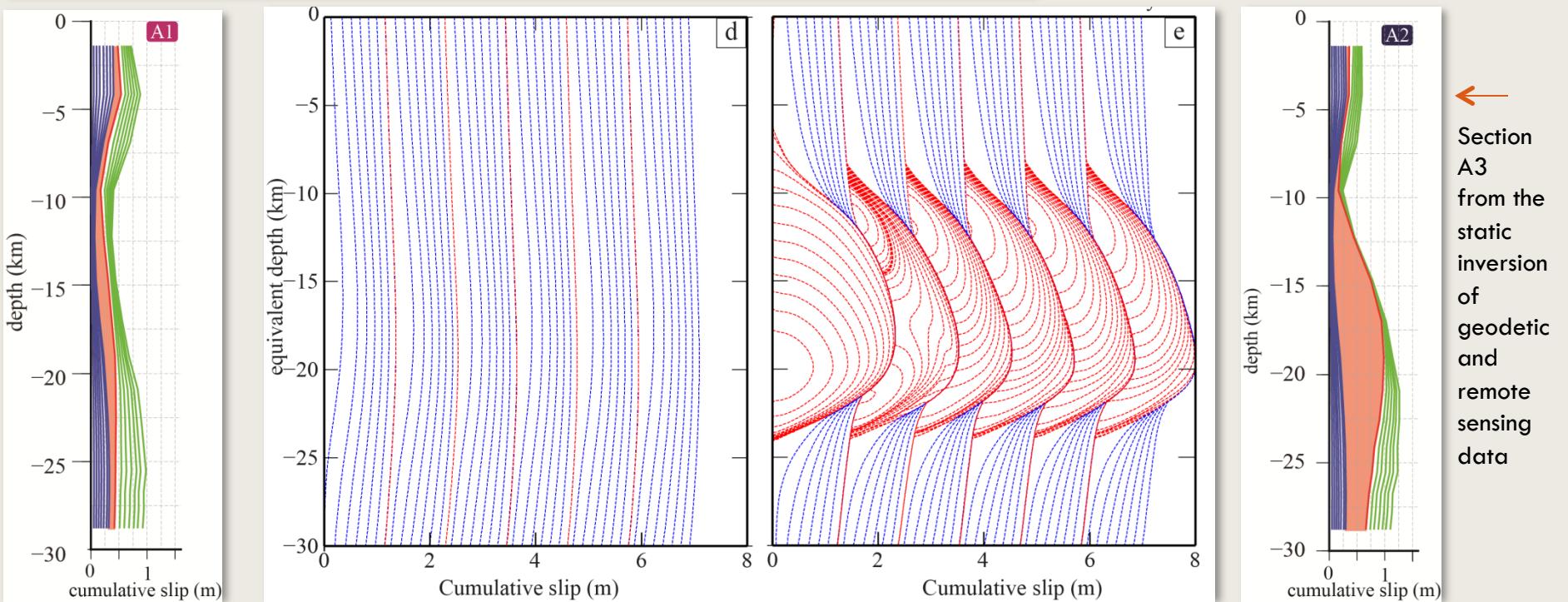


DYNAMIC MODELING ON THE LVF



Output features :

- quasi periodic return of similar earthquakes rupturing the whole VW patch
- Mw 6.5 earthquakes
- Recurrence time = 36.2 years
- seismic ruptures do not reach the surface



SPATIAL CORRELATION OF ASEISMIC SLIP WITH THE LICI MELANGE

1. Introduction

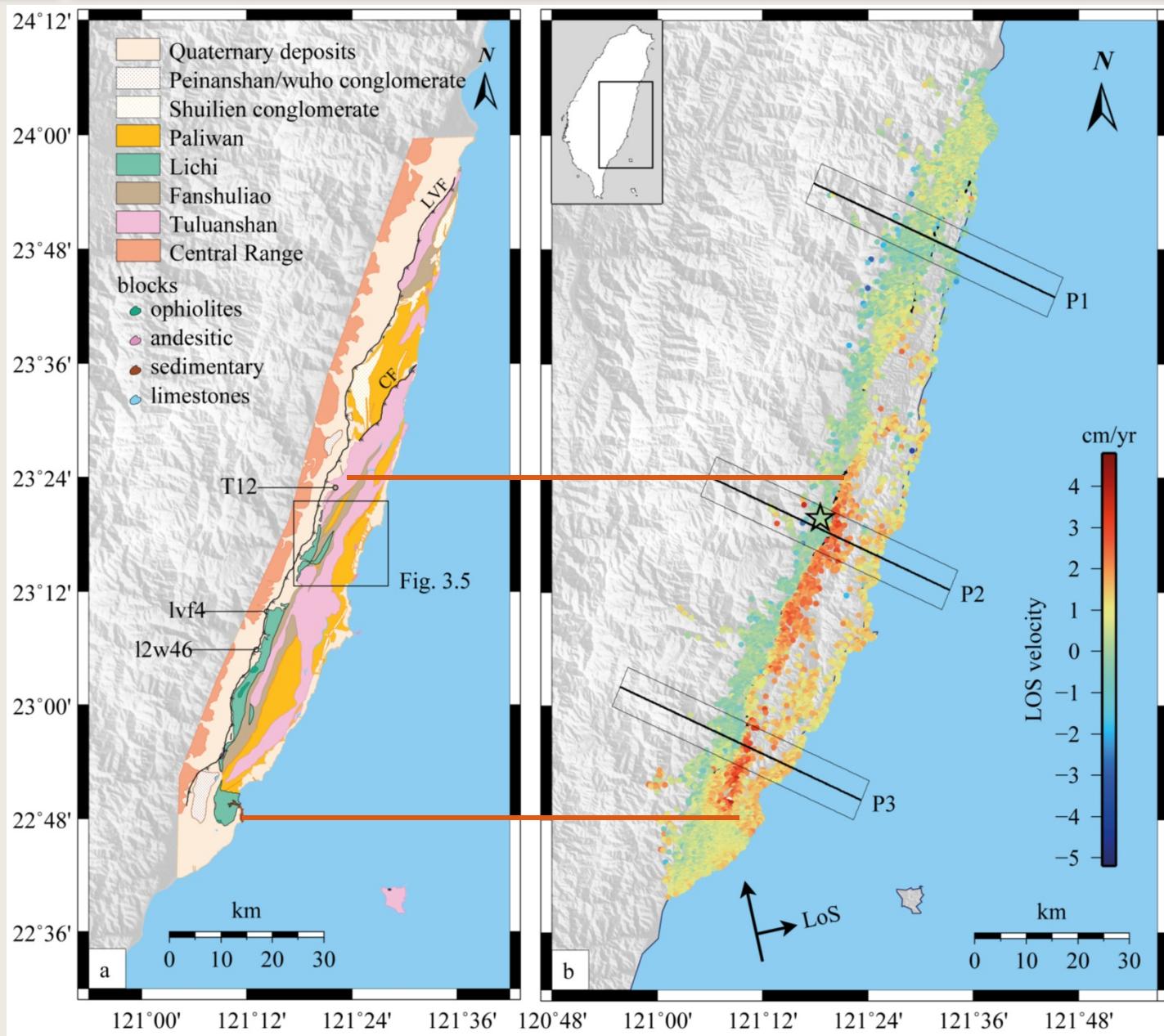
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

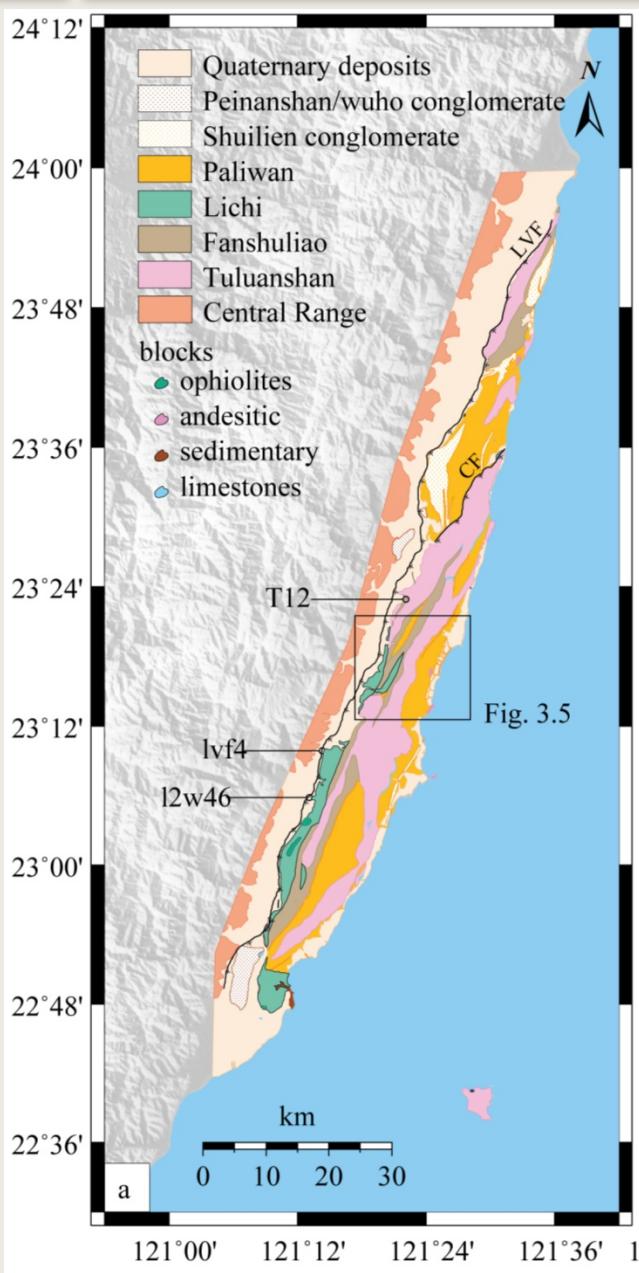
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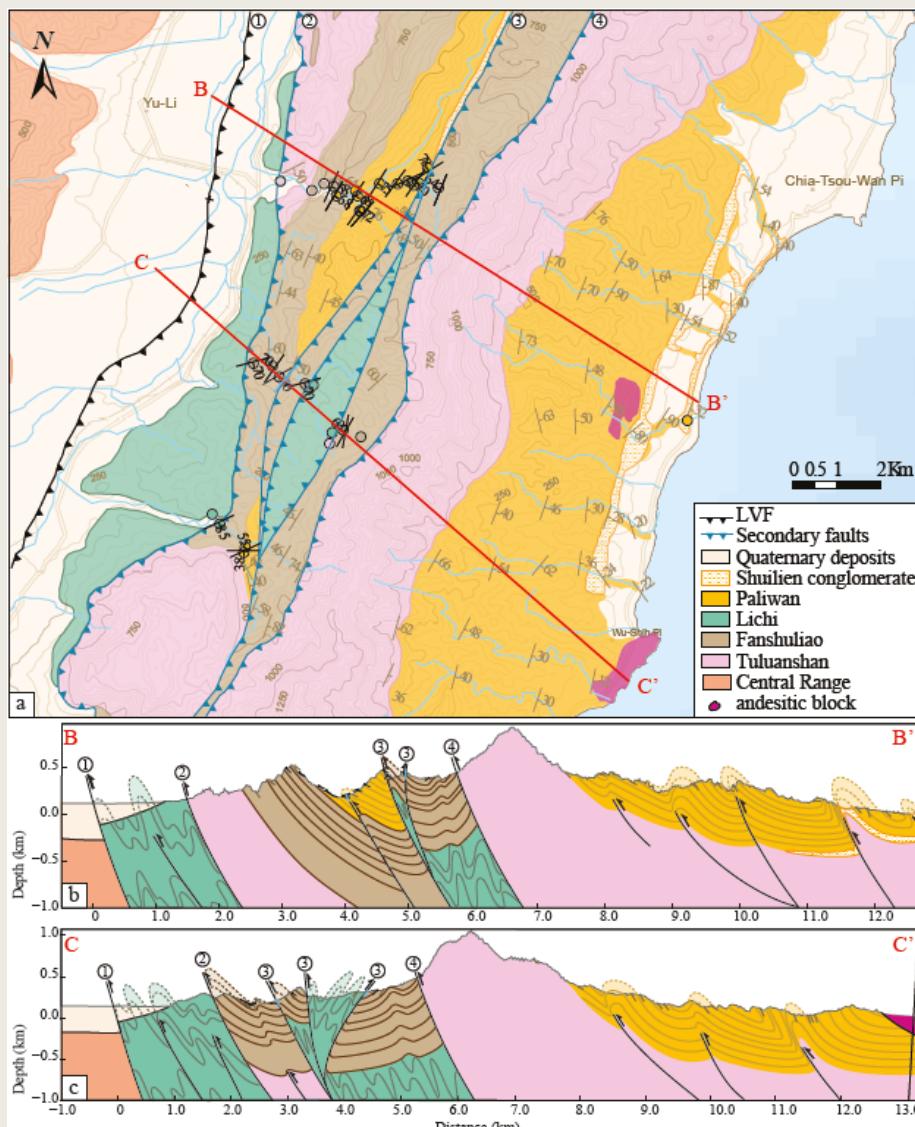
FIELD WORK: STRATIGRAPHIC RELATIONS

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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The Fanshuliao forearc deposits formation is the protolith of the Lichi Melange



LICHI MELANGE VS FANSHULIAO

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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Lichi melange, a collision melange



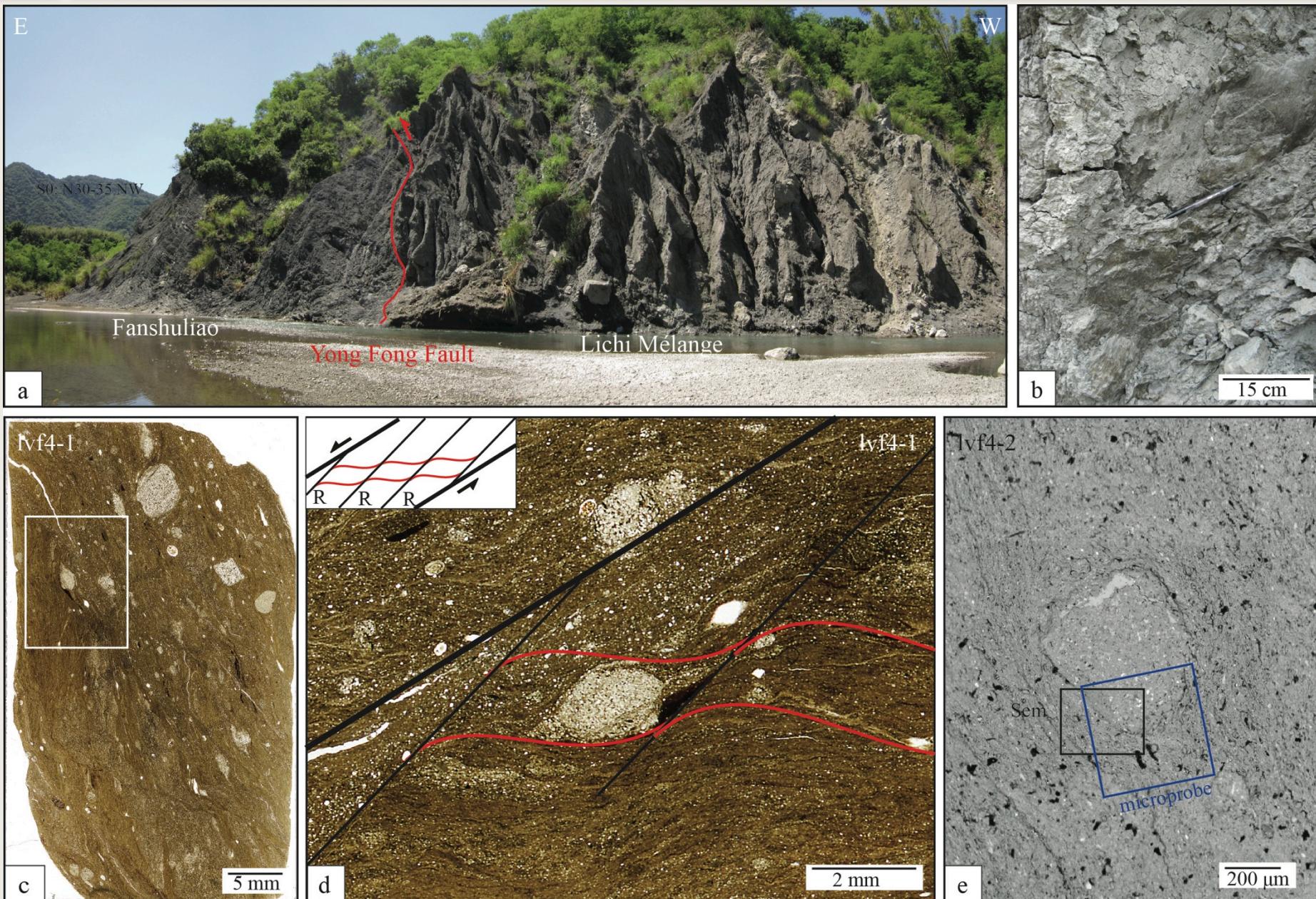
Fanshuliao, forearc deposits



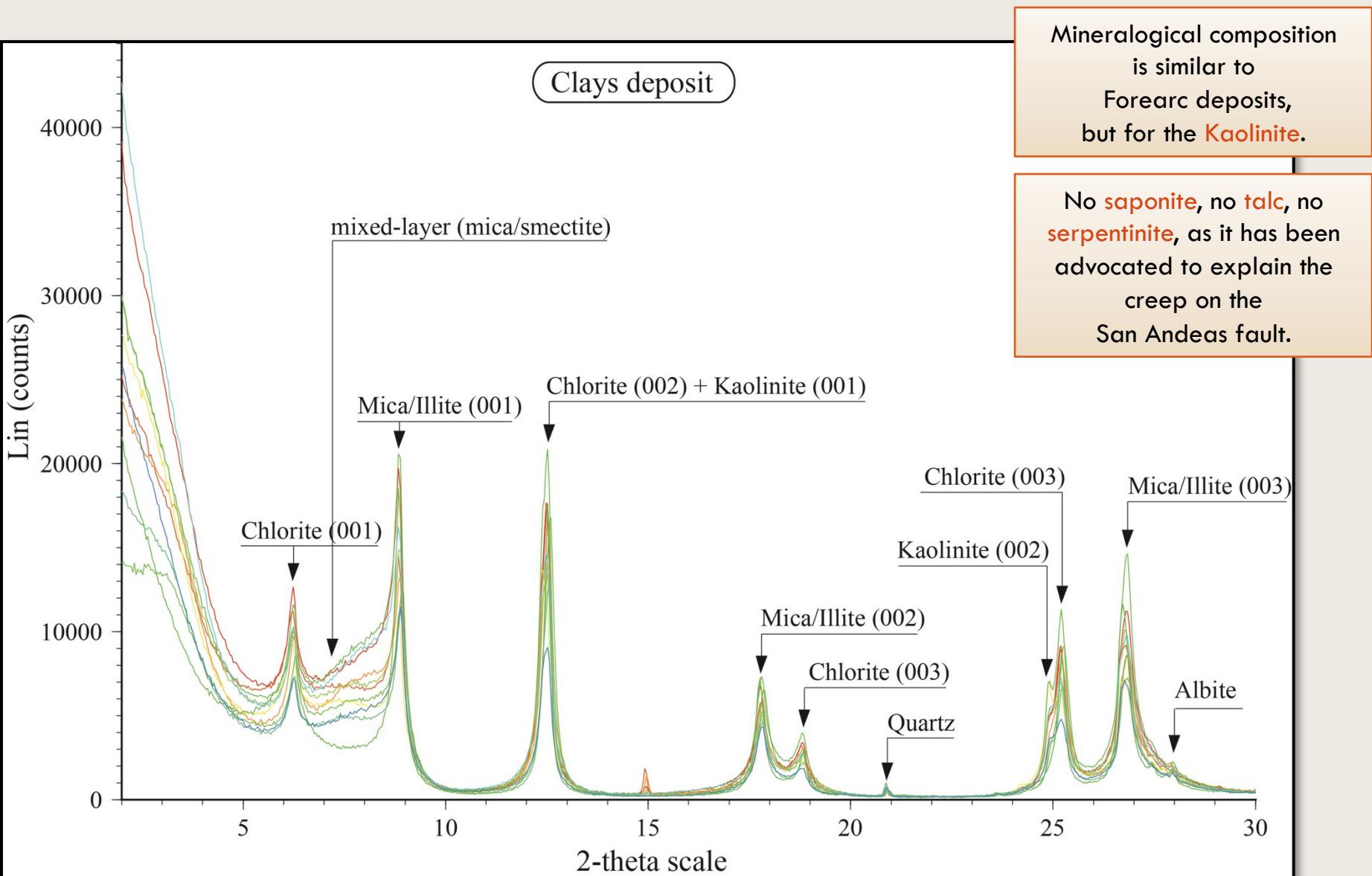
LICHI MELANGE: MICROSTRUCTURAL AND ANALYTICAL OBSERVATIONS

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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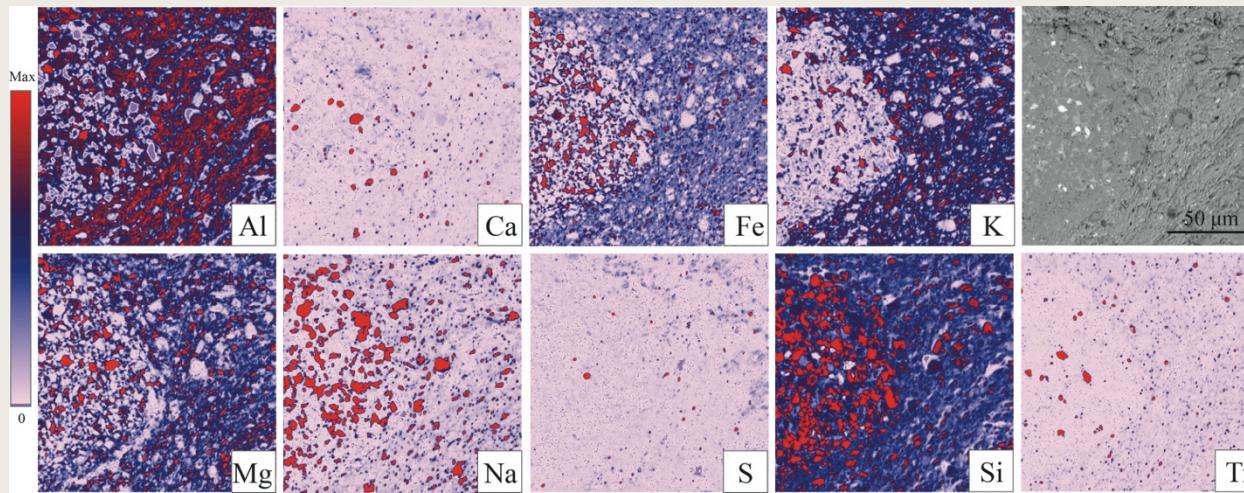


LICHI MELANGE: MINERALOGICAL COMPOSITION

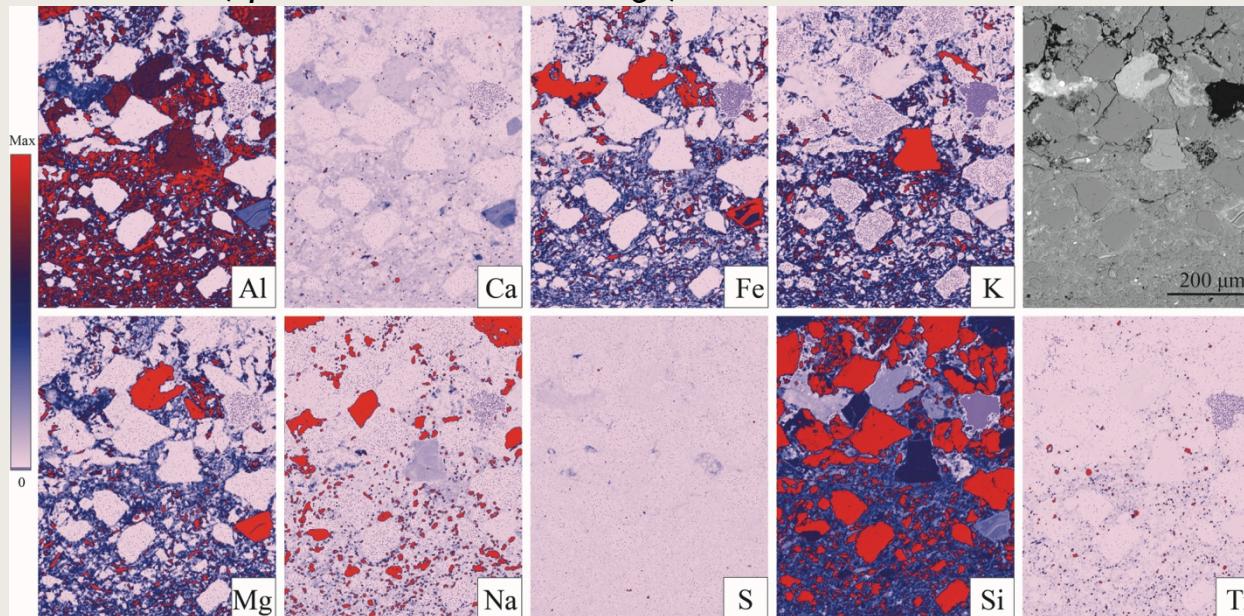


MICRO-ANALYZER COMPOSITIONAL MAP

Lichi melange, inside the LVF fault gouge



Fanshuliao, protolith of Lichi melange, near the fault zone



In the matrix, in comparison to the microlithons (initial state) or the protolith:

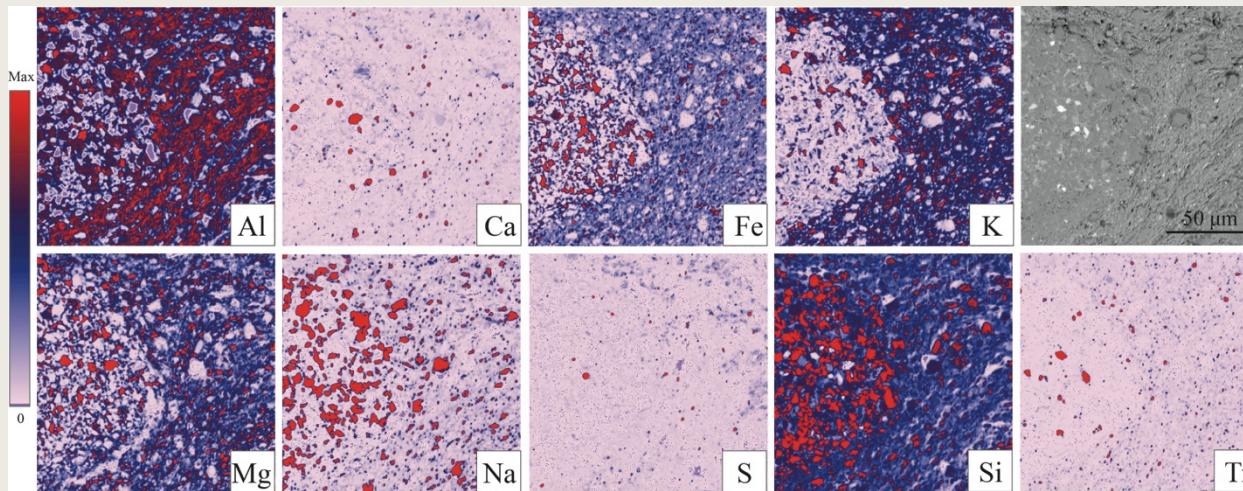
■ **Depletion:**

- Si
- Na
- Ca

■ **Passive concentration:**

- Al
- K
- Ti
- S

Lichi melange, inside the LVF fault gouge



For pressure-solution creep to develop, it requires:

- Soluble minerals
- Fluid phase

To accommodate large creep rate:

- Small grain size
- phyllosilicates

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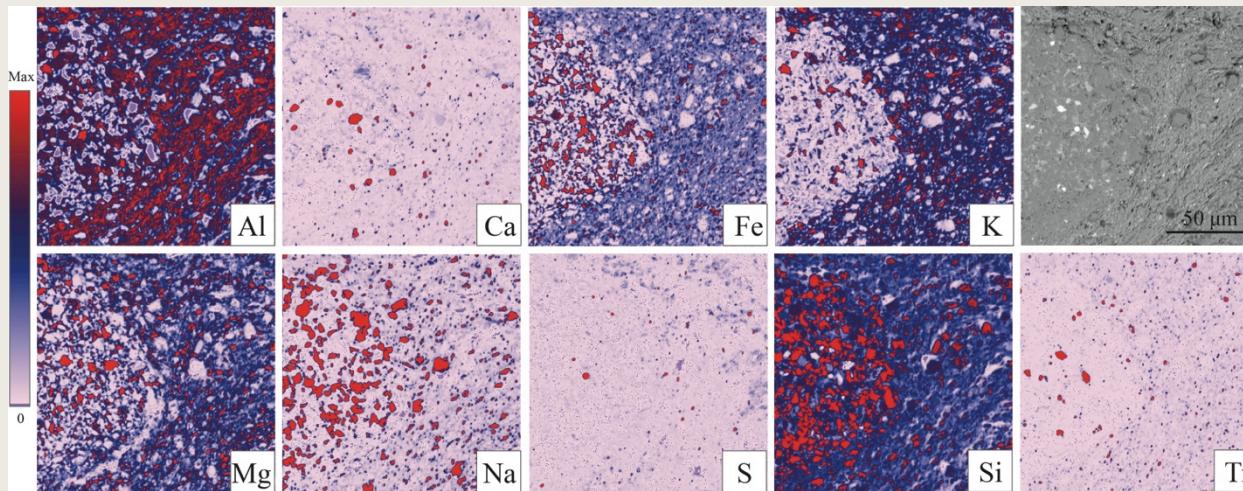
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- S

Deficit in soluble minerals
=

Pressure solution creep

Lichi melange, inside the LVF fault gouge



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Lichi Melange gathers the specific conditions

Deficit in soluble minerals
=
Pressure solution creep

LICHI MELANGE: MICROSTRUCTURAL AND ANALYTICAL OBSERVATIONS

1. Introduction 2. Aseismic vs seismic slip mapping 3. Dynamic Modeling 4. Deformation Mechanisms 5. Conclusion

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E

W

R-type Ridel slip surfaces + evidences for cataclasis



Granular flow mechanism involving frictional sliding
are likely too.

S0-N30-35 NW

Fanshuliao

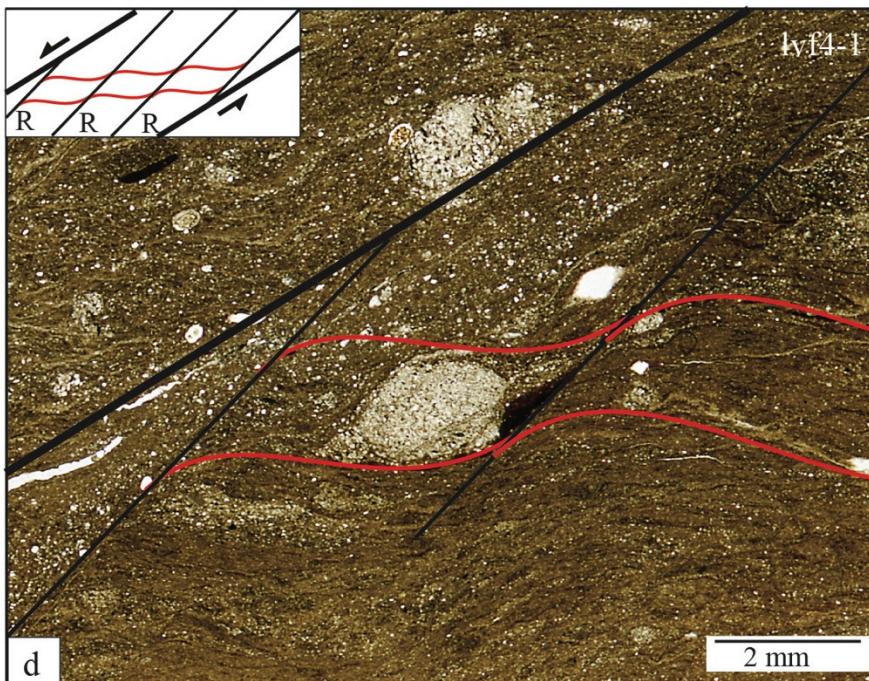
Yong Fong Fault

Lichi Mélange

a

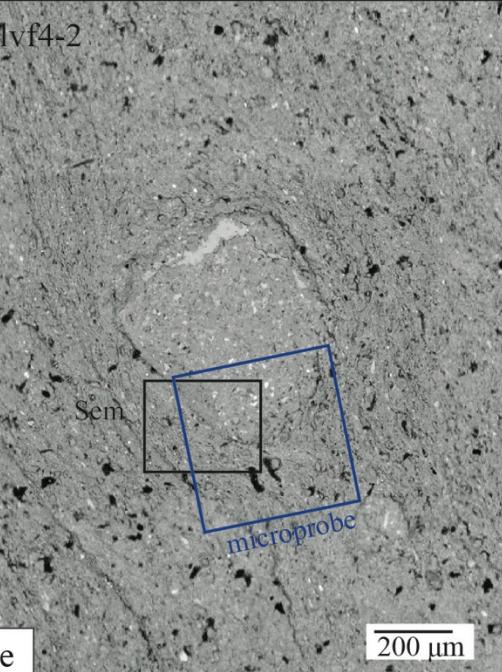
b

15 cm



c

d



e

Conclusion

- Map of seismic and aseismic segments on the LVF.
- Joint inversion of various dataset.
- Frictional properties of the fault retrieved from kinematic inversion.
- Cumulative slip history on the LVF is consistent with a simple model of a VW patch embedded in a VS area.
- Pressure-solution creep and Frictional sliding accommodate surface creep on the LVF.
- Tectonic fabric at the micro-scale is a key factors to control slip mode.

Conclusion

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On-going work

- Dynamic modeling of earthquakes sequences on the LVF; implications for frictional properties.
- Effect of Damage on Earthquake rupture dynamic

SLIP AT DEPTH, TEMPORAL HISTORY

1. Introduction

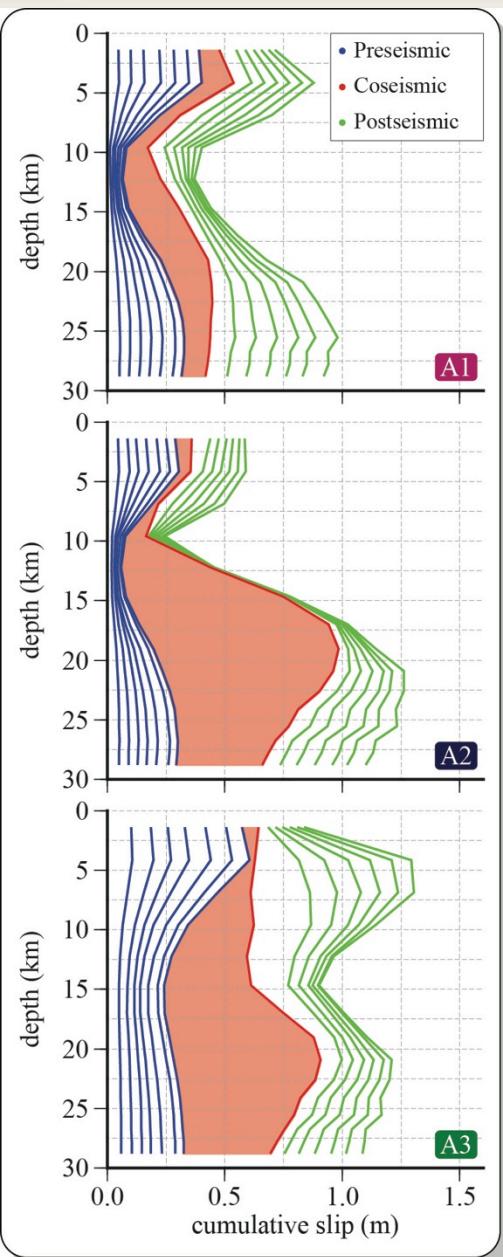
2. Aseismic vs seismic slip mapping

3. Dynamic Modeling

4. Deformation Mechanisms

5. Conclusion

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The decrease of resolution could not explain itself the overlap between seismic and aseismic slip at higher depth

